

NASA CONTRACTOR REPORT



NASA CR-2559 VOL. II



NUMERICAL NONLINEAR INFLASTIC ANALYSIS OF STIFFENED SHELLS OF REVOLUTION

Volume II - User's Manual for STARS-2P Digital Computer Program

V. Svalbonas and H. Levine

Prepared by GRUNMAN AEROSPACE CORPORATION Bethpage, N.Y. 11714 for George C. Marshall Space Flight Center 11 SEP 1975

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NATIONAL AFRONAUTICS AND SPACE ADMINISTRATION - WASHINGTON, D. C. - JULY 1975

1. REPORT NO.	TECHNICA 2. GOVERNMENT ACCESSION NO.	L REPORT STAND	
	2. GOVERNMENT ACCESSION NO.	J. RECIPIENT'S CA	ALGO NO.
NASA CR-2559		5. REPORT DATE	
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Numerical Nonlinear Inelastic A	-	6. PERFORMING ORG	the state of the s
Revolution, Volume II - User's	Manual for STARS-2P Digital	-W142	
Computer Program 7. AUTHOR(S)		B. PERFORMING ORGA	NIZATION REPORT #
V. Svalbonas and H. Levine		1	
9. PERFORMING ORGANIZATION NAME AND AD	DDECC	10. WORK UNIT NO.	
9. PERFORMING ORGANIZATION NAME AND AD	DRESS	10. WORK ONLY NO.	
Grumman Aerospace Corp.		11. CONTRACT OR GE	ANT NO
Bethpage, NY 11714			
		NAS8-28569	& DEDIOD COVERED
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12. SPONSORING AGENCY NAME AND ADDRESS		Contractor	D
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National Aeronautics and Space	Administration		
Washington, D.C. 20546		14. SPONSORING AG	ENCY CODE
.15. SUPPLEMENTARY NOTES			
16. ABSTRACT			
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	ated for Rotational Structures -2		-
This addition to the STARS syste	em of programs retains the basic	features charact	eristic
of the system.			
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	Unclassified	166	\$6,25
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SYMBOLS

Lower Case Latin

- a semi-diameter perpendicular to Z-axis in ellipsoid
- b semi-diameter parallel to Z-axis in ellipsoid
- f distributed loads in local coordinates
- h shell thickness; face sheet thickness
- i index: beginning edge of shell segment; independent joint of kinematic link; subscript "inside"
- j index: ending edge of shell segment; dependent join't of kinematic link
- n index on harmonic
- o subscript "outside"
- r radius
- s index of segment; coordinate in cylinder or cone
- t core thickness in sandwich shell
- w normal deflection, positive inward

Upper Case Latin

- C stiffness eccentricity parameters; offset distance in ogive, ellipse
- D bending stiffness parameters
- E Young's modulus (lb/in²)
- F lineal force (lb/in)
- G shear modulus (lb/in²)
- K extensional stiffness parameters
- M bending moment on shell (in-lb/in)
- N membrane stress resultant (lb/in)
- Q transverse shear stress resultant (lb/in)
- R radius; "global" coordinate, positive radially outward

SYMBOLS (continued)

- T temperature; "global" coordinate, tangential
- X Cartesian coordinate, $\theta = 0$ at X-axis
- Y Cartesian coordinate
- Z Cartesian and "global" coordinate, coincides with axis of revolution

Greek

- α angle between rotated coordinates
- β ratio of semi-diameter parallel to Z-axis in ellipsoid to semidiameter perpendicular to Z-axis
- y shear strain; non-linear parameter; angle of inclination of kinematic link
- 5 normal coordinate, positive inward
- θ circumferential angular coordinate (rad)
- λ shell parameter
- Poisson's ratio
- o normal stress (lb/in²)
- τ shear stress (lb/in²)
- p meridional angular coordinate (rad)
- ω rotational displacement (rad)
- Ω rotational displacement in "global" coordinates (rad)
- Δ displacements in fixed or "global" coordinates
- A segment length parameter

Miscellaneous

- eq equivalent
- sø sin ø
- co cos o

Other symbols are defined in the text where used.

SECTION 1

PROGRAM CAPABILITY

The use of an accurate shell theory to analyze structural shell problems usually involves complex mathematics and numerical techniques, which are nearly impossible to treat without the aid of automated procedures. On this basis, a digital computer program based upon the Love-Reissner first order shell theory has been developed. Isotropic and kinematic hardening laws are available using an orthotropic yield surface and including the Bauschinger effect. This program can perform a nonlinear geometric and material analysis of orthotropic thin shells of revolution, subjected to nonproportional cyclic axisymmetric distributed loading or concentrated line loads, as well as thermal strains (Reference 1). Furthermore, a shell with artitrary boundary conditions, under loads which vary arbritrarily with position and under a temperature variation through the thickness, is tractable with this program. The shell can consist of any combination of the following geometric shapes:

- 1) Ellipsoidal spherical (offset from the axis of revolution allowed)
- 2) Ogival toroidal
- 3) Modified ellipse shape
- 4) Conical circular plate
- 5) Cylindrical
- 6) General point input geometry
- 7) Dummy geometry slot to be filled by the user
- 8) Discrete ring

The shell wall crossection can be a sheet, sandwich, or reinforced sheet or sandwich. The reinforcement can consist of rings and/or stringers, a waffle construction rotated at any angle to the principal coordinates, or an isogrid construction. General stiffness input options are also available. The reinforcement material properties can differ from those of the main shell, and a temperature variation can cause different properties in the two face sheets of a sandwich shell.

The basic approach to the problem (Reference 1) is to cut the structure into several shell regions. These regions need to be singly-connected shells, and can only have line loads applied at their end points. There are no restrictions on geometry, or uniform or thermal loads. The regions are further subdivided into several shell segments, each being free to have its own geometric shape, provided that the shape falls into one of the categories mentioned above.

Stiffness matrices obtained for each segment, are coupled by standard matrix methods to obtain region stiffnesses, which, after being reduced in size, are in turn coupled to form the total shell structure under analysis. Currently, the computer programs are sized to handle a structure composed of up to 29 segments in each of 29 regions arbitrarily connected to each other. There is a limitation on the size of a shell segment, which is a consequence of the demand that boundary disturbances be felt throughout the segment. This limitation is mathematically described in Section 2 (pages 2-35 to 2-37) as a length parameter. This parameter, however, is not reliable near the apex of any shell shape $(\phi = 0)$, and the segments needed in this region are actually much smaller than predicted by the parameter. A mathematical singularity occurs at the apex where r (the radius of revolution) becomes zero. It is this singularity which prevents the length parameter from being meaningful near the apex. Furthermore, the point $(\phi = 0)$ is not an acceptable input point of the program (except for the torus-ogive and offset ellipsoid), although any point outside a circle of infinitesimal radius is satisfactory. There is a considerable latitude in what can be done within each shell seg-

ment. The thickness of any segment can be symmetrically tapered and it can contain up to 14 points of discontinuity, provided that the segment center-line remains continuous and describable by a single shell geometry. A temperature distribution through the thickness can be specified at three points in a homogeneous shell, and 4 points in a shell of rigid core sandwich construction. The distribution is considered to be linear between these points. Thus, it is possible to approximate temperature distributions other than linear distributions. In the event of physically discontinuous shell centerlines, a kinematic link is available for use in the analysis. The link relates displacements across the discontinuity. This link may be used between

regions, and between segments within a region. Discrete offset rings are also available for use within or between regions.

SECTION 2

INPUT INFORMATION

2.1 GENERAL NOTES

The preceding section provides some insight into the capability of the program, and the potential that it might have for future use. If the program is applied judiciously it can be an extremely powerful tool. The mechanics of applying it should be clearly understood. With this in mind, the remaining section should be studied carefully.

The required input data may be subdivided into three main parts, namely: geometric, topological (or coupling orientation) and joint data (degree of freedom description for each joint component). Each segment requires its own geometric configuration and numerical integration control.

The output consists of stiffness coefficients for each shell segment and the actual symmetry of the coefficients is presented in a convenient form for a check on the accuracy of the integration through the segment. Region stiffnesses and their symmetry checks are also provided. Final stresses, displacements, and plastic strains are printed out for each shell segment at intervals along the segment as specified by the user of the program. The output will be further discussed in Section 3.

The present program size is described in the table below.

Table of Program Sizing

I.	Segments per region:	29
II.	Segment joints per region:	30
III.	Regions:	29
IV.	Region joints:	30

Table of Program Sizing (continued)

V. Number of points available per segment for specifying geometric or load data:

30

VI. Number of points available through the thickness for specifying temperature data:

4 plus reinforcement temperatures.

VII. Geometries:

ellipsoid, sphere, offset ellipsoid, modified ellipsoid, ogive, toroid, cone, annular plate, cylinder, general geometry, ring, elastic support, dummy geometry.

VIII. Wall cross-section options:

single sheet, equal face sheet sandwich, unequal face sheet sandwich, eccentric reinforcement (rings, stringers or both), waffle reinforcement rotated at an arbitrary angle to coordinate axes, isogrid reinforcement, arbitrary stiffness input.

IX. Number of material property tables per submission:

10

X. Number of points per material property table:

10

XI, Hardening laws:

kinematic, isotropic, perfect plasticity

XII. Orthotropy options:

isotropic or orthotropic sheet, isotropic or orthotropic sandwich, isotropic or orthotropic sandwich with different face sheet properties caused by thermal gradients, isotropic or orthotropic sheet or sandwich reinforced by different property rings or different property stringers or both, isotropic or orthotropic sheet or sandwich reinforced by a different property waffle system rotated by an angle β to coordinate axes, isotropic or orthotropic sheet or sandwich reinforced by a different property general isogrid reinforcing system, arbitrary stiffness input options used to describe other configurations.

Table of Program Sizing (continued)

XIII. Number of rings per region: 28

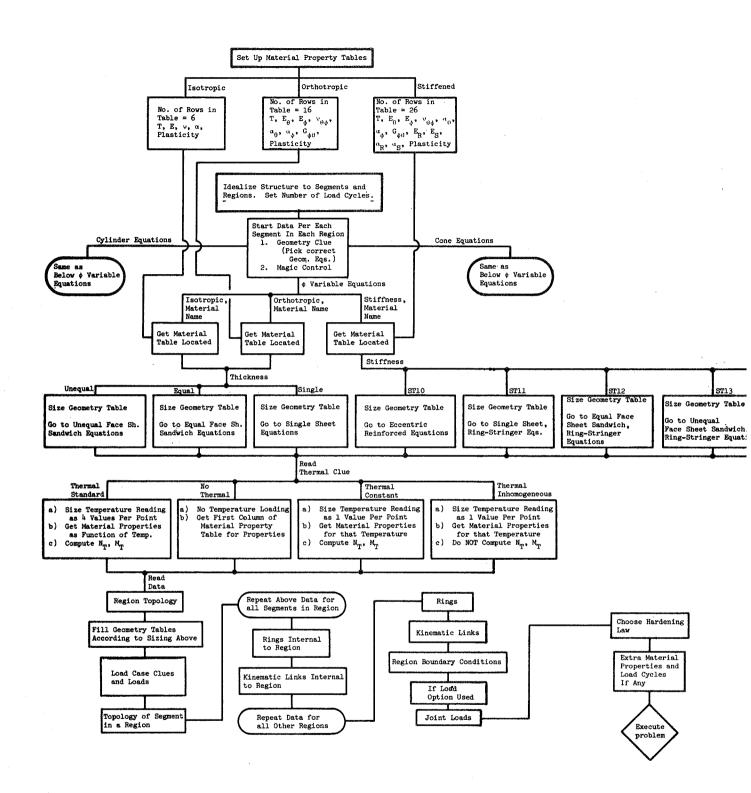
XIV. Total number of rings at

region joints in structure: 28

Figure 2-1 shows the detailed option flow chart for the present programs.

GENERAL NOTES - Idealizations

Before discussing the specific card input order, it would be advantageous to introduce some general guidelines in the area of idealizations and topology. In many computer programs there is such an abundance of numerical computation, that minimizing numerical roundoff errors becomes as important as getting the final answers. In some cases the engineer can aid the program in this effort throught the use of judicious idealizations. a possibility exists in the STARS-2 programs, since many internal operations are involved with building and inverting stiffness matrices. of the user therefore, should be to help the computer by avoiding the creation of ill-conditioned matrices at any step (see Reference 2). Physically, the way to achieve this end is to have all the segment stiffness matrices of the same order of magnitude. This will in turn produce region stiffness matrices which are of similar orders of magnitude, and minimize possible ill-conditioning in the total structure matrices. The user can help to achieve this end by sizing his segments in such a way so that no short stiff segment is contained alone in a region with all other long flexible segments, or that no region comprised of all short stiff segments exists in a structure whose other regions contain only long flexible segments. No accurate measure can be given on the relative stiffness or flexibility of segments allowed, and thus the best check is



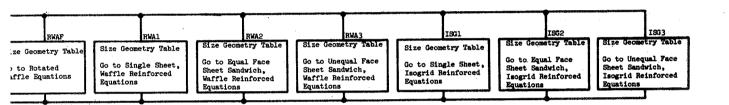


Figure 2-1 Program Option Flow Chart

to see if a structure is in equilibrium under the applied loading. In the case of the nonlinear analysis an internal equilibrium correction may be specified in the input. The symmetry checks of segment and region stiffness matrices are useful for many reasons, but will not necessarily alert a user to ill-conditioning.

In the use of regions, one other type of accident must be avoided. This is the creation of a single region structure with both ends fixed, wherein no suitable boundary condition matrix can be formed. Thus, in the use of region idealizations, which are less physically meaningful to a user than pure segment idealizations, care should be taken so that all boundary conditions are not zeroed out. To avoid this problem, and to minimize program running time, it is best to maximize the number of regions in a structure, and minimize the number of segments per region. Thus, in small problems, for best numerical efficiency, there should only be one segment per region.

In the solution of static axisymmetric problems, torsional and non-torsional states may be uncoupled. Thus if no torsional loads exist in combination with non-torsional loads, all torsional degrees of freedom can be removed. When both types of loads exist, the nonlinear analysis will be coupled.

In an incremental analysis such as the present, the number of load increments is part of the user specified "idealization". The current analysis uses each load step as a one step Newton-Raphson cycle. Thus the number of load steps necessary is directly proportional to the nonlinearity of the material stress-strain behavior. In general it may be necessary to run each problem twice: once with large steps to determine gross behavior and then, after comparing the analysis strain increments in the shell to the material property curves, with smaller steps.

GENERAL NOTES - Restarts

Since the solution of a nonlinear geometric and material problem requires the consecutive execution of a series of analyses, the program may be inadvertently cut off due to an insufficient time estimate, or the user may wish to examine the solutions of a cycling or consecutive loading problem before executing further. In order to allow the user to utilize the good data generated in such runs, a restart option has been incorporated into the STARS-2P program. This option is used as follows:

- After the complete execution of any load step the completed load step number is printed. In a load cycling run both the overall step counter (initially started from zero) and the local step counter (initialized to zero at every load change) are printed. In order to be able to restart, the tapes on units 11, 12, 13 and 15 must be saved. (The first two are necessary only if the run contains discrete rings.) These are called respectively RINGER11, RINGER12, SHPIAS13, and SHPIAS15.
- 2. Upon receipt of an aborted run the necessary restart tapes can be obtained from the completed load step printout. If the last overall load step completed was odd, the necessary tapes are RINGER11 and SHPIAS15; the other two may be released. If the last overall load step completed was even, the necessary tapes are RINGER12 and SHPIAS13; the other two may be released. (An exception to the above formula involves restarting restarted runs: If the previous restart started on an even load step the above formula is reversed.)
- In order to initiate a restart run the following must be done:
 - a. In a single load run adjust the Program Control Card as noted in items 2I and 2J.
 - b. In a load-time history or cycling run convert the load data by removing the completed cycles from the deck, and adjust

the Program Control Card accordingly. Note the item about the Ramberg-Osgood "s" parameter in the cycling input description on p 2-79.

- c. Operator instructions must be given to mount the SHPLAS restart tape on logical unit 13, and the RINGER restart tape (if necessary) on logical unit 11 (regardless of the numbers associated with the restart tape names). Scratch tapes will be mounted as usual on logical units 12 and 15.
- d. The run will now proceed as normal (even restarts of restarts).
- 4. Note: The restart tapes for any given run are not useable more than once. Upon the initiation of the computer run these tapes become scratch tapes and additional information (more load step data) will be written on them.

GENERAL NOTES - Data debugging

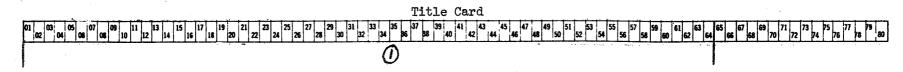
The STARS programs have been provided with special separate data debugging packages called SATELLITE programs. In order to be able to debug as much of a given data deck as possible in one computer submission, the data is grouped by inserting special cards, termed "dash-separator cards", appropriately. In order so that additional errors are not made by requiring insertion and removal of these cards, the STARS program has been coded to accept these dash-separator cards in the input. A dash-separator card is shown below:

As can be seen, a minus-symbol is inserted straight across the computer card from column 1 through column 80.

Since the dash-separator cards subdivide the data deck, there exists the possibility that a separated data block may be completely omitted (for example no kinematic links in a structure). In this case one dash-separator card is also omitted. Under no circumstances can there exist two adjacent dash-separator cards in a data deck. The SATELLITE programs are described in Reference 3.

2.2 CARD FORMATS

The following different card formats are presently required by the STARS-2P program. A full description and explanation of the information to be entered on the cards is presented in Section 2.3.



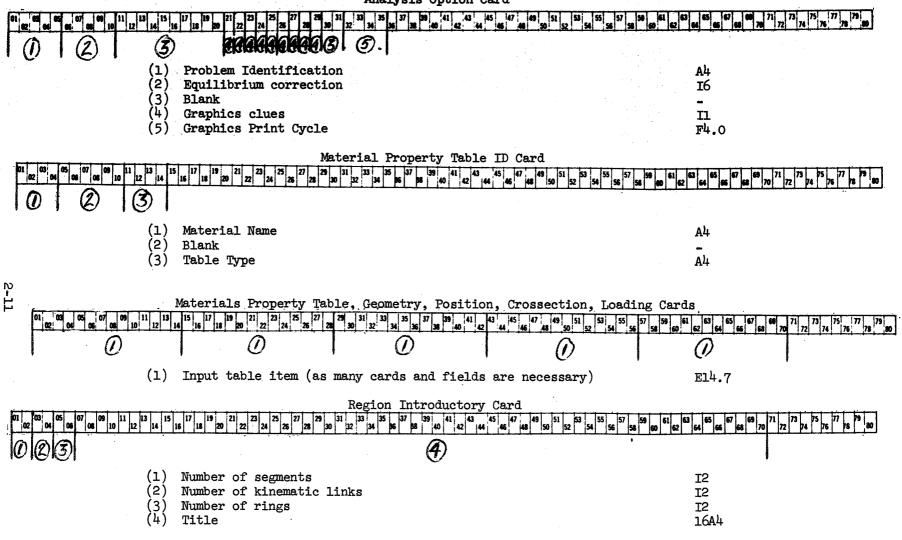
(1) Alphameric Title

16A4

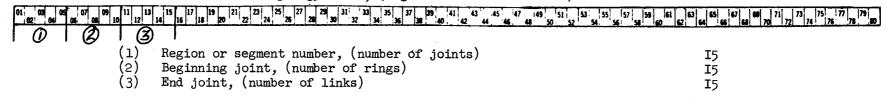
Program Control, Program Cycling Cards

01 02 03 04 05 07 09 10 11		3	0 51 53 55 57 59 0 52 54 56 58	61 63 65 67 68 70	71 73 75 77 79 80
012319151	6		\mathcal{G}	(S)	
	(1)	Number of regions		I2	
	(2)	Total number of segments		13	
က်	(3)	Number of material property tables		I2	
<u>.</u> 10	(4)	Intermediate print clue		I 2	
•	(5)	Number of load cycles		I2	
	(6)	Number of load steps		F6.0	
	(7)	Load step print increment		F4.0	
	(8)	Load unit clue	-	12	
	(9)	Nonproportional load clue	*	12	
	(10)	New material table clue		I2	
	(11)	Completed load steps in last cycle for restart		F6.0	
	(12)	Total completed load step for restart		F6.0	
	(13)	Blank		***	
	(14)	Rotation clue		. I2	
	(15)	Rotational speed		E14.7	

Analysis Option Card



Topology Cards, (Region Joint Control Card)



Segment Identification Card



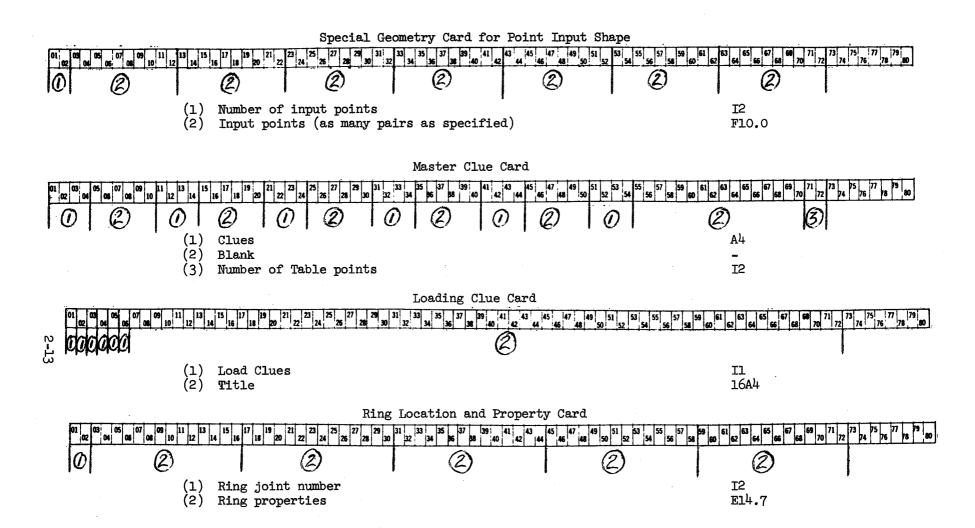
2

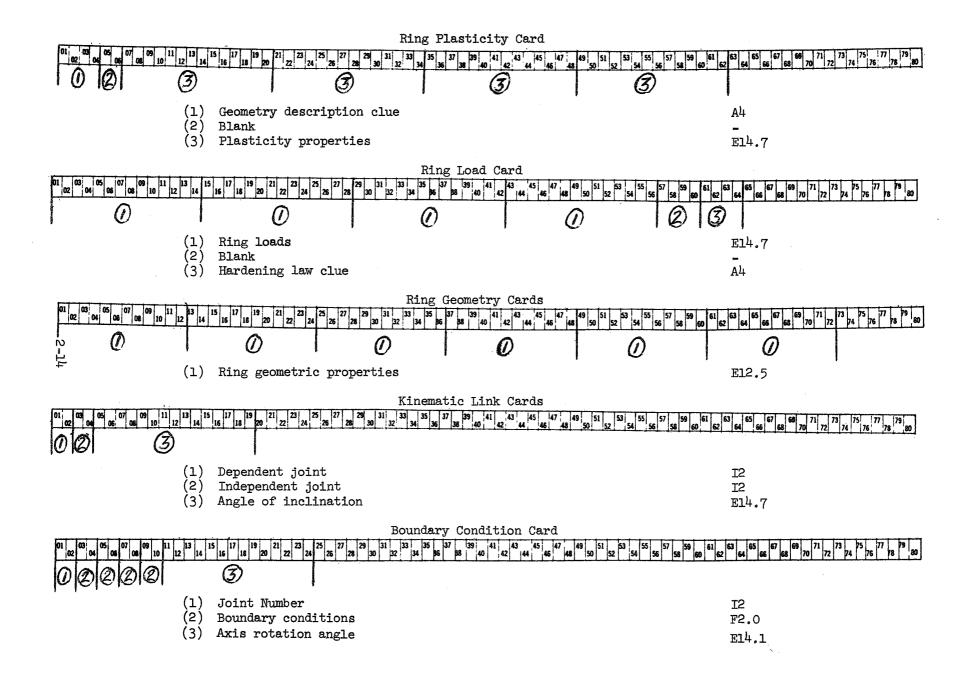
MAGIC Integration Card

| MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Card | MAGIC Integration Ca

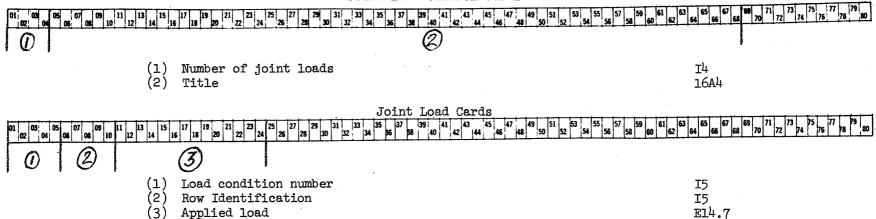
(4) Blank (5) Step control

F2.0





Joint Load Control Cards



CT-72

2.3 DETAILED ORDER OF INPUT (See Figures 2-1, 2-2)

GEN	ERAL	INTRODUCTORY CARDS	Column	Format
1.	Tit	le Card		
	A.	Alphameric title (submission description)	1-64	16A4
2.	Pro	gram Control Card		
	A.	Number of regions to be coupled (Max. = 29)	1-2	I2
	В.	Total number of segments $(Max. = 29 \times 29 = 841)$	3-5	13
	C.	Number of Material Property Tables (Max. = 10)	6-7	I 2
	D.	Intermediate print clue	8-9	I2
		If this clue is set to unity, stiffness matrices and symmetry checks will be printed for all segments and regions at the specified load step print interval (item G below). To delete this intermediate print the clue should be set to zero.		
	E.	Number of load changes	10-11	I2
		Number of load patterns or cycles to be applied in a cycling load analysis (see p 2-76).		
	F.	Number of load steps	12-17	F6.0
		Number of loading increments to be made for the first loading cycle.		

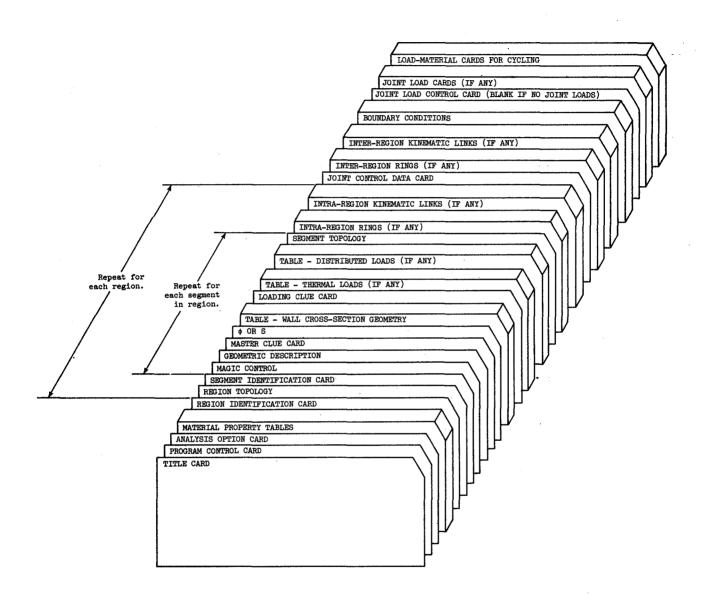


Figure 2-2 Data Sequence

		Column	Format
G.	Load step print increment	18-21	F4.0
	The interval number of load increments at which printout is desired. (Ex: print every 20 steps)	•	
H.	Load unit clue	22-23	I 2
	This clue is zero (0) for a single loading analysis. If there is a change of load distribution with time (sequential loading) this clue is two (2). For further information and load cycling see the input for the Load Cyclin Program Control Card on p 2-76.	ng	
I.	Local cycle load step count for restart	28-33	F6.0
	If the restart submission is concerned with load amplitude changes or cycling, this entry is the local count of load steps completed with the last loading amplitude input. If there is no load amplitude changes item J below and the present item are equal for restart. (See p 2-7 for restart information.)		
J.	Total load step count for restart	34-39	F6.0
	In the event that the submission is a restart problem, this entry provides the total count of previously completed load steps.		
K.	Shell rotation clue	57-58	12
	If the shell is rotating at an angular velocity about its centerline, the input clue is <u>unity</u> . If there is no rotation the clue is <u>zero</u> .		
L.	Angular Velocity in rad./sec.	59-72	E14.7
	The maximum amplitude of angular velocity of the rotating shell. This velocity will be attained in a series of steps in a nonlinear analysis analogous to a mechanical or thermal loading. The step size has been defined in item F of this card.		

				Column	Format
3.	Ana	lysis Option Card			
	A.	Analysis Description Clue		1-4	A ¹ 4
		There are three possible analysis formulating the problem is to be a small deflection plastic analysis, then the clue word is PLI If the problem is to be a large deflection elastic analysis then the clue word is NLD If the problem is to be a large deflection inelastic analysis then the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word is NLD inelastic analysis the number of the clue word inelastic analysis the number of the number of the clue word inelastic analysis analysis and number of the numb	<u>4s</u> . <u>u</u> .		٠.
	в.	Equilibrium Correction Clue		5-10	16
		Equilibrium correction loads can be used whall three analysis options above. To utilithis option set the clue to unity. To elimequilibrium corrections set the clue to zer It is recommended that equilibrium correctialways be included.	ize minate <u>ro</u> .		
	C.	Graphics Control Clues			
		The following nine (9) data fields determine plotting required for the run.	ne the		
		a. Circumferential displacement clue Clue = 1 plot u Clue = 0 or blank, do not plot u		21	n
		<pre>b. Meridional displacement clue Clue = 1, plot v Clue = 0 or blank, do not plot v</pre>		22	n
		c. Normal displacement clue Clue = 0, plot w Clue = 0 or blank, do not plot w		23	Il
		d. Hoop stress (inner face) clue Clue = 1, plot σ_{θ} in Clue = 0 or blank, do not plot σ_{θ} in		24	Il
		e. Meridional stress (inner face) clue Clue = 1, plot σ_{ϕ} in		25	Il
		Clue = or blank, do not plot σ_{ϕ} in			

			Column	Format
	f.	In-plane shear stress (inner face) clue Clue = 1, plot $\tau_{\phi\theta}$ in	26	11
		Clue = 0 or blank, do not plot $\tau_{\varphi\theta}$ in		
	g.	Hoop stress (outer face) clue Clue = 1, plot σ_{θ} out Clue = 0 or blank, do not plot σ_{θ} out	27	Il
	h.	Meridional stress (outer face) clue Clue = 1, plot σ ϕ out Clue = 0 or blank, do not plot σ ϕ out	28	Il
	i.	In-plane shear stress (outer face) clue Clue = 1, plot $\tau_{\phi\theta}$ out Clue = 0 or blank, do not plot $\tau_{\phi\theta}$ out	29	11
D.	Gra	phics Print Cycle	32-35	F4.0
	Gra	phical output will be provided in accordance		

MATERIAL PROPERTY TABLES (Max. = 10 sets)

As many sets of these cards are used (<10) as there are different material property segments in the structure to be analyzed. These tables will be used to obtain the thermal variation of material properties if thermal loadings exist. Thus the range of temperature in this table should be greater than that of the thermal loads. If no thermal loads exist, the values given in the first column of this table will be used, and the rest of the table can be left blank. If there are thermal loads, the range of the table is to be considered as that between the second and tenth columns.

'X' load step as input here.

with the Graphics Control Clues above at every

Since apex segments should not be allowed to go plastic, separate tables with fictitiously high yield stresses should be prepared for this case (see p. 2-35).

MATE	RIAL	PROPERTY TABLES (continued)	Column	Format
1.	Ide	ntification Card		
	A.	Material Title (Alphameric)	1-4	4 A
		Any name can be made up as long as it is consistently used on the segment cards to which it refers. The same name cannot appear on more than one (1) table.		
	В.	Type of Table	11-14	A4
		One of several possible alphameric clues is written here. These clues serve to size the number of cards in the property table, and define which properties belong on which card. The possible clues are:		
		ISOT ORTH STIF		
		Their definitions are provided in Item 2 below.		
2.	Mat	erial Property Cards		
	upo	material property cards below are given depending n which table type clue is used. If the table e clue is "ISOT" (isotropic table):	•	
	A.	Temperature values (5 values per card; 2 cards)		5E14.7
		These are the temperatures at which the values of material properties will be given. The first value in the table must always be the room or stress-free temperature, since the material properties in only the first column of the table will be used in an analysis involving no thermal load. The values of temperature in table columns 2 through 10 must be in algebraically increasing order.		
	В.	Values of Young's Modulus at the given temperature (5 values per card; 2 cards)	S.	5E14.7
	C.	Values of Poisson's Ratio at the given temperature (5 values per card; 2 cards)	S• .	5E14.7
	D.	Values of the thermal coefficient of expansion at the given temperatures. (5 values per card; 2 cards)		5E14.7

		Column	Format
E.	Values of the Ramberg-Osgood "s" (see Ref. 1) at the given temperatures. (5 values per card; 2 cards).		5E14.7
F.	Values of the Ramberg-Osgood "n" (see Ref. 1) at the given temperatures. (5 values per card; 2 cards).		5E14.7
G.	Values of the yield stress at the given temperatures. (5 values per card; 2 cards)		5E14.7
	Note: If the hardening law for the segment is perfect plasticity (PERF on the Master Clue Card) the items E and F above are zero.		
If the	table type clue is "ORTH" (orthotropic table):		
Α.	Temperature values (5 values per card; 2 cards)		5E14.7
	These are the temperatures at which the values of material properties will be given.		
В.	Values of Young's Modulus in the θ direction (E_{θ}) at the given temperatures. (5 values per card; 2 cards)		5E14.7
C.	Values of Young's Modulus in the ϕ direction (E $_{\phi}$) at the given temperatures. (5 values per card; 2 cards)		5 E 14.7
D.	Values of the Poisson's Ratio $v_{\theta\phi}$ at the given temperatures. Orthotropic identity defined as $E_{\theta}v_{\theta\phi}=E_{\phi}v_{\phi\theta}$.		5E14.7
	(5 values per card; 2 cards)		
E.	Values of the thermal coefficient of expansion in the θ direction (α_{θ}) at the given temperatures.		5E14.7
	(5 values per card; 2 cards)		
F.	Values of the thermal coefficient of expansion in the ϕ direction $(\alpha_{_{\dot{\varphi}}})$ at the given temperatures.		5 E 14.7
	(5 values per card; 2 cards)		
G.	Values of the Shear Modulus $G_{\phi\theta}$ at the given temperatures. (5 values per card; 2 cards)		5E14.7

		Column	Format
н.	Values of the Ramberg - Osgood "s" in the ϕ direction (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
I.	Values of the Ramberg - Osgood "n" in the ϕ direction (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
J.	Values of the yield stress in the ϕ direction at the given temperatures. (5 values per card; 2 cards)		5E14.7
K.	Values of the yield stress in the θ direction at the given temperatures. (5 values per card; 2 cards)		5E14.7
L.	Values of the yield stress in the normal (ζ) direction at the given temperatures. (5 values per card; 2 cards)		5E14.7
Μ.	Values of the shear yield stress in the $\phi\theta$ plane at the given temperatures. (5 values per card; 2 cards)	3	5E14.7
N.	Values of the Ramberg - Osgood "s" in the θ direction (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
0.	Values of the Ramberg - Osgood "n" in the θ direction (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
Ρ,	Values of the Ramberg - Osgood "s" in the $\phi\theta$ directions (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)	3	5E14.7
Q.	Values of the Ramberg - Osgood "n" in the $\phi\theta$ direction (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)	3	5E14.7
	Note: If the hardening law for the segment is perfect plasticity (PERF on the Master Clue Card) items H, I, and N through Q are zero.		

		Column	Format
	table type is "STIF" (table to be used for ced shells):		
AQ.	The values in these locations are the same as those above for the "ORTH" clue case, and refer to the basic shell.		5E14.7
R.	Values of ring Young's Modulus (E_R) at the given temperatures. (5 values per card; 2 cards)		5E14.7
s.	Values of stringer Young's Modulus (E _s) at the given temperatures. (5 values per card; 2 cards)	·	5E14.7
T.,	Values of ring thermal coefficient of expansion (α_R) at the given temperatures.		5E14.7
Ŭ•	(5 values per card; 2 cards) Values of stringer thermal coefficient of expansion (α_s) at the given temperatures.		5E14.7
	(5 values per card; 2 cards)		
٧.	Values of the Ramberg - Osgood "s" in the rings (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
W.	Values of the Ramberg - Osgood "n" in the rings (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
х.	Values of the ring yield stress at the given temperatures. (5 values per card; 2 cards)		5E14.7
Υ.	Values of the Ramberg - Osgood "s" in the stringers (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5E14.7
Z.	Values of the Ramberg - Osgood "n" in the stringers (see Ref. 1) at the given temperatures. (5 values per card; 2 cards)		5 E1 4.7
α•	Values of the stringer yield stress at the given temperatures. (5 values per card; 2 cards)		5E14.7
	Notes: If the hardening law for the segment is perfect plasticity (PERF on the Master Clue Card) items H, I, N through Q, V, W, Y, and Z are zero.		

Column Format

In a rotated waffle or isogrid constructions, items R and S, T, and U, V and Y, W and Z, X and α refer to the grid directions and are respectively identical.

D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (See General Notes - Data Debugging)

minus in 1-80

REGION INTRODUCTORY CARDS

These two cards are placed at the beginning of each region data information. Each region contains the following data set (see Figure 2-2): a) Two region introductory cards; b) data cards for each segment within the region; c) ring cards describing the discrete rings within the region, if any; and d) kinematic link cards describing the kinematic links within the region, if any.

1.	Tdent.	ificatio	n Card
	T(C)110		ii oara

	Α.	Number of segments within the region (<29)	1-2	12
	В.	Number of kinematic links between segments within the region.	3-4	12
	C.	Number of discrete rings between segments within the region.	5 - 6	I2
	D.	Any alphameric information (region description)	7 -7 0	16A4
2.	Тор			
	Α.	Region Number Number of the region under consideration.	1-5	I5
	В.	Joint (i) Joint associated with i th (beginning) end of the region.	6-10	I5
	C.	Joint (j) Joint associated with j th (ending) end of the region.	11 - 15	15

There is no coordinate flow in regions (unless 1 region = 1 segment), such as that shown for segments in Figures 2-3 to 2-9. However, the start joint of a region must match with 1 in segment numbering, and the end joint must match with the highest segment joint number in the region (see Figure 2-12 and page 2-57). If 1 region = 1 segment, the segment topology card will be a dummy card [1 1 2] (see page 2-57).

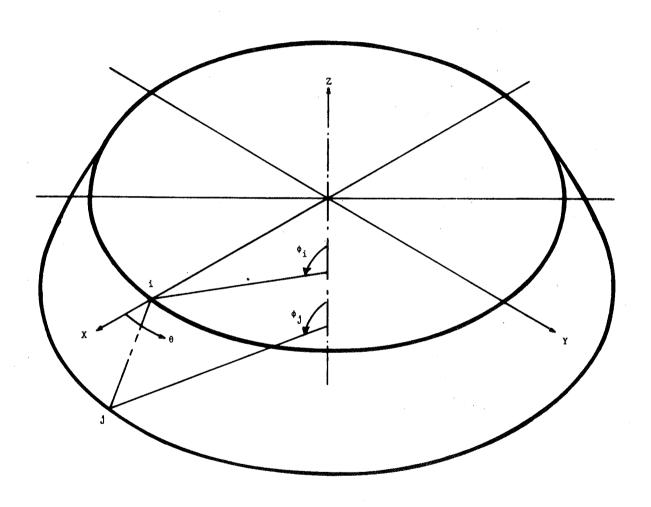


Figure 2-3. Typical Shell Segment

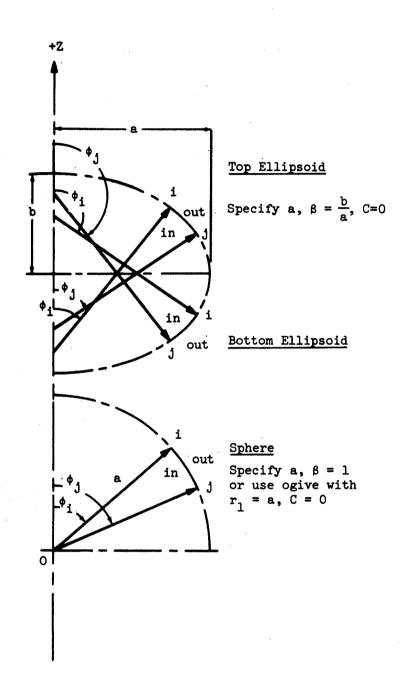


Figure 2-4a. Ellipsoid

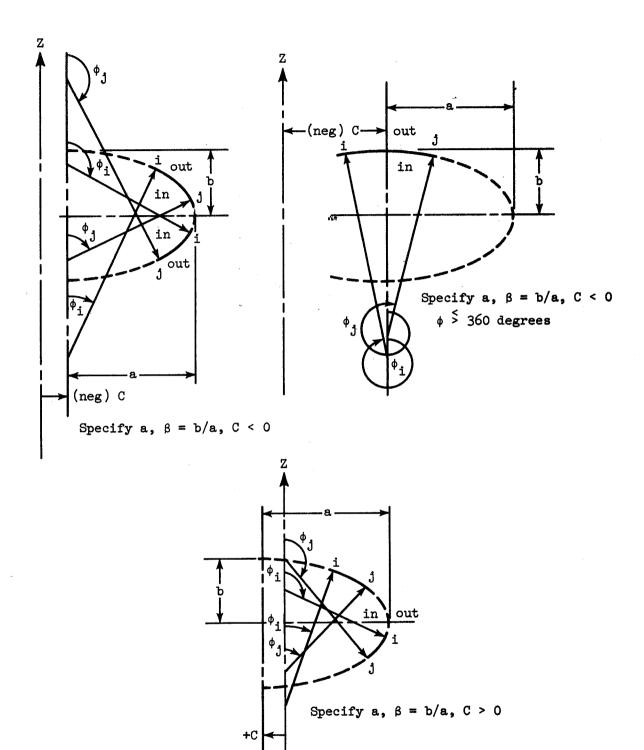


Figure 2-4b. Translated Ellipsoid 2-28

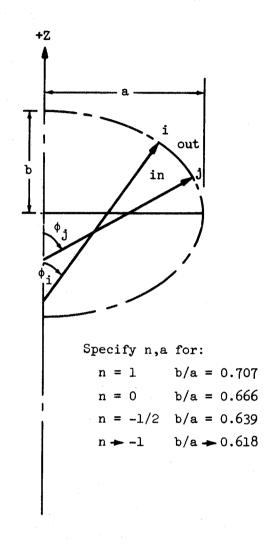


Figure 2-5. Modified Ellipsoid

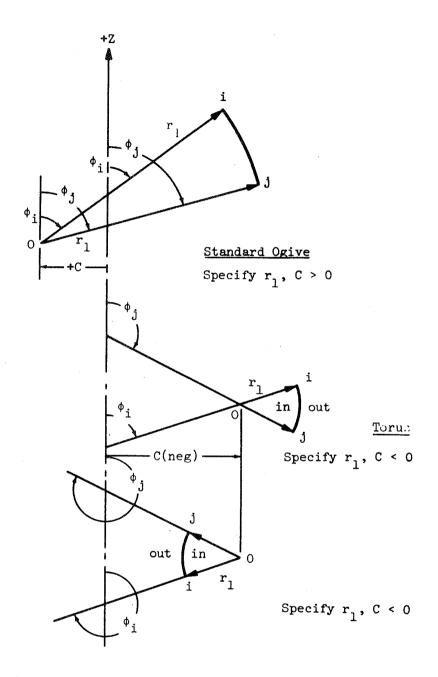
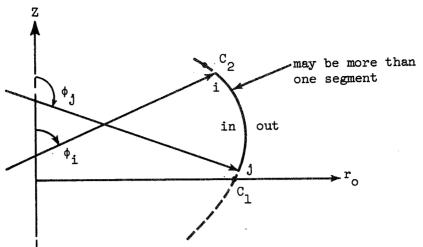


Figure 2-6. Ogive



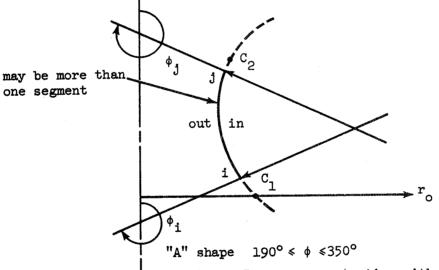
In the ranges of ϕ $0^{\circ} \le \phi < 10^{\circ}$ $170^{\circ} < \phi < 190^{\circ}$ 350° < φ ≤ 360° spherical, toroidal or elliptical segments can be used with sufficient accuracy.

one segment

10° ≤ φ ≤ 170° "B" shape

Specify: Z versus r_0 starting with Z = 0 at C_1 , and going to C_2 .

Note: Z vs r input table should overlap total range of ϕ input for all segments.



Specify: Z versus r starting with Z = 0 at C_1 , and going to C_2 .

Note: Z vs r input table should overlap total range of ϕ input for all segments.

Figure 2-7. General Geometry

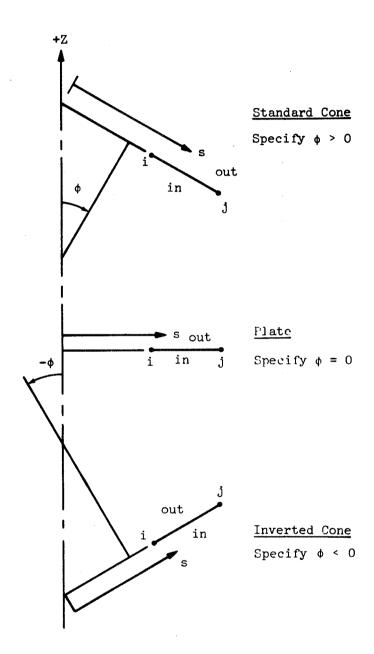


Figure 2-8. Cone

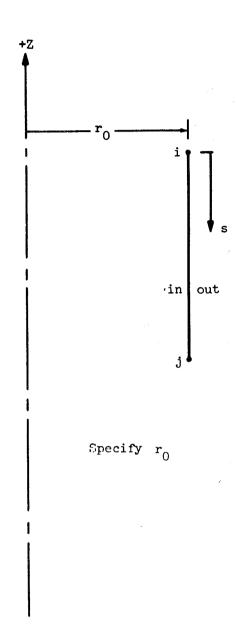


Figure 2-9. Cylinder

SEGMENT CARDS	Column	Format
This sequence of cards is repeated for each segment within the region.		
1. Identification Card		
A. Segment identification code (see Figures 2-4 to 2-	9)	
1. Ellipsoidal or spherical shell Code = 11 2. Modified ellipse shape Code = 12 3. Ogival - Toroidal Code = 13 4. General Geometry Code = 14A or (see Figure 2-7)* 5. Dummy geometry slot Code = 15	1-2 1-2 1-2 1-3	F2.0 F2.0 F2.0 F2.0Al
(φ coordinate) 6. Conical - Circular Plate Code = 21	1-2	F2.0
The plate is treated as a cone with zero angle.		
7. Cylindrical shell Code = 31	1-2	F2.0
B. Number of layers through the thickness	4-5	15
This is the number of layers through the thickness for plastic strain integration. In a single sheet construction the maximum number of layers is 20. In a sandwich construction both face sheets are divided into the same number of layers and this is the required input. The maximum number of layers for the sandwich face sheet is 8.	t	
C. Any alphameric information (segment description)	6 - 67	16A4
2. "MAGIC" Control Card		
A. Interval at which final answers are to be printed (in radians or inches).	1-14	E14.1
The \$\phi\$-coordinate is defined for all geometric shapes except the cylinder, cone and plate, for which the s coordinate is used. Figures 2-4 through 2-9 describe these coordinates for each shape.		
B. Difference	15-28	E14.1
The value recommended depends upon the computer used. For eight figure accuracy computers it is 1.0 E-6; for the IBM 360 it is 1.0 E-4.		
C. Integration interval	29-42	E14.7
The Runge Kutta numerical integration procedure is substantially more accurate than finite differencing. An interval of (.01 to.03) x segment size (in radians or inches) is recommended in eigenvalue analysis so as to be able to represent eigenvectors with high wrinkling in the segment interior (In using a 30 point segment table (see p.2-41) there should be at least 30 integration steps.)	•	

_			1/1-	- 1
n	Apex Clue		46-49	A4
۽ حد	TIPCE OLUC		70-72	**-

Column

Format

In the STARS program an apex segment is liable to have fictitiously high stresses due to the singularity effect of $r_0 \rightarrow 0$. Thus such a segment should not be allowed to go plastic, since it may prematurely stop the run. Therefore a separate material property table should be prepared containing fictitiously high yield stresses. The word \underline{APEX} should also be entered here as a reminder, and will trigger a reminder message in the output.

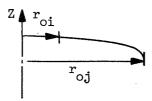
E. Delta 71-72 F2.0

For a fixed-step integration, Delta = 0.

This card controls the Runge-Kutta numerical integration scheme. The suggested values above yield accurate results for a fixed-step integration method.

Calculation of Segment Length

There is a restriction on the length of the shell segments. Physically, the restriction demands that boundary disturbances at one edge be distinctly felt at the other edge. This is a consequence of using a numerical integration procedure. Since the segment stiffness matrices must be symmetric, the calculations involved in obtaining each matrix element must be such that a computer round off error never becomes prominent. Limiting the segment length insures satisfaction of this criterion. This length is a function of both geometric shape and segment location within a specific geometry. One of the limiting factors is that the ratio of the radii of revolution at the initial and final points of a segment be greater than one hundredth and less than one hundred. Thus $\frac{1}{100} < \left(\frac{r_{oi}}{r_{oi}}\right) < 100$ where:



This requires smaller segments than will normally be predicted by formula in the area of an apex. In addition, note that $(\phi = 0)$ is <u>not</u> an acceptable input point (except for the torus-ogive or offset ellipsoid). Also the apex segment should <u>not</u> be allowed to go plastic by adjusting the corresponding material property table.

For a cylinder, the segment length parameter,

$$\Lambda = (1 + \gamma)^{\frac{1}{2}} \beta \Delta s$$

should be held to about 4.0. In this expression, " γ " is a non-linear parameter. For homogeneous shells:

$$\gamma = \left[3(1 - v^2)\right]^{\frac{1}{2}} \left(\frac{\overline{N}_{\phi} r_0}{EH^2}\right)$$

It is zero for a linear problem.

" β " is a measure of the rate of decay of a disturbance in the shell.

"As" is the meridional length.

$$r_0 = r_2 \sin \phi$$

The values of β^{l_1} and Δs for various shell geometries are given below:

The values of	β and Δs for various shell ge	ometries are given below:
		Por ν = 0.3, A ≤ %
Nomogeneous Cylinder	$g^{k} = \frac{3(1-v^{2})}{r_{0}^{2}H^{2}}$	$\Delta a \le \frac{3.11(r_0 N)^{\frac{1}{2}}}{(1+\gamma)^{\frac{1}{2}}}$
Sandwich Cylinder - Equal Pace Sheets	$s^{k} = \frac{3(1-v^{2})}{r_{0}^{2}(4h^{2}+6ht+3t^{2})}$	as 5 3.11 [r ₀ ² (4h ² + 6he + 3e ²)]
Sandwich Cylinder - Unequal Face Sheets	$s^{b} = \frac{3(1-v^{2})}{(h_{1}+h_{0})^{b}+12h_{1}h_{0}t(h_{1}+h_{0}+t)} \left[\frac{h_{1}+h_{0}}{r_{0}}\right]^{2}$	$\Delta s \leq 3.11 \left[\frac{r_0}{h_1 + h_0} \right]^{\frac{1}{2}} \left[(h_1 + h_0)^{h} + 12h_1h_0t(h_1 + h_0 + t) \right]^{\frac{1}{4}}$

Approximate formulas can be obtained for near cylindrical regions of generally curved surfaces. The length parameter,

$$\Lambda = (1 + \gamma)^{\frac{1}{2}} \lambda \Delta \phi$$

should be held to about 4.0. In this expression " γ " has the same definition as in the cylinder case.

" λ " is a measure of the rate of decay of a disturbance in the shell.

" $\Delta \phi$ " = $\frac{\Delta s}{r_1}$ is the angle intercepted by a meridional arc length " Δs ".

The values of $\lambda^{\frac{1}{4}}$ and Δs for various shell geometries are given below:

		For v = 0.3, A ≤ 4:
Nomogeneous Construction	$\lambda^{k_1} = 3(1 - v^2) \frac{r_1^{k_1}}{r_2^2 H^2}$	$\Delta s \le \frac{3.11(r_2 H)^{\frac{1}{2}}}{(1 + \gamma)^{\frac{1}{2}}}$
Sandwich Construction - Equal Face Sheets	$\lambda^{\frac{1}{4}} = \frac{3(1 - v^2)r_1^{\frac{1}{4}}}{r_2^{2}(4h^2 + 6ht + 3t^2)}$	$\Delta s \ s \ 3.11 \left[\ r_2^{\ 2} (\ln^2 + 6 \ln t + 3t^2) \right]^{\frac{1}{h}}$
Sandwich Construction - Unequal Face Sheets	$\lambda^{h} = \frac{3(1 - v^{2})r_{\lambda}^{h}}{(h_{1} + h_{0})^{h} + 12h_{1}h_{0}t(h_{1} + h_{0} + t)} \left[\frac{h_{1} + h_{0}}{r_{2}}\right]^{2}$	$\Delta a \leq 3.11 \left[\frac{r_2}{h_1 + h_0} \right]^{\frac{1}{2}} \left[(h_1 + h_0)^{h} + 12h_1h_0 \epsilon(h_1 + h_0 + \epsilon) \right]^{\frac{1}{h}}$

The minimum allowable segment length is 1 x 10^{-3} (inches or radians according to segment sizing).

3. Geometric Description Card

Ell	ipsoid and sphere (Figure 2-4)	Column		Format
	Ratio of semi-axis in the Z-direction (b)	1-14 15-28		E14.1 E14.1
2	(4)	00 10		77.1. 7
		29-42		E14.1
ı.	Axis ratio coefficient (n)	1-14 15-28		E14.1 E14.1
Ogi	ve (Figure 2-6)			
1.	r ₁ = radius	1-14		E14.1
2.	<pre>C = offset distance (±)</pre>	15-28		E14.1
Gen	eral Geometry (Figure 2-7)		•	
ı.	Number of pairs of Z versus r points (<14)	1-2		12
2.	Z versus r points, in pairs, starting	3-72		Flo.0
	with Z value (7 values per card, including first card, for up to 4 cards total).	1-70	or	F10.0
	In the input table the first Z value is taken as $Z_1 = 0$, and furthermore $Z_i > 0$			
	(i = 2 - 14) (see Figure 2-7).			
	1. 2. Mod 1. 2. Ogi 1. 2. Gen 1.	 Ratio of semi-axis in the Z-direction (b) to (a), β = (b/a) C = offset distance (±) (C = 0.0 if no offset) Modified ellipse shape (Figure 2-5) Axis ratio coefficient (n) Semi-axis perpendicular to Z-direction (a) Ogive (Figure 2-6) r₁ = radius C = offset distance (±) General Geometry (Figure 2-7) Number of pairs of Z versus r₀ points (<14) Z versus r₀ points, in pairs, starting with Z value (7 values per card, including first card, for up to 4 cards total). In the input table the first Z value is taken as Z₁ = 0, and furthermore Z_i > 0 	1. Semi-axis perpendicular to Z-direction (a) 2. Ratio of semi-axis in the Z-direction (b) 15-28 to (a), β = (b/a) 3. C = offset distance (±) (C = 0.0 if no offset) 29-42 Modified ellipse shape (Figure 2-5) 1. Axis ratio coefficient (n) 2. Semi-axis perpendicular to Z-direction (a) 15-28 Ogive (Figure 2-6) 1. r 1 = radius 1-14 2. C = offset distance (±) General Geometry (Figure 2-7) 1. Number of pairs of Z versus r points (<14) 1-2 2. Z versus r points, in pairs, starting with Z value (7 values per card, including first card, for up to 4 cards total). In the input table the first Z value is taken as Z 1 = 0, and furthermore Z 1 > 0	1. Semi-axis perpendicular to Z-direction (a) 1.14 2. Ratio of semi-axis in the Z-direction (b) 15-28 to (a), β = (b/a) 3. C = offset distance (±) (C = 0.0 if no offset) 29-42 Modified ellipse shape (Figure 2-5) 1. Axis ratio coefficient (n) 2. Semi-axis perpendicular to Z-direction (a) 15-28 Ogive (Figure 2-6) 1. r 1 = radius 1-14 2. C = offset distance (±) General Geometry (Figure 2-7) 1. Number of pairs of Z versus r points (<14) 2. Z versus r points, in pairs, starting with Z value (7 values per card, including first card, for up to 4 cards total). In the input table the first Z value is taken as Z 1 = 0, and furthermore Z i > 0

	E+	Cone (Figure 2-8)	Column	Forma
		 Angle φ in radians (for flat plate, φ = 0). Keep in mind that this φ is a constant for a given cone and should not be confused with the φ on card set 5. 	1-14	E14.1
	F.	Cylinder (Figure 2-9)		
		1. Radius	1-14	E14.1
4.	Mas	ter Clue Card		
	ter use mas	s card contains a series of clues which de- mine the program and table locations to be d for the segment being described. For a ster flow chart of clues and options in the gram see Figure 2-1.		
	Α.	Material Table Type Clue	1-4	Alt
		This clue defines the type of material property table to be expected for the segment. This, as well as the following clue determines the material properties that will be used in the structural analysis for the segment. Thus these two clues should match the two clues used on the identification card of the corresponding material property table. As mentioned before on page 2-21, the three possibilities are:		
		ISOT ORTH STIF		
	В.	Material Title	11-14	Al+
		This name should be the same as the name which appears on the material property table which contains the properties to be utilized for this segment.		
	C.	Sheet Clue	21-24	Al+
		This clue informs the program as to what kind of shell wall crossection to expect. If the shell is of single sheet construction, the clue to be used is: SING. If the shell wall is an equal-size face sheet sandwich, the clue to be used is: EQUA. If the shell wall is a sandwich but the face sheets are not equal, the clue to be used is: UNEQ. Finally, if the shell segment is reinforced by rings, stringers, waffle, or an isogrid, the clue to be used is: BLAN.	<u>a</u>	
		930399 (75.777-6)		

A4

D. Reinforcement Clue

31-34

This clue describes the type of reinforcement that is present on the shell. If the shell is purely of single sheet or equal or unequal-size face sheet honeycomb construction (no reinforcing), the clue to be used is: THIC. If the reinforcement consists of rings or stringers or both, located along the coordinate axes (θ and ϕ or s), three clues are possible depending upon the basic shell wall construction. If the basic wall construction is a single sheet, the clue to be used is ST11. If the basic shell wall is an equal-size face sheet sandwich, the clue to be used is ST12. If the basic shell wall is a sandwich but the face sheets are unequal, the clue to be used is ST13. If the reinforcement consists of a waffle which is rotated at an arbitrary angle β from the meridional axis the following three clues are possible depending upon the basic shell wall construction. If the basic wall construction is a single sheet, the clue to be used is RWAL. If the basic shell wall is an equal-size face sheet sandwich, the clue to be used is RWA2. If the basic shell wall is a sandwich but the face sheets are unequal, the clue to be used is RWA3. If the reinforcement consists of an isogrid construction of general angle β from the meridional axis (normally $\beta = 30^{\circ}$) the following three clues are possible depending upon the basic shell wall construction. If the basic wall construction is a single sheet, the clue to be used is ISG1. If the basic shell wall is an equal-size face sheet sandwich, the clue to be used is ISG2. If the basic shell wall is a sandwich but the face sheets are unequal, the clue to be used is ISG3. Two other clues are available, namely ST10 and RWAF, if the user wishes to imput his own stiffness constants. These constants may represent any wall construction as long as the basic Hooke's Laws used with the clues are appropriate to describe the construction to be considered. The Hooke's Laws used with these clues are given under the description of segment card set 6. No plastic analysis is allowed with the last two clues since a geometric description of the crossection is not input.

Column

Form

Α4

The reinforcement described in the segment cards is closely spaced reinforcement which will be smeared over the segment. Discrete rings at segment ends in a region are described at the end of all segment data for that region.

Thermal Clue

41-44

This clue describes the type of thermal problem which exists in the segment. The user is reminded that in a cycling run this clue is constant for all cycles, requiring zero thermal loads to be input if necessary. If there is no thermal load on the segment, the clue to be used is NOTH. If the thermal loading on the segment is of general, standard type, that is if there is variation of temperature through the thickness as well as in the coordinate directions, the clue to be used is THST. If the thermal load is such that the variation is all in the coordinate directions, and there is no thermal variation through the thickness, the clue to be used is THCN. The last clue concerns a shell which is inhomogeneous in the meridional direction. This is not really a thermal problem at all, but merely a manipulation of the material property tables. If a structure has a wide variation in material properties in the meridional direction, without this last option one must take short segments of constant properties for analysis. With this option, however, the property variation is placed in the material property table, and expressed on the segment as a function of temperature. No thermal loads are calculated, however, and the temperatures are only used to interpolate for material properties as integration is progressing along the segment. Thus continual variation of properties in the meridional direction is accommodated. The clue for this option is THIN.

F. Hardening Law Clue

51-54

A4

This clue determines the hardening law to be used for the segment. If isotropic hardening is to be used the clue is ISOT. If kinematic hardening is to be used the clue is KINE. If perfect plasticity is to be used the clue is PERF.

Note: ISOT hardening law is not allowed with ORTH material (item A on this card).

G. Table control - Number of points in each of the following tables.

71-72

12

This can vary from 2 to 30 depending upon the shell geometry and loading. For a linearly varying geometry and/or loading only 2 input points would be required. These two points would be the end points. For more general loading and/or geometry a larger number of points are required. In particular, each abrupt change is specified by two points. One should use as many points as necessary (up to 30) in order to completely describe the problem, rather than using very short segments.

5. Table of ϕ or s Values

A. Initial, intermediate and final values of \$\phi\$ or s. Each point requires 14 columns on a card and thus there can be 5 values per card and up to 6 cards to make a total of up to 30 points. The points to be specified are the beginning point of the segment, any point of discontinuity, and the end point of the segment. The input must be consistent with item G of the previous card. 5E14.7

6. Table of Wall Crossection Geometry

The contents of these cards (up to 6 cards per item below) are dependent upon the clues registered on the Master Clue Card. If the shell to be described contains no reinforcing, the pertinent clue is item 4C, the Sheet Clue. The geometry is input and the stiffnesses are calculated by the program (see Figure 2-10). The input is presented below as a function of the Sheet Clue.

If the Sheet Clue is SING (single sheet construction):

A. Initial, intermediate and final values of wall thickness (h_i) at points defined by table of \$\phi\$ or s values.

5E14.7

$$\overline{\zeta}_{\text{in}} = \frac{h_1^2 + h_0^2 + 2h_1h_0 + 2h_0t}{2(h_1 + h_0)}$$

$$\overline{\zeta}_{\text{out}} = \frac{h_1^2 + h_0^2 + 2h_1h_0 + 2h_0t}{2(h_1 + h_0)}$$

$$\overline{\zeta}_{\text{out}} = \frac{h_1^2 + h_0^2 + 2h_1h_0 + 2h_1t}{2(h_1 + h_0)}$$

$$\overline{\zeta}_{\text{out}} = \frac{h_1^2 + h_0^2 + 2h_1h_0 + 2h_1t}{2(h_1 + h_0)}$$

$$\overline{\zeta}_{\text{out}} = \frac{h_1^2 + h_0^2 + 2h_1h_0 + 2h_1t}{2(h_1 + h_0)}$$

E,v, Constant through thickness

Unequal material properties for the face sheets.

Restriction: properties are such that a neutral plane exists.

Configuration	Extensional Stiffness	Flexural Stiffness	Shear Stiffness
fhi Orthotropic	$K_{11} = \frac{E_{\theta}h_{1}}{1 - v_{\phi\theta}v_{\theta\phi}}$ $K_{22} = \frac{E_{\phi}h_{1}}{1 - v_{\phi\theta}v_{\theta\phi}}$	$D_{11} = \frac{E_{\theta}h_{1}^{3}}{12(1 - v_{\theta\theta}v_{\theta\phi})}$ $D_{22} = \frac{E_{\phi}h_{1}^{3}}{12(1 - v_{\theta\theta}v_{\theta\phi})}$	$R_{33} = G_{\phi \theta} h_1$ $R_{33} = \frac{G_{\phi \theta} h_1^{3}}{12}$
Thi Equal t Face Sheets	$K_{11} = \frac{E_{\theta_1}^{h_1}}{1 - v_{\theta\theta_1}^{h_{\theta_1}} v_{\theta\theta_1}} + \frac{E_{\theta_2}^{h_1}}{1 - v_{\theta\theta_2}^{h_1} v_{\theta\theta_2}}$ $K_{22} = \frac{E_{\phi_1}^{h_1}}{1 - v_{\phi\theta_1}^{h_1} v_{\theta\theta_1}} + \frac{E_{\phi_2}^{h_1}}{1 - v_{\phi\theta_2}^{h_2} v_{\theta\phi_2}}$	$ D_{11} = \frac{E_{\theta_{1}}^{h_{1}^{3}}}{12(1-v_{\theta\theta_{1}}^{h_{1}^{3}}v_{\theta\theta_{1}}^{h_{1}^{3}})} + \frac{E_{\theta_{2}}^{h_{1}^{3}}}{12(1-v_{\theta\theta_{2}}^{h_{2}^{3}}v_{\theta\theta_{2}}^{h_{2}^{3}})} + h_{1} \left\{ \frac{E_{\theta_{1}}^{(\zeta_{1n}^{-\frac{h_{1}}{2}})^{2}}}{1-v_{\theta\theta_{1}}^{h_{1}^{3}}v_{\theta\theta_{1}}^{h_{1}^{3}}} + \frac{E_{\theta_{2}}^{(\zeta_{0n}^{-\frac{h_{1}}{2}})^{2}}}{12(1-v_{\theta\theta_{2}}^{h_{2}^{3}}v_{\theta\theta_{2}}^{h_{2}^{3}})} + h_{1} \left\{ \frac{E_{\theta_{1}}^{(\zeta_{1n}^{-\frac{h_{1}}{2}})^{2}}}{1-v_{\theta\theta_{1}}^{h_{2}^{3}}v_{\theta\theta_{1}}^{h_{2}^{3}}} + \frac{E_{\theta_{2}}^{(\zeta_{0n}^{-\frac{h_{1}}{2}})^{2}}}{1-v_{\theta\theta_{1}}^{h_{2}^{3}}v_{\theta\theta_{1}}^{h_{2}^{3}}} \right\} $	$K_{33} = h_{1}(G_{\phi\theta_{1}} + G_{\phi\theta_{2}})$ $D_{33} = \frac{h_{1}^{3}}{12}(G_{\phi\theta_{1}} + G_{\phi\theta_{2}}) + h_{1}(G_{\phi\theta_{1}}(\overline{\xi}_{1n} - \frac{h_{1}}{2})^{2} + G_{\phi\theta_{2}}(\overline{\xi}_{out} - \frac{h_{1}}{2})^{2}]$
Thi Unequal Face Sheets	$K_{11} = \frac{E_{\theta_{1}}^{h_{1}}}{1 - v_{\theta \theta_{1}}^{h_{\theta_{1}}}} + \frac{E_{\theta_{2}}^{h_{0}}}{1 - v_{\theta \theta_{2}}^{h_{\theta_{2}}}}$ $K_{22} = \frac{E_{\theta_{1}}^{h_{1}}}{1 - v_{\theta \theta_{1}}^{h_{\theta_{1}}}} + \frac{E_{\theta_{2}}^{h_{0}}}{1 - v_{\theta \theta_{2}}^{h_{\theta_{2}}}}$	$D_{11} = \frac{E_{\theta_{1}}h_{1}^{3}}{12(1-v_{\theta\theta_{1}}v_{\theta\theta_{1}})} + \frac{E_{\theta_{2}}h_{0}^{3}}{12(1-v_{\theta\theta_{2}}v_{\theta\theta_{2}})} + \frac{E_{\theta_{1}}h_{1}(\overline{\zeta}_{1n}\frac{h_{1}}{2})^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}\frac{h_{0}}{2})^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{1n}\frac{h_{1}}{2})^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}\frac{h_{0}}{2})^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{1}}h_{1}(\overline{\zeta}_{1n}-h_{1}/2)^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}-h_{0}/2)^{2}}{1-v_{\theta\theta_{2}}v_{\theta\theta_{2}}} + \frac{E_{\theta_{1}}h_{1}(\overline{\zeta}_{1n}-h_{1}/2)^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}-h_{0}/2)^{2}}{1-v_{\theta\theta_{2}}v_{\theta\theta_{2}}} + \frac{E_{\theta_{2}}h_{1}(\overline{\zeta}_{1n}-h_{1}/2)^{2}}{1-v_{\theta\theta_{1}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}-h_{0}/2)^{2}}{1-v_{\theta\theta_{2}}v_{\theta\theta_{2}}} + \frac{E_{\theta_{2}}h_{1}(\overline{\zeta}_{1n}-h_{1}/2)^{2}}{1-v_{\theta\theta_{2}}v_{\theta\theta_{1}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}_{out}-h_{0}/2)^{2}}{1-v_{\theta\theta_{2}}v_{\theta\theta_{2}}} + \frac{E_{\theta_{2}}h_{0}(\overline{\zeta}$	$K_{33} = G_{\phi\theta_{1}}^{h_{1}} + G_{\phi\theta_{2}}^{h_{0}}$ $\supset_{33} = \frac{G_{\phi\theta_{1}}^{h_{1}}}{12} + \frac{G_{\phi\theta_{2}}^{h_{0}}}{12} + G_{\phi\theta_{1}}^{h_{0}} + G_{\phi\theta_{1}}^{h_{1}} (\bar{\zeta}_{1n} - \frac{h_{1}}{2})^{2} + G_{\phi\theta_{2}}^{h_{0}} (\bar{\zeta}_{out} - \frac{h_{0}}{2})^{2}$

Figure 2-10 Shell Section Properties

		Column	Format
If the Sheet Clue is sandwich):	EQUA (equal-size face sheet		
	diate and final values of face (h _i) at points defined by table		5E14.7
	diate and final values of core points defined by table of ϕ		5E14.7
If the Sheet Clue is sandwich):	UNEQ (unequal-size face sheet		
	diate and final values of <u>inner</u> ness (h _i) at points defined by values.		5E14.7
B. Initial, intermediation thickness (t) at or s values.	diate and final values of core points defined by table of ϕ		5E14.7
	diate and final values of <u>outer</u> ness (h _o) at points defined by values.		5E14.7
ment Clue (item 4D) of card series 6. For geometry can be composed reinforcing are to	forced, the Sheet Clue will be it is the following, or Reinforce which will determine the contents or the reinforcement cases the lex and varied, since all types o be included. The reinforced nted below as a function of the		
If the Reinforcement reinforced by rings	Clue is STll (single sheet and/or stringers):		
torsional stiffn	diate and final values of the ess in the ϕ direction (GJ $_\phi$) at y table of ϕ or s values.		5E14.7
torsional stiffn	diate and final values of the ess in the θ direction (GJ $_{m{ heta}}$) at y table of ϕ or s values.		5E14.7
•	diate and final values of $\begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ at points defined by table of		5 El⁴. 7
	diate and final values of ring nts defined by table of ϕ or s		5 E1 4.7
stringer eccentry base shell centre	diate and final values of icity (measured inwards from oid as positive) at points of ϕ or s values.		5E14.7

		Column	Format
F.	Initial, intermediate and final values of ring eccentricity (measured inwards from base shell centroid as positive) at points defined by table of ϕ or s values.		5 E 14.7
G.	Initial, intermediate and final values of stringer moment of inertia (about base shell centroidal axis) at points defined by table of ϕ or s values.		5E14.7
Н.	Initial, intermediate and final values of ring moment of inertia (about base shell centroidal axis) at points defined by table of ϕ or s values.		5E14.7
I.	Initial, intermediate and final values of stringer spacing at points defined by table of ϕ or s values. (Do <u>not</u> set to zero if no stringe	rs.)	5E14.7
J.	Initial, intermediate and final values of ring spacing at points defined by table of ϕ or s values. (Do <u>not</u> set to zero if no rings.)	*	5 E14. 7
K.	Initial, intermediate and final values of base shell wall thickness (h _i) at points defined by table of ϕ or s values.		5E14.7
	the Reinforcement Clue is ST12 (equal face sheet dwich reinforced by rings and/or stringers):		
Α.	through J. The items contained on these cards are those described for the STll clue above.	10 sets of	5E14.7
к.	Initial, intermediate and final values of base shell face sheet thickness (h_i) at points defined by table of ϕ or s values.		5E14.7
L.	Initial, intermediate and final values of base shell core thickness (t) at points defined by table of ϕ or s values.		5E14.7
	the Reinforcement Clue is ST13 (unequal face et sandwich reinforced by rings and/or stringers):		
Α.	through J. The items contained on these cards are those described for the STll clue above.	10 sets of	5E14.7
K.	Initial, intermediate and final values of base shell <u>inner</u> face sheet thickness (h_i) at points defined by table of ϕ or s values.		5E14.7
L.	Initial, intermediate and final values of base shell core thickness (t) at points defined by table of ϕ or s values.		5E14.7

		Co1	.umn		Format
Μ.	Initial, intermediate and final values of base shell <u>outer</u> face sheet thickness (h_0) at points defined by table of ϕ or s values.				5E14.7
rei	the Reinforcement Clue is RWAl (single sheet nforced by a waffle rotated at an arbitrary angle m the meridional direction):				
Α.	Initial, intermediate and final values of waffle grid area at points defined by table of ϕ or s values.		· -		5 E1 4.7
В.	Initial, intermediate and final values of waffle grid eccentricity (measured inwards from base shell centroid as positive) at points defined by table of ϕ or s values.				5 E1 4.7
C.	Initial, intermediate and final values of waffle grid moment of inertia (about base shell centroidal axis) at points defined by table of ϕ or s values.				5E14.7
D.	Initial, intermediate and final values of waffle grid spacing at points defined by table of ϕ or s values.				5E14.7
Е.	Initial, intermediate and final values of waffle grid rotation angle, β , (in radians from the meridional direction) at points defined by table of ϕ or s values.				5E14.7
F.	Initial, intermediate and final values of extreme distance from base shell centroid to waffle outer edge (\pm value, positive inwards), at points defined by table of ϕ or s values.				5 E1 4.7
G•	Initial, intermediate and final values of base shell wall thickness (h) at points defined by table of ϕ or s values.				5E14.7
sar	the Reinforcing Clue is RWA2 (equal face sheet adwich reinforced by a waffle rotated at an vitrary angle from the meridional direction):				
Α.	through F. The items contained on these cards are those described for the RWAL clue above.	6	sets	of	5 E 14.7
G•	and H. The items contained on these cards are those described for the ST12 clue above as items K. and L.	2	sets	of	5E14.7
sar	the Reinforcing Clue is RWA3 (unequal face sheet adwich reinforced by a waffle rotated at an ditrary angle from the meridional direction):				
Α.	through F. The items contained on these cards are those described for the RWAL clue above.	6	sets	of	5 E1 4.7
G.	through I. The items contained on these cards are those described for the ST13 clue above as items K. through M.	3	sets	of	5E14.7

	Column	Format
If the Reinforcing Clue is ISG1 (single sheet reinforced by a general angle isogrid construction):		
A. through D. The items contained on these cards are identical to those described for the RWAl clue above, but with reference to the isogrid.	4 sets of	5 E 14.7
E. Initial, intermediate and final values of the isogrid angle, β, (in radians from the meridional direction, see Reference ^l Appendix A). For the normal isogrid, the angle is 30° (input in radians).		5E14.7
F. Initial, intermediate and final values of base shell wall thickness (h_i) at points defined by table of ϕ or s values.		5E14.7
If the Reinforcing Clue is ISG2 (equal face sheet sandwich reinforced by a general angle isogrid construction):		
A. through E. The items contained on these cards are those described for the ISG1 clue above.	5 sets of	5 E 14.7
F. and G. The items contained on these cards are those described for the ST12 clue above as items K. and L.	2 sets of	5E14.7
If the Reinforcing Clue is ISG3 (unequal face sheet sandwich reinforced by a general angle isogrid construction):		
A. through E. The items contained on these cards are those described for the ISG1 clue above.	5 sets of	`5E14.7
F. through H. The items contained on these cards are those described for the ST13 clue above as items K. through M.	3 sets of	5E14.7
If the Reinforcing Clue is ST10 the following Hooke's Laws will be used by the program for the description of the shell wall:		
$N_{\theta} = K_{11} \epsilon_{\theta}^{i} + K_{12} \epsilon_{\phi}^{i} - C_{11} k_{\theta} - N_{T\theta}$		
$N_{\phi} = K_{22} \epsilon_{\phi} + K_{12} \epsilon_{\theta} - C_{22} k_{\phi} - N_{T\phi}$		
$N_{\phi\theta} = N_{\theta\phi} = K_{33} \gamma_{\phi\theta}$		

		<u>Column</u>	Format
	$M_{\theta} = D_{11}k_{\theta} + D_{12}k_{\phi} + C_{11}\epsilon_{\theta} - M_{T\theta}$		·
	$M_{\phi} = D_{22}k_{\phi} + D_{12}k_{\theta} + C_{22}\epsilon_{\phi} - M_{T\phi}$	7	
	$M_{\phi\theta} = -M_{\theta\phi} = -2D_{33}k_{\phi\theta}$		
Ther	refore the input is (see Ref. 4 Appendix A):		
Α.	Initial, intermediate and final values of $K_{\text{at points defined by table of } \phi}$ or s values.		5 E 14.7
В.	Initial, intermediate and final values of K_{12} at points defined by table of ϕ or s values.		5E14.7
C.	Initial, intermediate and final values of K_{22} at points defined by table of ϕ or s values.		5E14.7
D.	Initial, intermediate and final values of K_{33} at points defined by table of ϕ or s values.		5E14.7
E.	Initial, intermediate and final values of D_{ll} at points defined by table of ϕ or s values. (Should be input as negative for sign convention.)		5E14.7
F.	Initial, intermediate and final values of D ₁₂ at points defined by table of ϕ or s values. (Should be input as negative for sign convention.)		5E14.7
G.	Initial, intermediate and final values of D_{22} at points defined by table of ϕ or s values. (Should be input as <u>negative</u> for sign convention.)		5E14.7
Η.	Initial, intermediate and final values of D at points defined by table of ϕ or s values.		5 E1 4.7
I.	Initial, intermediate and final values of C_{11} at points defined by table of ϕ or s values.		5E14.7
J.	Initial, intermediate and final values of C_{22} at points defined by table of ϕ or s values.		5E14.7

Note: No plasticity is allowed for this option.

If the Reinforcing Clue is RWAF the following Hooke's Laws will be used by the program for the description of the shell wall:

$$\begin{split} & N_{\theta} &= K_{11} \varepsilon_{\theta_{0}} + K_{12} \varepsilon_{\phi_{0}} - C_{11} k_{\theta} - C_{15} k_{\phi} - N_{T\theta} \\ & N_{\phi} &= K_{22} \varepsilon_{\phi_{0}} + K_{12} \varepsilon_{\theta_{0}} - C_{15} k_{\theta} - C_{22} k_{\phi} - N_{T\phi} \\ & N_{\phi\theta} &= K_{33} \gamma_{\phi\theta_{0}} - 2C_{16} k_{\phi\theta} \end{split}$$

$M_{\theta} = D_{11} k_{\theta} + D_{12} k_{\phi} + C_{11} \epsilon_{\theta} + C_{15} \epsilon_{\phi} - M_{T\theta}$	<u>Column</u>	<u>Format</u>				
$M_{\phi} = D_{22} k_{\phi} + D_{12} k_{\theta} + C_{15} \epsilon_{\theta} + C_{22} \epsilon_{\phi} - M_{T\phi}$						
$M_{\phi\theta} = -2D_{33} k_{\phi\theta} + C_{16} \gamma_{\phi\theta}$						
Therefore the input is (see Ref. 4 Appendix A):						
A. through J. The items contained on these cards are those described for the ST10 clue above.	10 sets of	5E14.7				
K. Initial, intermediate and final values of C $_{\mbox{\scriptsize 15}}$ at points defined by table of ϕ or s values.		5E14.7				
L. Initial, intermediate and final values of $^{\rm C}$ at points defined by table of ϕ or s values.		5E14.7				
Note: No plasticity is allowed for this option.						
Table of Reinforcement Temperatures						
This card set is included only if the Reinforcement Clue (Item D page 2-39) is ST11, ST12, ST13, RWA1, RWA2, RWA3, ISG1, ISG2, or ISG3 and the Thermal Clue (Item E page 2-40) is THST or THON. The input is presented below as a function of the Reinforcement Clue.						
If the Reinforcement Clue is ST11, ST12, or ST13:						
A. Initial, intermediate and final values of the stringer temperature, at points defined by table of φ or s values.		5E14.7				
B. Initial, intermediate and final values of the ring (smeared) temperature, at points defined by table of φ or s values.		5 E 14.7				

If the Reinforcement Clue is RWA1, RWA2, RWA3, ISG1, ISG2, or ISG3:

7.

A. Initial, intermediate and final values of the reinforcement (waffle or isogrid) temperature, at points defined by table of φ or s values.

5E14.7

8. Table of Mass Densities (Dimensions = weight/volume/ acceleration due to gravity.)

	Column	Format
This card set is included only if the Shell Rotation Clue (Item K page 2-18) is set to unity, i.e. if the shell undergoes rotation. In such a case, the contents of these cards (up to 6 cards per item below) are dependent upon the clues registered on the Master Clue Card. If the shell to be described contains no reinforcing, the pertinent clue is item 4C, the sheet clue. The input is presented below as a function of the Sheet Clue.		
If the Sheet Clue is SING (single sheet construction):		
A. Initial, intermediate and final values of the wall mass density at points defined by table of ϕ or s values.		5E14.7
If the Sheet Clue is EQUA or UNEQ (sandwich construction):		
A. Initial, intermediate and final values of the core mass density at points defined by table of $\boldsymbol{\phi}$ or s values.		5E14.7
B. Initial, intermediate and final values of the face sheet mass density at points defined by table of $\boldsymbol{\phi}$ or s values.		5E14.7
If the shell is reinforced, the Sheet Clue will be BIAN. In this case it is the following, or Reinforcement Clue (item 4D) which will determine the contents of card series 8. The reinforced shell input is presented below as a function of the Reinforcement Clue.		
If the Reinforcement Clue is STll (single sheet reinforced by rings and/or stringers):		
A. Initial, intermediate and final values of the base shell mass density at points defined by table of ϕ or s values.		5E14.7
B. Initial, intermediate and final values of the stringer mass density at points defined by table of ϕ or s values.		5E14.7
C. Initial, intermediate and final values of the ring mass density at points defined by table of ϕ or s values.		5E14.7
If the Reinforcement Clue is ST12 or ST13 (sandwich reinforced by rings and/or stringers):		
A. Initial, intermediate and final values of the base shell core mass density at points defined by table of ϕ or s values.		5E14.7

	Column	Format
B. Initial, intermediate and final values of the base shell face sheet mass density at points defined by table of ϕ or s values.		5E14.7
C. and D. The items contained on these cards are those described for the ST11 clue as items B. and C.	2 sets of	5 E 14.7
If the Reinforcement Clue is RWAl or ISG1 (single sheet reinforced by a rotated waffle or isogrid):		
A. Initial, intermediate and final values of the base shell mass density at points defined by table of ϕ or s values.		5E14.7
B. Initial, intermediate and final values of the reinforcement mass density at points defined by table of $\boldsymbol{\Psi}$ or s values.		5 E 14.7
If the Reinforcement Clue is RWA2, RWA3, ISG2 or ISG3 (sandwich reinforced by a rotated waffle or isogrid):		
A. Initial, intermediate and final values of the base shell core mass density at points defined by table of ϕ or s values.		5E14.7
B. Initial, intermediate and final values of the base shell face sheet mass density at points defined by table of ϕ or s values.		5E14.7
C. Initial, intermediate and final values of the reinforcement mass density at points defined by table of ϕ or s values.		5 E1 4.7
If the Reinforcing Clue is ST10 or RWAF the program does not have any crossection description available to it for calculations. Thus no plasticity analysis is allowed, and the required input in card set 8 for these clues is (see Refs. 1, 4 and 5):		
A. The meridional distributed load on the crossection due to rotation at points defined by table of ϕ or s values. For example for a layered section this can be expressed as:		5E14.7
$f_{\varphi}^{1} = \sum_{i=1}^{n} \rho_{i} \omega_{r_{i}}^{2} t_{i} \cos \varphi$		*.

B. The normal distributed load on the crossection due to rotation at points defined by table of ϕ or s values. For example for a layered section this can be expressed as:

$$f^{l}_{\zeta} = \sum_{i=1}^{n} \rho_{i} \omega^{l}_{i} t_{i} \sin \varphi$$

C. The circumferential distributed moment load on the crossection due to rotation at points defined by table of φ or s values. For example for a layered section this can be expressed as: 5E14.7

$$m_{\theta} = -\sum_{i=1}^{n} \rho_{i} \omega^{2} r_{i} t_{i} \overline{y}_{i} \cos \varphi$$

Note: The sign convention for the above loads is as shown in Figures 2-11.

9. Loading Clue Card

The contents of this card are numerical clues which alert the program to the types of loads that exist on the segment. In addition, if the clue indicates that some load does <u>not</u> exist, the appropriate cards in series 10 which would ordinarily contain the numerical values of this load are omitted from the sequence. In the case of a rotating shell the inertia loads are calculated internally by the program.

The appropriate clues are as follows:

A. Thermal Clue

1

Il.

If there are no thermal loads (Item 4E is NOTH) the clue number is zero (0).

If there is a standard thermal variation through the thickness (Item 4E is THST) the clue number is four (4).

If the temperature is constant through the thickness (Item 4E is THCN) or if the in-homogeneous option is used (Item 4E is THIN) the clue number is one (1).

B. Circumferential Load Clue (f_0)

2

Il

If there are no circumferential loads, then the clue number is zero (0).

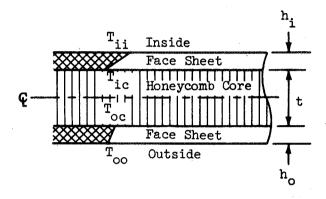
If there are circumferential loads, then the clue number is one (1).

			Column	Format
	c.	Meridional Load Clue (f_{ϕ})	3	Il
		If there are <u>no</u> meridional loads, then the clue number is zero (0).		
		If there are meridional loads, then the clue number is one (1).		
	D.	Normal Load Clue (f _c)	4	Il
•		If there are <u>no</u> normal loads, then the clue number is zero (0).		
		If there are normal loads, then the clue number is one (1).		
	E.	Circumferential Moment Load Clue $(m_{_{m{\Theta}}})$	5	Il
		If there are <u>no</u> circumferential moment loads, then the clue number is zero (0).		
		If there are circumferential moment loads, then the clue number is one (1).		
	F.	Meridional Moment Clue (m_{ϕ})	6	Il
		If there are <u>no</u> meridional moment loads, then the clue number is zero (0).		
		If there are meridional moment loads, then the clue number is one (1).		
	G.	Any alphameric information (load description)	7-70	16A4
10.		le of Applied Loads (see Figures 2-lla, b for n convention).		
func	tio	ropriate card sequence is given below as a n of the Loading Clues on card 9. If the Thermal one (1):		
	Α.	Initial, intermediate and final values of the temperature of the shell at points defined by table of ϕ or s values. (These values will be used either for a thermal problem where there is no thermal variation through the thickness {Clue = THCN}, or to calculate varying material properties along the shell for an inhomogeneous problem {Clue = THIN}.)		5E14.7

If the Thermal Clue is four (4):

A. Initial, intermediate and final values of the temperature $T_{i\,i}$ at points defined by table of ϕ or s values. (The subscripts "nm" indicate temperature location - see below.)

5E14.7



B. Initial, intermediate and final values of the temperature T at points defined by table of ϕ or s values.

5E14.7

C. Initial, intermediate and final values of the temperature T at points defined by table of \$\phi\$ or s values. 5E14.7

D. Initial, intermediate and final values of the temperature T at points defined by table of φ or s values. 5E14.7

If the Thermal Clue is zero (0), the above cards are omitted. All temperature values above refer to the base shell.

If the Circumferential Load Clue is one (1):

E. Initial, intermediate and final values of the circumferential loads f_{θ} at points defined by table of $_{0}$ or svalues.

5E14.7

If the Circumferential Load Clue is zero (0), cards E are omitted.

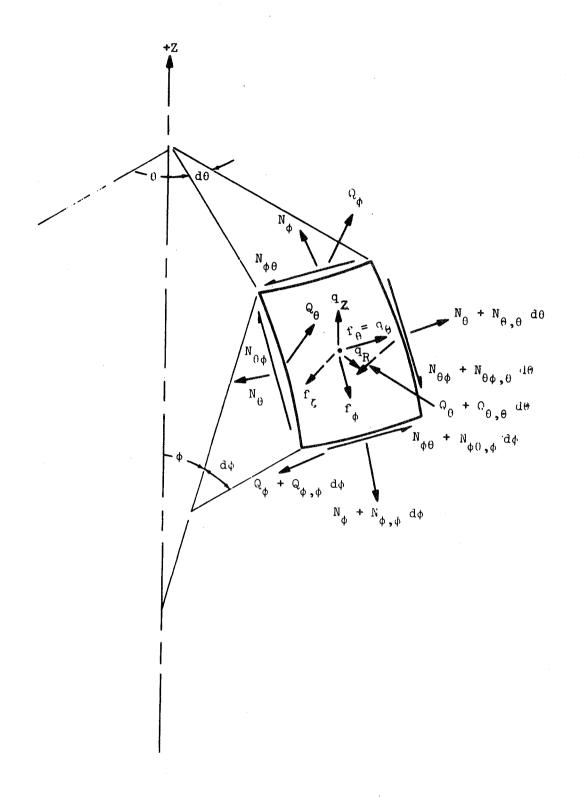


Figure 2-lla. Forces on Shell Element

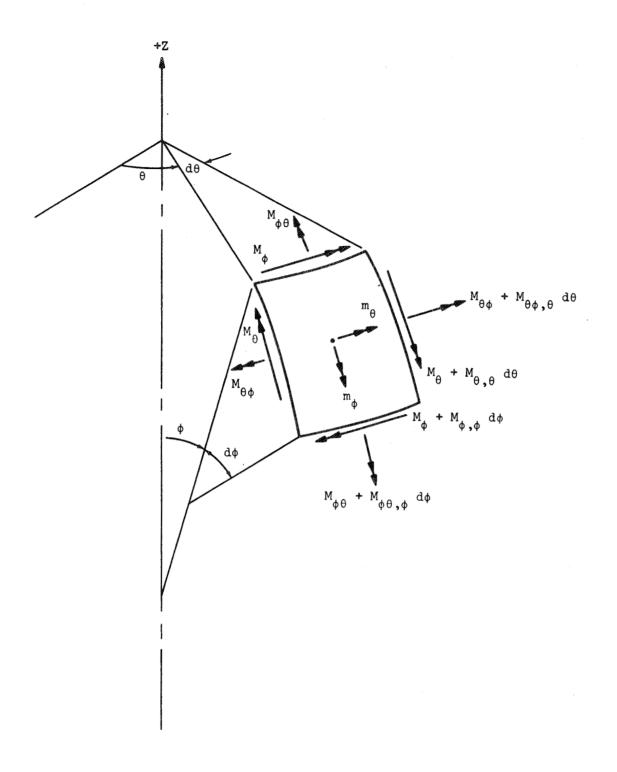


Figure 2-11b. Moments on Shell Element

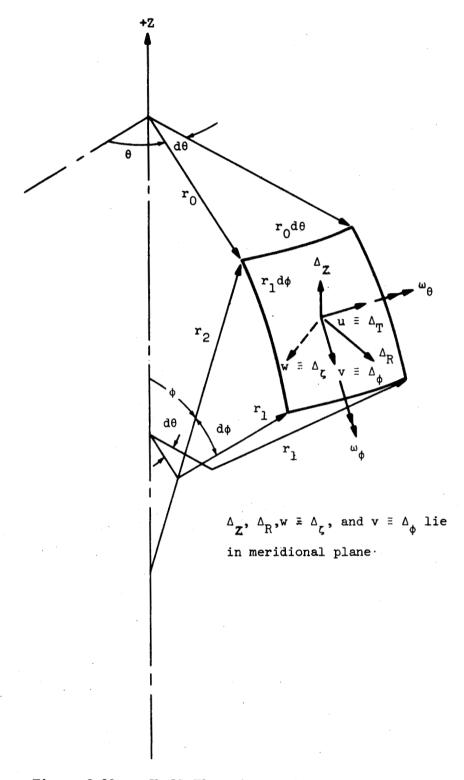


Figure 2-11c. Shell Element Geometry and Displacements

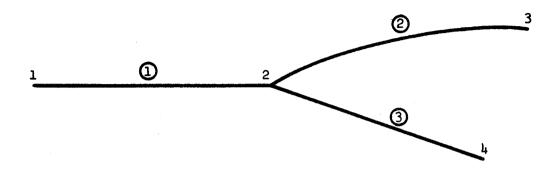
			Column	Format	
If	the	Meridional Load Clue is one (1):			
	F.	Initial, intermediate and final values of the meridional loads f $_{\varphi}$ at points defined by table of φ or s values.		5E14.7	
	the tted	Meridional Load Clue is zero (0), cards F are			
If	the	Normal Load Clue is one (1):			
	G•	Initial, intermediate and final values of the normal loads f at points defined by table of ϕ or s values.		5E14.7	
If	the	Normal Load Clue is zero (0), cards G are omitte	ed.		
If	the	Circumferential Moment Load Clue is one (1):			
	н.	Initial, intermediate and final values of the circumferential moment loads \textbf{m}_{θ} at points defined by table of ϕ or s values.		5E14.7	
		Circumferential Moment Load Clue is zero (0), are omitted.			
If	the	Meridional Moment Load Clue is one (1):			
	I.	Initial, intermediate and final values of the meridional moment load m at points		5E14.7	
		defined by table of φ or s values.			
If the Meridional Moment Load Clue is zero (0), cards I are omitted.					
11.	Seg	ment Topology Cards			
	Α.	Segment number	1-5	15	
		Number of the segment under consideration.			
	В.	· \-/	6-10	I 5	
		Joint associated with i th end of the segment (TIC).			
	C.	(0)	11- 15	I5	
		Joint associated with the j th end of the segment (STOP).			
		Since within a region the segments are all singly connected, the segment joint numbers should be in adjacent numerical pairs. That is, if joint (j) is 6, joint (i) could only be 5 or 7. This is true only within a region.			

		Column	Format
region mundering region mundering region muin the selection the selection reases. The user	ion, the initial joint of each ust be 1 in segment topology g, and the final joint of each ust be the last (highest) number egment topology numbering (see -12). The coordinate \$\phi\$ or s from TIC to STOP, i to j. is again advised to see 2-3 to 2-9.		
	S-E-P-A-R-A-T-O-R C-A-R-D	minus	in 1-80
(See Gene	eral Notes - Data Debugging)		
INTRA-REGION DISCF	RETE RING CARDS		
item 1C), are placed data for the region	ny exist (region introductory card, ced at the end of all the segment on. They contain the following ach ring (in groups of 5 cards):		
1. Ring Property	Card		
attached disconti a kinema ring is	joint number to which the ring is d. If there is also a radial inuity at this location necessitating atic link, the joint number of the the independent joint number of the see Figure 2-13a).	1- 2	I2
B. Ring ex	tensional stiffness (EA)	3-16	E14.7
C. Ring be axis (E	nding stiffness about centroidal y I_y). See Figure 2-14.	17-30	E14.7
D. Ring creaxes (E.	oss-bending stiffness about centroidal xy).	31-44	E14.7
E. Ring be x axis	ending stiffness about centroidal $(EI_{\mathbf{x}})$.	59 - 72	E14.7
F. Ring Yo	ung's Modulus	45-58	E14.7
2. Ring Plastici	ty Card		
A. Ring Ge	eometry Description Clue	1-4	A ¹ 4

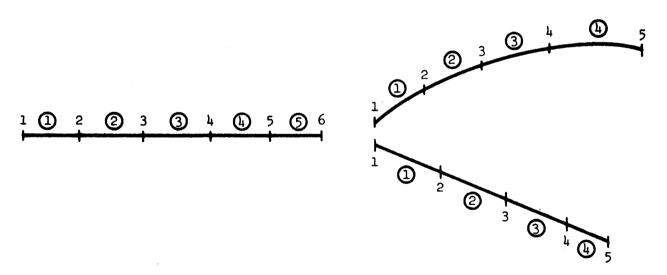
the associated shapes are presented in

A specific clue word is necessary to describe the ring shape. The possible clue words and

Figure 2-15.

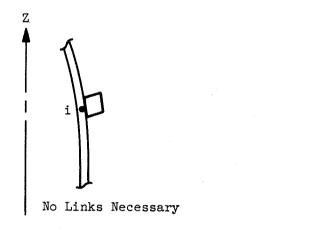


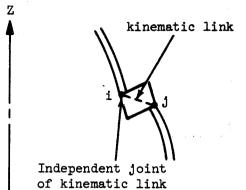
Region Numbering



Numbering of Segments Within Regions

Figure 2-12. Topology Schemes

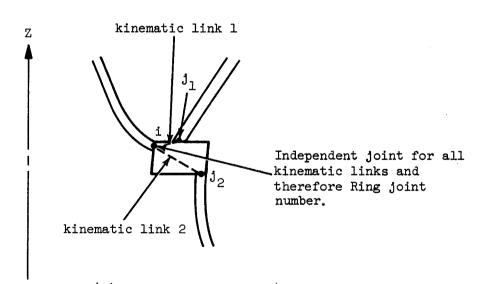




and therefore Ring joint number.

Kinematic Link Necessary

(a) Segment or Simple Region Rings



(b) Possible Region Multi-connected Rings

Figure 2-13. Discrete Ring Topology

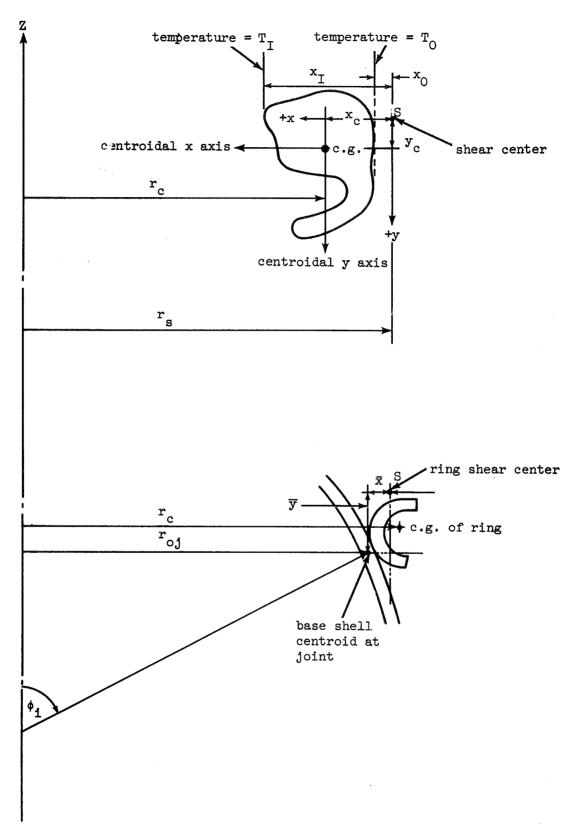


Figure 2-14. Discrete Ring Geometry

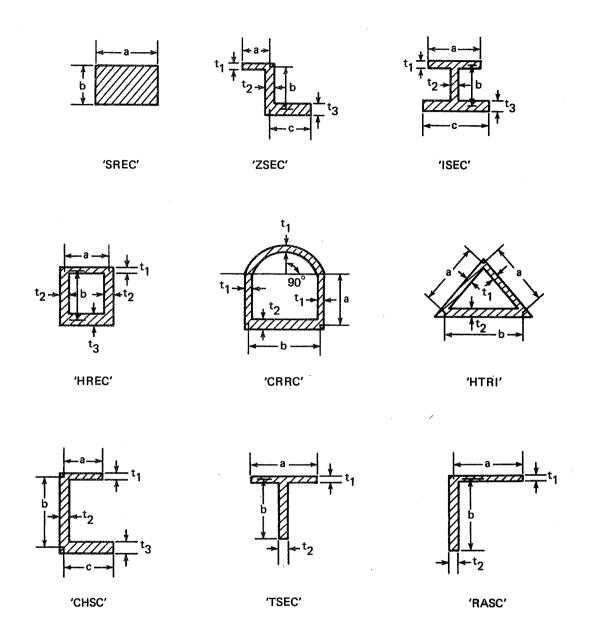


Figure 2-15. DISCRETE RING CONFIGURATIONS

			Q - 7	771 s. d.
			Column	Format
	B.	Ring Orientation Angle	7-20	E14.7
		Angle (in radians) at which ring is oriented. Normally this entry is the same as the "phi input" for a curved shell; or is equal to the angle input for a cone (see Figure 2-8, but $_{\phi}$ range here is between 0 and 3π radians [no negative angles in inverted cone]); or is equal to $\pi/2$ for a cylinder.		
		Notes: 1. In order to "invert" the ring, i.e., turn it upside down from the position shown in Figure 2-15, as it rotates clockwise, and attach it to the inside part of the shell, add π to the angle above.		
		2. If the ring is oriented at another angle rather than tangent to the shell wall, the angle should be entered accordingly above.		
	C.	Ring Yield Stress	21-34	E14.7
	D.	Ramberg - Osgood constant "s" for the discrete ring (see Ref. 1).	35-48	E14.7
	E.	Ramberg - Osgood constant "n" for the discrete ring (see Ref. 1).	49-62	E14.7
3.	Ring	Location Card (see Figure 2-14)		
	Α.	Ring thermal coefficient of expansion $(\alpha_{\widehat{R}})$.	1-12	E12.5
	В.	Ring centroidal radius (r_c) .	13-24	E12.5
	C.	Distance (\pm) between ring centroid and shear center in the x direction (x_c).	25-36	E12.5
	D,	Distance (\pm) between ring centroid and shear center in the y direction (y_c).	37-48	E12.5
	E.	Offset (±) of ring shear center from attached shell joint (see item 1A) in the x direction (\bar{x}) .	49-60	E 12.5
	F.	Offset (±) of ring shear center from attached shell joint (see item 1A) in the y direction (\overline{y}) . Note: The shear center (S) is the origin of the x, y axes shown in Figure 2-14.	61-72	E12.5
١.	TD 4	mbows 1 Deposite to a Court (Co. Titure Co. 1)		

4. Ring Thermal Description Card (See Figure 2-14)

		Column	Format
A.	Innermost point temperature $(T_{\underline{I}})$	1-14	E14.7
в.	Outermost point temperature (T_{O})	15-28	E14.7
C.	Radius of revolution at the segment joint which is used to identify the ring (Item 1A).	29-42	E14.7
D.	Ring mass density (ρ)	43-56	E14.7
E.	Hardening Law Clue	61-64	A4
	Different hardening laws can be used for each ring (as well as each segment). If isotropic hardening is to be used the clue is <u>ISOT</u> . If kinematic hardening is to be used the clue is <u>KINE</u> . If perfect plasticity is to be used the clue is <u>PERF</u> . For this <u>last</u> clue word items 2D, E(above) are set to <u>zero</u> .		
Rin	g Geometry Card (see Figure 2-15)		
ite	ring geometry is specified on this card (as many ms as necessary) as a function of the Ring Geometry cription Clue (item 2A).		
If	the clue word is ZSEC, ISEC, or CHSC:		
A.	Length dimension, a	1-12	E12.5
B.	Length dimension, b	13-24	E12.5
C.	Length dimension, c	25 - 36	E12.5
D.	Thickness dimension, t ₁	37-48	E12.5
E.	Thickness dimension, t ₂	49-60	E12.5
F.	Thickness dimension, t ₃	61-72	E12.5
If	the clue word is HTRI, CRRC, TSEC, or RASC:		
Α.,	B. These items are the same as those identified	1-24	2E12.5

5.

C., D.

above for the ZSEC clue.

the ZSEC clue as items D and E.

These items are those identified above for

2E12.5

25-48

		Column	Format
If	the clue word is HREC:		
A-D	. These items are the same as those identified above for the HTRI clue	1-48	4E12.5
E.	Thickness dimension, t ₃	49-60	E12.5
If	the clue word is SREC:		
, A .	Length dimension, b	1-12	E12.5
В.	Length dimension, a	13-24	E12.5
	D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (See General Notes - Data Debugging)	minum in	1 - 80
INTRA-REG	ION KINEMATIC LINK CARDS		
item 1B),	ds, if any exist (region introductory card, are placed at the end of all the discrete for the region. They contain the following on:		
Α.	Joint (j) dependent joint	1-2	I2
В.	Joint (i) independent joint	3-4	12
	For intra-region kinematic links these joints must be in consecutive decending order. That is, joint (j) should always be greater than joint (i) by one.		
C.	Angle γ in radians (see Figure 2-16)	5 -1 9	E14.7
	γ cannot equal 0 or π .		
	The angle γ describes the orientation of the link; it is the inclination angle of the link from the vertical (Z axis).		
	The number of kinematic link cards must equal the number specified in item 1B, of the region introductory card.	s e	
	D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (See General Notes - Data Debugging)	minus in	1-80

REGION JOINT CONTROL DATA

These cards are placed at the end of all the data for all regions.

1. Joint Control Data Card

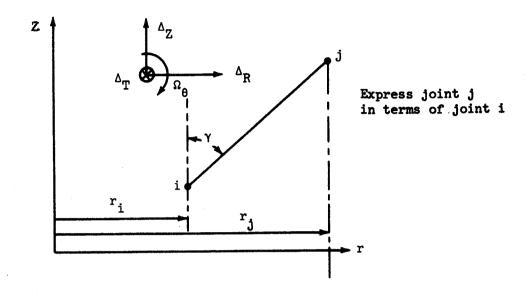


Figure 2-16. Kinematic Link

			Column	Format
	A.	Number of region joints	1-5	I 5
		Total number of region joints (Max. = 20).		
	В.	Number of discrete rings	6-10	I 5
		Total number of discrete rings <u>between</u> regions.		
	C.	Number of kinematic links	11-15	I 5
		Total number of kinematic links <u>between</u> regions.	3	
2.	Dis	screte Ring Cards (inter-region, if any exist)		•
	Α.	Ring Property Card		
		a. Region joint number to which the ring is attached. If there are also radial discontinuities at this location neces- sitating kinematic links, or multi- connections, the joint number of the ring	1-2	IS
		is the <u>independent</u> joint number of all the links (see Figure 2-13b).		•
		b. Ring extensional stiffness (EA)	3 - 16	E14.7
		c. Ring bending stiffness about centroidal y axis (EI _y). See Figure 2-14.	17-30	E14.7
		d. Ring cross-bending stiffness about centroidal axes (EI_{xy}).	31-44	E14.7
		e. Ring bending stiffness about centroidal x axis (EI_x) .	45 - 58	E14.7
		f. Ring Young's Modulus	59 - 72	E14.7
	В.	Ring Plasticity Card		
		a. Ring Geometry Description Clue	1-4	A ¹ 4
		A specific clue word is necessary to describe the ring shape. The possible clue words and the associated shapes are presented in Figure 2-15.		

			Column	Format
	b.	Ring Orientation Angle	7-20	E14.7
		Angle (in radians) at which ring is oriented. Normally this entry is the same as the "phi input" for a curved shell; or is equal to the angle input for a cone (see Figure 2-8, but φ range here is between 0 and 3π radians [no negative angles in inverted cone]); or is equal to $\pi/2$ for a cylinder.		
.3		Notes: 1. In order to "invert" the ring, i.e., turn it upside down from the position shown in Figure 2-15, as it rotates clockwise, and attach it to the inside part of the shell, add π to the angle above.		
		2. If the ring is oriented at another angle rather than tangent to the shell wall, the angle should be entered accordingly above.		
	c.	Ring Yield Stress	21-34	E14.7
	d.	Ramberg - Osgood constant "s" for the discrete ring (see Ref. 1).	35-48	E14.7
	е.	Ramberg - Osgood constant "n" for the discrete ring (see Ref. 1).	49 - 62	E14.7
C.	Rin	g Location Card (see Figure 2-14)		
	a.	Ring thermal coefficient of expansion (α_R) .	1-12	E12.5
	ъ.	Ring centroidal radius (r _c).	13-24	E12.5
	C.	Distance (\pm) between ring centroid and shear center in the x direction (x_c).	25 - 36	E12.5
	đ.	Distance (\pm) between ring centroid and shear center in the y direction (y_c).	37-48	E12.5
	е.	Offset (\pm) of ring shear center from attached shell joint (see item Aa) in the x direction (\overline{x}).	49-60	E12.5
	f.	Offset (\pm) of ring shear center from shell joint (see item Aa) in the y direction (\overline{y}).	61-72	E12.5
		Note: The shear center (S) is the origin of the x,y axes shown in Figure 2-14.		

			Column	Format
D.	Rin			
	a.	Innermost point temperature (T_T) .	1-14	E14.7
	b.	Outermost point temperature (T_0) .	15-28	E14.7
	c.	Radius of revolution at the region joint which is used to identify the ring (Item Aa).	24-42	E14.7
	đ,	Ring mass density (ρ) .	43-56	E14.7
	e.	Hardening Law Clue	61-64	A4
E.	The (as of Aa)	Different hardening laws can be used for each ring (as well as each segment). If isotropic hardening is to be used the clue is <u>ISOT</u> . If kinematic hardening is to be used the clue is <u>KINE</u> . If perfect plasticity is to be used the clue is <u>PERF</u> . For this <u>last</u> clue word items Bd, e(above) are set to <u>region</u> geometry Card (see Figure 2-15) ring geometry is specified on this card many items as necessary) as a function the Ring Geometry Description Clue (item the clue word is ZSEC, ISEC, or CHSC:	ero.	
	a.	Length dimension, a	1-12	E12.5
		,		-
	b.	Length dimension, b	13-24	E12.5
	c.	Length dimension, c	25-36	E12.5

Thickness dimension, t₁

Thickness dimension, to

Thickness dimension, t_{2}

If the clue word is HTRI, CRRC, TSEC, or RASC:

These items are the same as those identified above for the ZSEC clue.

37-48

49-60

61-72

1-24

E12.5

E12.5

E12.5

2E12.5

2E12.5

						Column	Format
		If the clue wor	d is HREC:				
			ms are the the HTRI o		hose identified	1-48	4E12.5
		c. Thickness d	imension,	3		49-60	E12.5
		If the clue wor	d is SREC:				
		a. Length dime	nsion, b			1-12	E12.5
		b. Length dime	nsion, a			13-24	E12.5
		D-A-S-H S- (See Genera				minus in	1-80
3.	Kir	ematic Link Cards	s (inter-re	gion, if s	ny exist)		
	A.	Joint (j) depend	dent joint			1-2	12
	В.	Joint (i) indepe	endent join	t		3-4	12
		For kinematic 1: are no restrict:		STATE OF THE PARTY			
		The only restrict kinematic link of should be in inconsecutive). I	lata cards reasing or	the (j) jo der (not n	int entry		
			j	i	7		
		Must be	(3	2	_		
		in	1 4	2 2 1 6	-		
		increasing	1 0	ī	_		
		order.	3 4 9 12	6	0. 77		
	c.	Angle γ in radio	ans (see Fi	gure 2-16)	9	5-19	E14.7
		7 cannot equal (or π.				
		The angle y desc	ribes the	orientatio	n of the		
		link; it is the					
		link from the ve					

link from the vertical (Z axis). The number of kinematic link cards must equal the number specified in item 1C of the joint Control Data Card.

			Column	Format
		A-S-H S-E-P-A-R-A-T-O-R C-A-R-D See General Notes - Data Debugging)	minus	in 1-80
		ary Condition Cards (Joint Data - one card egion joint)		
	A. Jo	oint Number	1-2	12
į.	B. Jo	oint component conditions on:		
	1)	Δ_{T}	3-4	F2.0
	2)	Δ _Z or Δ _N (see Figure 2-17)	5-6	F2.0
	3)	AR or Ag	7-8	F2.0
	4)	Ω _θ	9-10	F2.0
	C. An	gle α in radians	11-24	E14.1

To be used only in conjunction with a 2 or 3 code.

Note: There must be as many boundary condition cards as there are joints as indicated in item 1A of the Joint Control Data Card.

There are 4 different codes that are used to prescribe joint component conditions. They are:

- a. 0 = no displacement allowed.
- b. l = displacement allowed in the indicated direction.
- c. 2 = Δ and Δ are rotated through an angle of (*/2 α) and become Δ and Δ respectively, while a displacement is allowed in the Δ direction.

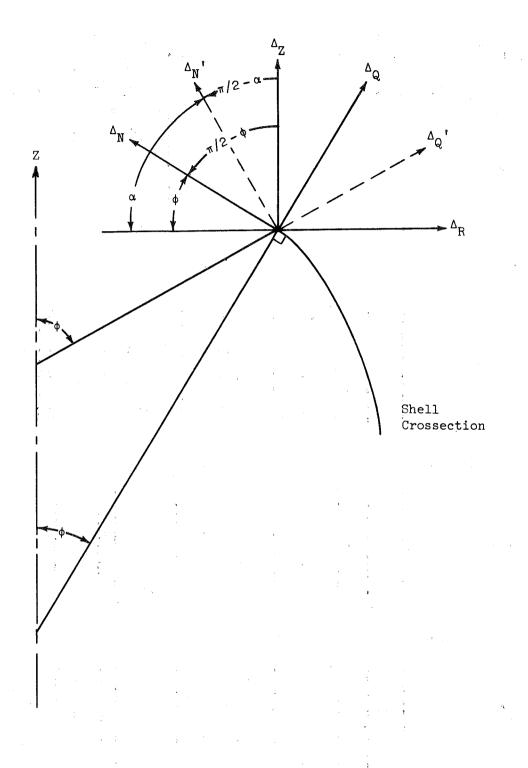


Figure 2-17a. Description of General Coordinate Rotation ($\alpha \neq \phi$)

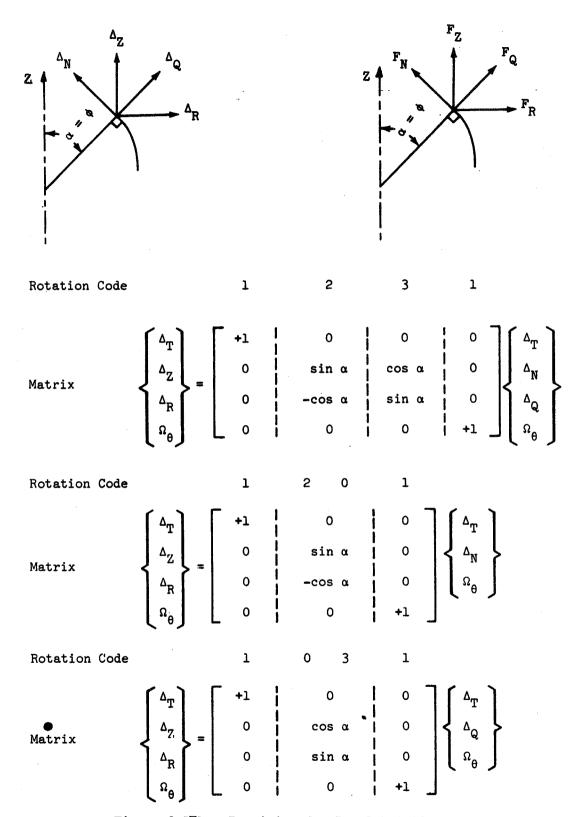


Figure 2-17b. Provision for Local Rotations

d. $3 = \Delta_Z$ and Δ_R are rotated through an angle of $(\pi/2 - \alpha)$ and become Δ_R and Δ_Q respectively, while a displacement is allowed in the Δ_Q direction.

See Figure 2-17 for a geometric explanation of codes 2 and 3.

When using rotation codes:

Code 3 can exist only as $\Delta_{\!\stackrel{}{R}}$ coding.

Codes 0 and 1 can appear in either column 4 or column 6, in addition to columns 8 and 10. Thus, there are twelve possible boundary conditions when rotation codes are used. ($\alpha = \phi$ for table below.)

	Free edge (possible to apply shear and/ or membrane loads)	Δ _Q = 0, normal support (possible to apply membrane load)	$\Delta_{ m N}=0$, membrane support (possible to apply shear load)
Δ_{T} , $\Omega_{\mathrm{\theta}}$ free	1,2,3,1	1,2,0,1	1,0,3,1
Δ_{T} , $\Omega_{\mathrm{\theta}}$ fixed	0,2,3,0	0,2,0,0	0,0,3,0
$\Delta_{f T}^{}$ fixed $\Omega_{f heta}^{}$ free	0,2,3,1	0,2,0,1	0,0,3,1
$\Delta_{\!$	1,2,3,0	1,2,0,0	1,0,3,0

Apex boundary conditions:

Since the closed apex (ϕ = 0) angle is not acceptable input, the apex boundary conditions must be simulated at a small ϕ angle. These boundary conditions vary per Fourier harmonic, and are as follows:

n	$\Delta_{ m T}$	$\Delta_{\!\mathbf{Z}}$	$\Delta_{ m R}$		angle
0.0	0	0	3	0	α = φ
1.0	1	2	0	1	α = φ
>2.0	0	0	Ò	0	

General Notes:

- 1) To establish a datum for measuring displacement, free body motion must be eliminated from the structure. This should be accomplished by suitably applied boundary conditions.
- 2) The ability of a dependent joint in a kinematic link to prescribe motion independently should be removed by setting all boundary conditions of that joint to zero. See pages 2-65 and 2-84

D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (See General Notes - Data Debugging)

minus in 1-80

JOINT LOAD DATA

- 1. Load Control Data Card
 - A. Number of Joint Loads

1-4

I4

Total number of joint loads in analysis. (Line loads can only be applied to region joints.)

B. Any alphameric information (load description)

5-68

16A4

Note: If there are no Joint Loads for the structure, card 1 of the JOINT LOAD DATA is blank and card set 2 is omitted.

			Column	Format
2.	Joi	nt Load Cards (as many as in item LA above)		
	A.	Enter unity in column 5	1 - 5	15
	В.	Row Identification	6-10	I 5
		The identification is the location of the degree of freedom at which the load is applied. This is obtained by counting the non-zero codes entered in the Boundary Conditions Cards, starting with Joint 1; T, Z, R, Ω_{θ} , Joint 2; T, Z,etc., and stopping at the joint and degree of freedom where the line load is to be applied. The location number of this degree of freedom is the information necessary.		
	C.	Applied Joint Load	11-24	E14.7
		The input is 2mr times the running load in lb./in. In the particular case of the axial axisymmetric load, this is simply the net force. For sign convention see Figures 2-11, 2-17 and 2-18.		
		D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (See General Notes - Data Debugging)	minu	s in 1-80

LOAD CYCLING CARDS

If only a single loading is being investigated these cards are omitted. For changes of load distribution, magnitude, or material property tables with time, the appropriate cards below are included. (See also item 2H in the General Introductory Cards p 2-18). These cards are repeated to amount described in Item 2E on p 2-16

- 1. Load Cycling Program Control Card
 - A. Intermediate print clue

8-9

I2

(See item 2D General Introductory Cards p 2-16).

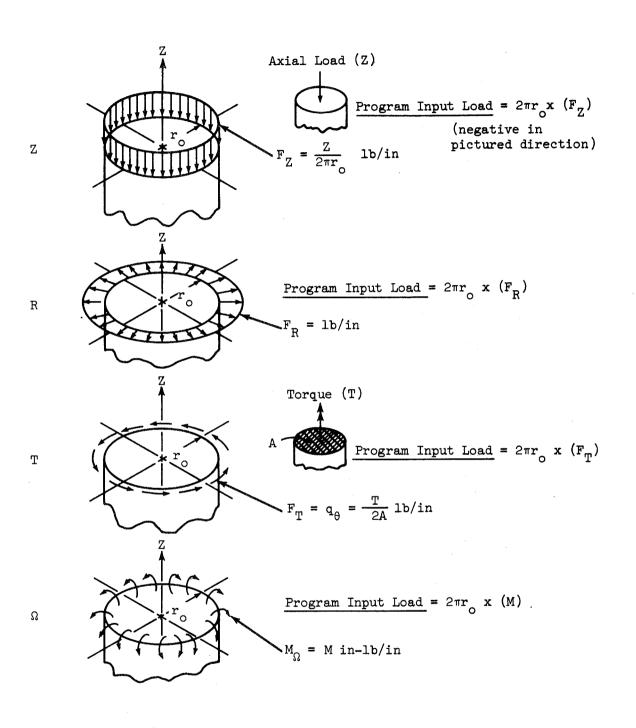


Figure 2-18 Line Loading for Harmonic n = 0.0 2-77

		Column	Format
В.	Number of load steps	12-17	F6.0
	Number of loading increments to be made for the next loading cycle. If the loading reverses in direction, this number is input as being of opposite sign to the same entry for the previous loading cycle.		
C.	Load step print increment for next loading cycle. (See Item 2G General Introductory Cards p 2-18 .)	18-21	F4.0
D.	Load amplitude change clue	24-25	I2

If the previous loading cycle load amplitudes are to be reused, and the only changes involved are load directions or step sizes (controlled by item C above) or material property tables, the clue is zero. If the load amplitudes are also changed, the clue is five, and new load cards will be expected to be read. It should be noted that load amplitudes are sequential. For further clarification see Figures below.

Load Cycle	No. Load Steps	Amplitude	Load Cycle	No. Load Steps	Amplitude
1	Ex: 10	a _l	1	Ex: 5	a <u>1</u>
2	-20	change to a ₂	2	5	change to a ₂
3	30	no change	3	- 5	no change
Applied Load	a ₁	3/a ₂ = a ₃		a a a a a a a a a a a a a a a a a a a	time

	Column	Format
E. Material Table Change Clue	26-27	12
If the previous loading cycle material property tables are to be reused the clue is <u>zero</u> . If new material property tables are supplied the clue is one.		
Note: At the first load reversal in direction the material property tables must be re-read with all the Ramberg - Osgood "s" constants being doubled in value. This is done only at the first load reversal, and the new tables can be reused thereafter. If the constants above are all zero this can be disregarded. This is true for all reinforcement as well as the shell.		
F. Angluar velocity in rad./sec. for next loading cycle.	59 - 72	E14.7
Since the shell rotation clue (item 2K in the General Introductory Cards p 2-18) is constant for the total run, the above item is significant only if that clue was initially set to one. In order to apply or delete an angular velocity in the middle of a loading history, the velocity values for other load cycles may be set to zero.		
Material Property Tables for Next Loading Cycle		
If the preceding Material Table change clue was set to one a complete new set of material property tables must be provided. Note the special item above for the Ramberg - Osgood "s" parameter. The names of the material tables may not be changed. The necessary formats and card sequences are provided on p 2-21		
D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D	minus in	1-80

2.

(see General Notes - Data Dubugging)

		Column	Format
	ceeding Material Table Change Clue was set to zero, we and the separator card are omitted.		
3. Shel	l loading data for next loading cycle		
	he preceeding Load Amplitude Change Clue was set ive, the following card sequence must follow.		
Α.	Segment Loading Clue Card for next loading cycle		
	a. Load clues for temperature, circumferential, meridional, normal, circumferential moment, and meridional moment load, for next loading. cycle.	1-6	611
	Note: Variations in types of loadings as well as magnitudes are allowed per cycle. The thermal clue, however, is fixed and must remain constant. Thus $\Delta T = 0$ may have to be input as appropriate.		
В.	Table of Applied Loads for next load cycle (see segment card set 10). These cards contain the next set of loads as described previously in the segment data according to the Load Clues above.		5E14.7
	Note: The above data sets (3A and 3B) are repeated until all the segments in the first region are completed for the next load cycle.		
C.	Region Ring Load Cards for next loading cycle.		
	a. Ring Yield Stress	1-14	E14.7
	b. Ring Ramberg - Osgood "s" value (see note about doubling this value for <u>first</u> load reversal, above.)	15 - 28	E14.7
	c. Ring Ramberg - Osgood "n" value.	29-42	E14.7
	d. Innermost point temperature (T_I) .	43 - 56	E14.7
	e. Outermost point temperature (T_0) .	56-70	E14.7
	Note: The above data set (3C) is repeated until all the rings in region one are completed for the next load cycle.		
	The above data sets (3A through 3C) are then repeated until all the segments and rings in all the regions are completed for the next load cycle.		

		Column	Format
	The above data set (3C) is then repeated until all the structure rings are completed for the next load cycle.		
D.	Joint Load Control Data Card for next loading cycle.		
	a. Number of Joint Loads	1-4	1 4
	b. Any alphameric information	5 - 68	16A4
	Note: If no joint load changes exist in this load cycle, the above card is blank and card set 3E (below) is omitted.		
E.	Joint Load Cards for next loading cycle		
	a. Enter unity is column 5	1-5	I 5
	b. Row identification (see previous Joint Load Card description)	6-10	I 5
	Note: Locations of line loads may change from load cycle to cycle.		
	c. Applied Joint Load	11-24	E14.7
	The input is $2\pi r_0$ times the running load in lb./in. for this load cycle (see Figure 2-18).		
	D-A-S-H S-E-P-A-R-A-T-O-R C-A-R-D (see General Notes - Data Debugging)	minus in l	- 80
	If the preceeding Load Amplitude change clue was set t	o <u>zero</u> ,	

If the preceeding Load Amplitude change clue was set to zero, item 3 above and the separator card are omitted.

The above cycling cards (items 1-3) are repeated until all the load cycles input in item 2E on p 2-16 are completed.

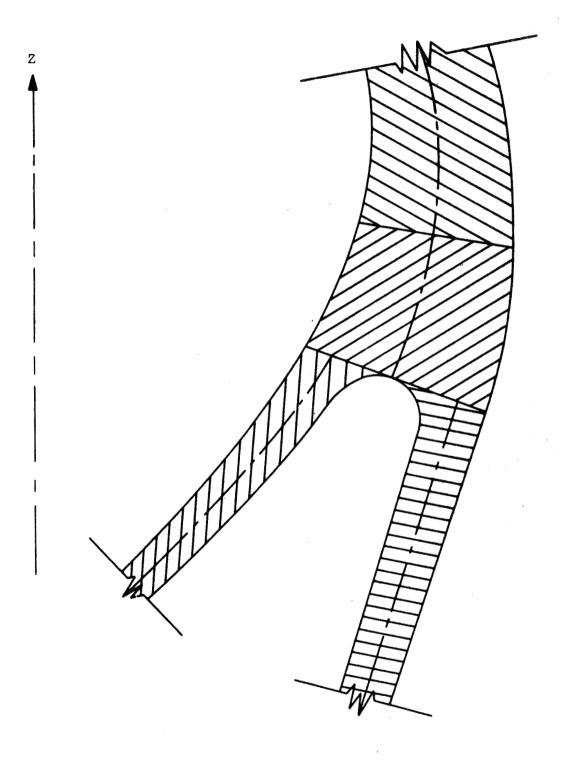


Figure 2-19. Y-Joint (Distorted Geometry)

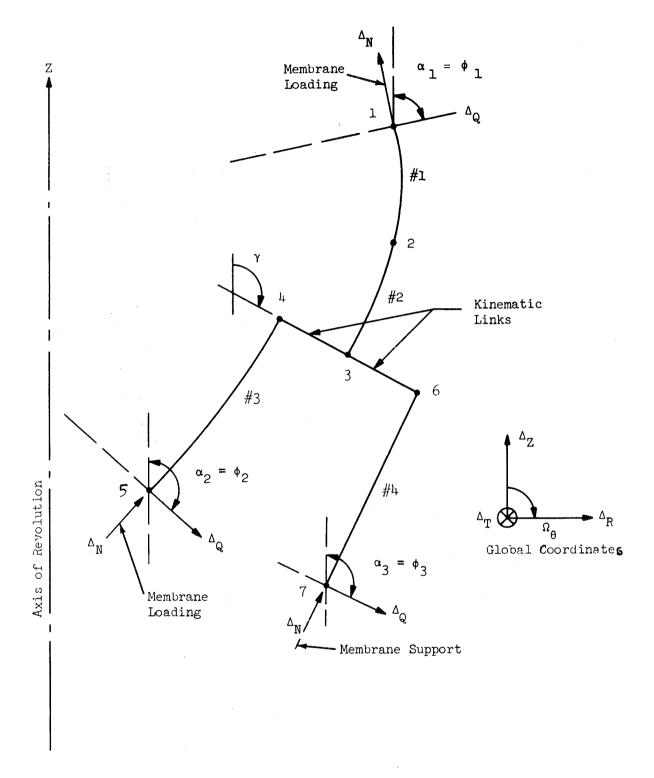


Figure 2-20. Idealized Y-Joint

It is hoped that the user is now able to use the STARS-2P program to good advantage. It is a powerful tool which will increase in value to the user as he uses it. One of the more complex areas of usage is the description of topology, especially when involved with rotation codes and joint loads. An illustrative example of a Y joint representation is therefore presented below. (See Figures 2-19 and 2-20 for the structure and idealization.) The idealized structure contains four regions and two kinematic links. The joints are numbered from 1 to 7. Membrane loading is applied to joints 1 and 5 and the structure is supported by membrane action at joint 7. All regions must be coupled.

The second card in each region description (topology card) is as follows:

Region	Joint (i)	Joint (j)
ı	1	2
2	. 2	3
3	4	5
4	6	7

The Joint Control Data card would contain a 7 in column 5 and a 2 in column 15.

In this example, the restraints at joints 1, 5 and 7 must be rotated from the fixed (global system) to a local system such that membrane action may be applied. In addition, joints 3 and 4, and 6 and 3 are to be coupled with kinematic links. Thus, the motions of joints 4 and 6 are dependent upon the motion of joint 3. This dependence will be insured by using 2 kinematic link cards and setting the independent degrees of freedom of joints 4 and 6 equal to zero. It should be noted in this particular case that the motion of joints 4 and 6 is not being equated to zero, but rather, the ability to prescribe motion independently is being removed. The required data has the following appearance.

A. Kinematic Link Cards (2 cards)

Joint (j)	<u>Joint (i)</u>	<u>Angle</u>	Note: In a double link of the type
4	3	$\gamma + \pi$	shown in Figure 2-20, one joint
6	3	γ	must be consistently independent (joint 3 in example).

B. Bountary Condition Cards for a coupled torsional case (7 cards)

<u>Joint</u>	T	<u>z</u>	<u>R</u>	<u>θ</u>	Angle
1	1	2	3,	1	α_1
2	`1	1	1	l	
3	1	1	1	l.	
4	0	0	0 ,	0	
5	1	2	3	1	α_2
6	0	0	0	.O	<u>.</u>
7	0	0	3 '	l	α_3

The Load Control Data card would contain a 2 in column 4.

The external membrane loads are applied to the structure through the Joint Load Cards which, in this example, would appear as (2 cards):

Problem No.	Row	Load
1	2	2πr _O x Membrane Load (lb./in.)
1	14	2πr _o x Membrane Load (lb./in.)

SECTION 3

OUTPUT INFORMATION

The output of the STARS-2P program is straightforward, however a description is in order since the user should learn the significance of the various checks that are provided. It is important to point out that the output of the program will include a print-out of the input data. This gives the user the opportunity to check whether or not the input data was correct. In the detailed description of the complete output which follows, the user should refer to the output of the problem in Section 4 as an example.

The title page of the output contains all the data from the General Introductory Cards, prominently placed, and needs no comment. The next page of the output contains the first region Identification Card in the center. The following output is then presented for each segment in this region (in order of appearance):

- 1. Contents of segment Identification Card.
- 2. Contents of MAGIC Control Card
- 3. Contents of Geometric Description Card (Cards)
- 4. Contents of Master Clue Card
- 5. The material property table used for the segment
- 6. Crossection description table
- 7. Temperature load table (if any)
- 8. Distributed load tables
- 9. Segment influence coefficients (MAGIC output)
- 10. Segment stiffness matrix
- 11. Stiffness matrix symmetry check
- 12. Segment load matrices
- 13. Radius of revolution at ith and jth ends of segment

Item 11, the stiffness matrix symmetry check, is a check upon the validity of segment sizing and the accumulation of round-off error. For perfect symmetry to exist, it is necessary to have zeros above the main diagonal, and zeros or ones below the diagonal. The amount of error induced by improper sizing or round-off is related to the amount that the off-diagonal terms in the lower triangle differ from unity. An attempt should be made to keep the upper limit on this difference at one percent (maximum number in lower triangle should be 0.1010... E 01).

As mentioned previously, items 1-13 are repeated for all the segments within region one. The radius of revolution at every joint should be checked at corresponding joints of adjacent segments to make sure that proper coupling has been specified. At this stage in the output, the topology of the segments within the region, and the description of the intra-region rings and kinematic links is presented.

Next the region matrices are presented. Given in order are: region stiffness matrix, the stiffness matrix symmetry check, and the region load matrices. Again the numerical round-off, evident in the symmetry check, should be kept to a maximum of one percent (0.1010... E 01 in lower triangle). The output to this point, that is, sets of items 1-13, segment topology and links, and the region matrices, are now repeated as a group for each region within the structure. When this is completed, the region topology is presented. The next items to be provided by the output are the descriptions of the inter-region rings and kinematic links and the boundary conditions. At external points of the structure these are physical boundary conditions. At internal points they merely state the fact that no restraint exists and the joint in question is free to move. The last column in this set, gives the angle α , which is zero unless a rotation code is indicated. It is important to refer to Figure 2-17 once more and point out that α represents a rotation of the coordinate system.

There are a variety of errors that can be made in submitting input data. The STARS-2P program is set so that as an error is detected, (input or in the matrix calculations) the program is stopped. Therefore, to avoid delays in getting an answer, the SATELLITE-1P program was created to debug input data, and to check for other possbile inconsistencies. The use of this program is described in Reference 3, and all the STARS error messages are contained in the listings therein.

After having corrected any errors, so that it is now possible for the program to run to completion, the problem solution can be discussed. From the above point in the output, further output will depend upon the intermediate print clue. If this clue is set for full output, all stiffness matrices will be printed for all segments, regions, and structures in all print cycles specified. If the print clue is set for abbreviated print, only that noted below will be printed:

- 1. The applied line loads.
- 2. The region end deflections starting from region joint 1.
- 3. Tabulation of final print (per print interval) as shown in Table 3-1.

 Below this tabulation will appear the numerical results. In addition, if the crossection has gone plastic the following results will be available:
 - a. NPIA: if this indicator is zero the layer is elastic.
 if this indicator is + the layer is plastic.
 if this indicator is the layer is elastic
 but has previously been plastic.
 - b. Total stresses through the crossection.
 - c. Plastic strains through the crossection.

In item 3 above the following special cases may arise:

- 1. The 1,2 element will be zero for cylinders or cones.
- 2. No stresses will be calculated for the ST10 or RWAF options.
- 4. A restarted run will provide the initial print and start item 3 at the next print interval.

This completes the program output. The user is reminded to check continuity of stress resultants across segment boundaries where applicable.

	TABLE 3-1.	Tabulated Final Output Information
1,1	PHI (RAD. OR IN.)	$_{\mathfrak{O}}$ or s at which calculations are made
2,1	EPSILON THETA	ϵ_{o} , circumferential strain
3,1	Ū	circumferential displacement
4,1	V	meridional displacement
5,1	W	normal displacement
6,1	OMEGA THETA	$w_{\theta}^{}$, circumferential rotational displacement (rad)
1,2	DEGREES	φ, expressed in degrees
2,2	EPSILON PHI	en, meridional strain
3,2	K PHI THETA	$_{\omega \theta }^{\Psi }$, specific twist
4,2	J PHI STAR	J^{φ} , non-linear effective transverse shear
		stress resultant
5,2	T PHI THETA	${f T}_{{\mathfrak m}{f heta}},$ effective in-plane shear stress
		resultant
6,2	OMEGA PHI	$_{\Omega}^{\omega}$, meridional rotational displacement
		(rad)
1,3	R ZERO	r, radius of revolution
2,3	GAMMA PHI THETA	γ , shear strain
3,3	n theta	N_{A}^{0} , circumferential force resultant
4,3	M THETA	MA, circumferential bending moment resultant
5,3	SIGMA THETA IN	σ _{Ain} , circumferential stress on inside fiber
6,3	SIGMA THETA OUT	σ _{θout} , circumferential stress on outside
		fiber
1,4	BASE THICKNESS	basic shell wall thickness
2,4	K PHI	k_, meridional curvature
3,4	N PHI	N, meridional force resultant
4,4	M PHI	M, meridional bending moment resultant
5,4	SIGMA PHI IN	σ_{ϕ}^{ϕ} meridional stress on inside fiber
6,4	SIGMA PHI OUT	σ meridional stress on outside fiber φout

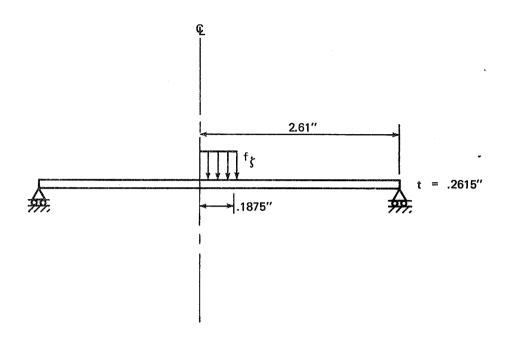
	TABLE 3-1. Tabulated Fi	inal Output Information (Continued)
1,5	STEP	numerical integration step size
2,5	K THETA	k _A , circumferential curvature
3,5	n phi theta	V .
4,5	M PHI THETA	N $_{\phi\theta}$, in-plane shear stress resultant M, twisting moment resultant $_{\phi\theta}$,
5,5	TAU PHI THETA IN	$\tau_{\phi\theta in}^{\phi\theta}$, in-plane shear stress on inside fiber
6 , 5	TAU PHI THETA OUT	$\tau_{\phi \theta { m out}}, \; { m in-plane} \; { m shear} \; { m stress} \; { m on} \; { m outside} \; \; \; \; \; \; \; \; \; \; \; \; \; \; \; \; \; \; \;$
1,6	EPSILON THETA IN	Extreme edge strain for base shell (inner)
2,6	EPSILON THETA OUT	Extreme edge strain for base shell (outer)
3,6	EPSILON PHI IN	Extreme edge strain for base shell (inner)
4,6	EPSILON PHI OUT	Extreme edge strain for base shell (outer)
5,6	GAMMA PHI THETA IN	Extreme edge strain for base shell (inner)
6,6	GAMMA PHI THETA OUT	Extreme edge strain for base shell (outer)

SECTION 4

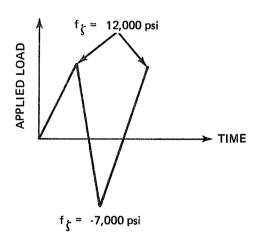
EXAMPLES OF INPUT AND SOLUTIONS

This section contains the full input for two example test problems, and the full output of the second test problem for the STARS-2P program. The first input problem was chosen simply to illustrate a load cycling run data set-up.

The test problem is presented in Figure 4-1. The loading involves both distributed and line loads. The intermediate print clue has been set for abbreviated output and graphic displays of some output variables have been requested. The necessary input is presented on the following pages.



(a) STRUCTURE



(b) LOADING PATTERN

Figure 4-1 TEST PROBLEM 1

```
TEATE UNDER CYCLIC LOAD
4 4 2 3 120 20 2 56 56
NLPL 1
ALUM ISOT
10.05 E 06
 .33
 8.417 E 03
  3.967
  4.0
         E 03
ALU1
         ISOT
 10.05
          E 06
  . 33
  8.417 E 03
  3.967
  4.0 E 08
 1 0 0 PLATE
1 1 2
21 20
21 20
.002 1.0 E-04 .0006
0.0
ISOT ALU1 SING THIC
                                                                      0.
                 SING THIC NOTH KINE
                                                                     2
            .02
 .0020
.2615
000100
             .2615
 12.000 E 03 12.000 E 03
1 1 2
1 0 0 PLATE
2 2 3
21 20
  .01780 1.0 E-04 .005933
                                                                     0.
0.0
ISOT ALUM S
.0200 .1875
.2615
                            THIC NOTH
                                                                      2
                  SING
                                               KINE
000100
12.000 E 03 12.000 E 03
1 1 2
 1 0 0 PLATE
3 3 4
21 20
```

```
.21130 1.0 E-04 .042250
                                                          0.
0.0
ISOT ALUM SING THIC NOTH KINE
.1875 .61
.2615 .2615
                                                          2
      1 2
1 0 0 PLATE
4 4 5
21 20
       1.0 E-04 .2
 1.0
                                                          0.
0.0
ISOT ALUM SING
.61 2.61
.2615
                       THIC NOTH KINE
                                                           2
 1 1 2
5 0
1 0 1 0 0
2 0 1 1 1 3 0 1 1 1
40111
 50011
1 1 -.150797
4 4 2 3 -190 20 5 1
ALUM
10.05 E 06
 .33
       E 04
1.6834
3.967
 4.0 E 03
ALU1
       ISOT
10.05 E 06
. 33
 1.6834 E 04
 3.967
 4.0 E 08
```

000100 19.000 E 03 19.000 E 03 000100 19.000 E 03 19.000 E 03 1 1 1 -.238762 4 4 2 3 190 20 0 The second test problem involves monotonic loading of a structure similar to that shown in Figure 4-1. The thickness of the plate for this problem is 0.1286" and the loaded area radius is 0.18675". The applied load increases monotonically to 5,000 psi. The input and output for the problem is presented on the following pages. The apex segment was treated as an elastic plug in this problem because of a local stress singularity at the apex which is dependent upon computer accuracy. Further discussions of this and other problem results are available in Ref. 1.

```
CARCULAR PLATE TP1
4 4 2 1 50 50

NLPL 1 1 1

ALUM ISOT
                     1 1 25
10.5 E 06
 . 33
 6.634
       E 03
 3.661
  4.0
         E 03
ALU1
        ISOT
 10.5 E 06
 .33
  6.634 E 03
  3.661
  4.0 E 08
 1 0 0 PLATE
1 1 2
21 20
  .002 1.0 E-04 .0006
                                                                0.
         ALU1 SING THIC NOTH KINE
.02
.1283
0.0
ISOT ALU1
 -0020
 .1283
000100
 000100
0.5000 E 04 0.5000 E 04
1 1 2
1 0 0 PLATE
2 2 3
21 20
  .01780 1.0 E-04 .005933
                                                                0.
0.0

ISOT ALUM SING THIC NOTH KINE

.0200 .1875

.1283 .1283

000100
 0.5000 E 04 0.5000 E 04
1 1 2
1 0 0 PLATE
```

```
.21130 1.0 E-04 .042250
0.0
ISOT ALUM
0.
                               2
1 1 2
1 0 0 PLATE
4 4 5
     1.0 E-04 .2
1.0
                                0.
0.0
ISOT ALUM SING THIC NOTH KINE
.61 2.61
                               2
.1283
      .1283
   1
     2
10100
20111
30111
40111
1 1 -.125664
```

UNSYMMETRIC. ORTHOTROPIC. REINFORCED SHELL ANALYSIS WITH COUPLING OF AT MOST 29 SHELL REGIONS STARS-2P

AS OF JULY 1. 1973

NUMBER OF SEGMENTS * 4 NUMBER OF REGIONS * 4 NUMBER OF MATERIAL PROPERTY TABLES USED * 2 NO. OF CYCLES *

LARGE DEFLECTION PLASTIC PROBLEM

CIRCULAR PLATE TPI

FOR INFORMATION CALL V. SVALBONAS

P. OGILVIE

(516) 575-7701



REGION NUMBER |

THERE ARE I SEGMENTS AND O KINEMATIC LINKS BITHIN THIS RESION

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+33090+00	+00000	+00000	*90000	+00000	+00000	*00000	.00000	+99900	• 000000
+00000	+00000	+00000	*90000	+00000	+00000	+00000	.00000	+00000	+00000
+44340+04	+00000	+00000	.00000	+00000	100900	+00000	.00000	400000	*80800
+34610+01	+00000	+00000	+60000	+00000	+00000	+80000	+00060	+80000	+99800
+48880*07	+00000	+00000	+00000	+00000	+00999	+00900	+00000	100000	*00000
			TABLE OR	SER PHI OR S	VS. CROSSECTION	PROFERTIES			
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	PROBLEM :	TABLE	ORDER PHI OR	S yS. DISTRI	BUTED LOADS (F	THETA, F PHI.	F ZETA, H	THETAL H PHES	
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*2000000±04	+8000000	FDY							
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+0000000	*0000000	2	*8080000	10000000	+0090000	+50000		10000000+01	+0000000
*0000000	*0000000		*0000000	**9574540*D	+00000na	*00000		10.6116229	,3917169ap
+1000+95-61			*0600000	*0000000	+1953874*			000000	+0000000
*0000000	+4492847		*0000000	+0000000		145979		0000000	*0000000
.00000000	+0000000		*4446446-01	+3374047-0		+00900		286077-07	**1743274*0
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14-65

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FORCE	,0000	000	,33593[[+09	,0000000	** 1226876+	07 ,0000008	<u> </u>	,0000000	.,3203037
FORCE	•0000	00	• 0000000	,	. 65580524	07 •0000000	• 0000000	•0000080	1919147+07	• 0000000
HOMENT	+0000	100	**1226831	+07	•0000000	• 1347656+	05 •0000000	•1226838 * 07	•000000	• 7065067
FORCE	w. 6435	722+06	•0000000	j	•0000000	• 0000000	*6435722+05	••0000000	•0000000	•0000000
FORCE	•0000	000	**3357317	+04	•0000000	*1226876+	07 •0000000	·3357317*09	•000000	•3803036
FORCE	.0000	100	.0000000	Γ	19193804	07 ,0000000	.000000	.0000000	,1282536408	,0000000
HOMENT	• 0000	000	320298	+07	•0000000		04 •0000000	•3202986+07	•000000	4411382
						SEGNENT SYNN	ETDY CHECK			
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•100000	0+01	+33573	118+04	•00000	00	•0000000	+0000000	+0000000	•0000000	•0000000
*100000	0+01	• 10000	100+01	• 65580	52*07	•0000000	+0000000	*0000000	•0000000	.0000000
.100000	0+01	*10000	31+01	.10000	100+01	+1347656+05	.000000	.0000000	0000000	,0000000
•100048	5+0!	+10000	100+01	+10000	100+01	+1000000+01	+ 6435922+05	*0000000	• 0000000	.0000000
• 1 00000	0+01	•10000	100+01	•10000	00+01	+1006031+01	+1000000+01	+3359317+09	•0000000	10000000
•100000	0+01	• 1 0000	100+01	•10001	21+01	+1000000+01	+1000000+01	•1000000+01	+1282536+08	.0000000
. 100000	0+01	. 10000	116+01	,10000	00+01	.1000014+01	*1000000+01	.1000016+01	• 1000000+01	, 48 [328 540
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REGION NUMBER 4

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.00000	.00000	.00000	.00000	+00000	+00000	•00000	•00000	.00000	.00000
966340+04	.00000	.00000	,00000	•00000	•00000	•00000	*00000	• 00000	.00000
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EXTERNAL LINE LOADS

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		R PHI OR S VS. DISTRI	BUTED LOADS (F'THETA,	F PHI, F ZETA, M THET	A, M PHI)
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•5000000+04	+5000000+04		V		
	The second secon		AND ADDRESS OF THE PARTY OF THE		10 m
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PHI (RAD. OR IN.	.) DEGRES	R ZERO	BASE THICKNESS	STEP	EPSILON THETA IN
EPSILON THETA	EPSILON PHI	GAMMA PHI THETA	K PHI	K THETA	EPSILON THETA OUT
	K PHI THETA	N THETA	N.PHI.	N PHI THEIA	EPSILON PHI IN
y	J PHI STAR	H THETA	M PHI	H PHI THETA	EPSILON PHI OUT
OHEGA THETA	T PHI THETA	SIGMA THETA IN SIGMA THETA OUT	SIGNA PHI OUT	TAU PHI THETA IN TAU PHI THETA OUT	GAMMA PHI THETA IN
	Martines Principles and American State of the Control of the Contr			The second secon	Boundary Control
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	•	CYCLE 50.		en e	memoria de la composición del composición de la composición de la composición del composición de la composición del composición de la composición del composición de la compos
	Additional to the second secon		and the same of th	The second secon	tigett in 1
			The state of the s	Transports to missions of the last from the first test dark as to pay appropriate participation of the last from the first test dark as to pay appropriate pays to the last from the first	and the second s
2.0000000=02	0 • 0000000	2+0000000*02	1 • 2830000 01	5.9330000-03	-1.7657655-03
1.0303418-03	5.3573559-03	0.000000	-2-9431634-01	-4.3587019#02	3+8264490=03
0.0000000	0.0000000	1 • 23 8 5 9 0 3 + 0 3	2 • 1021231+03	0.000000	-1.3523037-02
2+0606834-05 1+9437463-01	<u>∞6+0325635+01</u> 0+0000000	7 <u>•0103066+01</u> 3•2185439+04	1+2223504+D2 4+9888050+04	0.000000	2+4237749 <u>#02</u> 0+000000
-8.7174028-04	0.000000	-1.7721792+04	-3+0083850+04	0.000000	0+0000000
NPLA #	1 2 3 4 5	6 7 8 9	10 11 12 13	14 15 16 -17 18	19 20 21
SIGNA .	1.78881+04 3.21854*04	0.00000 4.7049		0+00000 4+43587+04	_
		U.0000n 3.8609		0.00000 3.54446+04	
4	4.16107+04 2.68351+04			n•0nngn 2•58598+04	1.63033*04 0.000
	3.22512+04 2.05910+04	0+0000n 2+9086			
	3.22512+04 2.05910+04 2.25144+04 1.40534+04	0.00000 1.8979	2104 1-17715104	0.00000 1.5279+04	9.92321+03 0:000
	3.22512+04 2.05910+04		2+04 1:177;5+04 4+03 5:72058+03 4+04 =7:54983+03		9.92321+03 0.000 9.07626+02 0.000 -1.06983+04 0.000

EPSICON PLAS #	2+04980-02	2+32907 -03	8+00000	1+88195-02	2 2 1 4 4 6 2 2 0 3	0.00000	1+71352-02	1:73775×03	0.0000
	1.54541-02	1.73965-03	0.00000	1.37892-02	2 1.55576*03	0.00000	1.21357-02	1.37914-03	0.0000
	1-04851-02	1.20134-03	0.00000	8.83257-03		0.00000	7-18299-03	8-49603-04	0.0000
	5.54285-Q3	6.79125-04	0.00000	3.91978=g3		0.00000	2.30234-03	2.73682004	0.0000
	6.95659-04	1+35369*04	0.00000	*9.63357 * 04		0.00000	~2·25070°03	=1.46683=04	0.0000
•	-3·47274-03	≈2 · 82978=64	0.00000	94.785 <u>0</u> 8903		0.00000	6.027107-03	*5.42991904	0.0000
	*7·91137*03		0.00000	~9.55694~Q3		0.00000	*1.12149*02	~1.02347-03	0.0000
								· · · · · · · · · · · · · · · · · · ·	
							24		
4.9664999=02		000000	409664		1.5830000+01		330000-03	*8.9874523*0	
4.0248667-03		3419606-03	0.0000		-3.5812223-01	- •	284207-01	1.7037185*0	
0.0000000		0000000	1 0 5 7 4 8 4		1 • 90004; 1 + 03		000000	*1.563[58] ~C	
1.9989499=04		2927106+92	9.3493		1 • 1 1 7 2 2 7 9 + 0 2		900000	3.0312203.0	12
1.9421613-01		0000000	3 • 7 5 3 0		4+23+2781+04		000000	0.0000000	
~1 • 0074151 ~ 02	0 • 0	0000000	*2*3465	155*04	-2+7251794+04	0.0	000000	0.000000	
NPLA ®	1 2	3 4 5	6 7	8 9 10	11 12 13	14 15	*16 *17 18	19 20 21	
SIGMA *	4.23628+04	3 + 75308 + 04	0 • 00000	4.00973*04	3.56027+04	0.00000	3.79102+04	3.37207*04	0.0000
	3 - 58273+04	3 - 18707+04	0.00000	3.37744404		0.00000	3-17039+04	2 . 8 1 3 3 7 + 0 4	0.0000
	2 . 95723+04	2+62070+04	0.00000	2.73338+04		0.00000	2 49321 +04	2.19949+04	0 = 0000
The body of the second	2.23804+04	1 . 9 4 4 2 8 + 0 4	0.00000	1.97210+04		0.00000	1.70162+04	1.42017+04	0.0000
	1 - 42269+04	1.07956404	0 • 0000n	1.05829+04		0.00000	#1.74008+03	97.15158+02	0.0000
	*1+07682+04	*8+04022*g3	0.00000	~1.75318+04		0.00000	#2.07146+04	*1.70994+04	0.0000
	~2.27267+g4		0.00000	~2.48633+04		0.00000	#2.72518+04	*2.34655+04	0 * 0 0 0 0
EPSILON PLAS *	2,74605-02	1,47942-02	0,00000	2,53183~02		0,00000	2,31701-02	1,24147.02	0,000
	2010130-02	1 . 12242 . 02	0.00000	1.88527*02	2 1.00354*02	0.00000	1.64935=02	8.84804×03	0.0000
	1.45386-02	7 • 66330 ~ 03	0.00000	1.23909"02	2 6.48421-03	0.00000	1.02535.02	5.31616.03	0.0000
	8.12519-03	4-15874-03	0+00000	6.00134*03	3 3.01547*03	0.00000	3.87036903	1.90588-03	0 0 0 0 0 0
	1073789-03	8 • 22319 * 04	0.00000	*2 * 90 9 90 *0 4	4 ~3.55326~04	0.00000	· *1.70231*03	~1 . 1 6727 Pg3	0.0000
	#3.37196#03	~2 · 0 5 3 9 9 ~ 0 3	0.00000	"5 · 2055 ; "03	3 "3+02126"03	0.00000	°7.30411°03	*4+10628*D3	0.0000
	≈9.47856≈Q3	<u>~5.26250~03</u>	0.00000	*1+16356*02	2 ~6.43761~03	0.60060	*1.37737 *0 2	<u>∞7+60913∞03</u>	0 * 0 0 0 0
						 ,		· · · · · · · · · · · · · · · · · · ·	
7.3396998*02		3000000	7 . 33 9 & 9	778*02	1+2830000*01	5.7	330000+03	*!.!234215*C	12
5 . 1782578-03		7142829-03	0+00000		-3-6734302"01		584526-01	2 - 15 9 0 7 3 1 9 0	
0.0000000		3000000	105444		1.8307066403		000000	P1+544877290	
3 - 800 6857 -04		8817653+02	9.33428		1.0585450102		000000	3-148133740	
1+9387452*01		0000000	306282		3.8918227904		000000	0 • 0000000	
*1 · 8778274=02	9 • 0	000000	-2.3672	i55 ⁺ 04	=2.5956944+04	0 • 0	900000 '	0,0000000	
1							**		
NPLA 8	1 2	3 4 5	6 7	8 9 10	11 12 13	14 15	*16 =17 18	19 20 21	
SIGNA "	3-87182-04	3+62828404	0.00000	3.71430404	3.46508+04	0.00000	3-84314+04	3.30683+04	0.000
	3 • 3 6 7 7 7 + 0 4	3 - 1 4444+04	0.0000	3.19889+84	2.98957+04	0.00000	3+02477+84	2 + 8 2 7 4 0 + 0 4	0.0000
	and the second s	2+45529+04	0.00000	2.63934404		0.00000	2.4[662+04	2.26191404	0.0000
	2 4 4 4 10 1 2 T 11 4				ייישוישנים פרום א	The first and the state of the	*******		
	2 · 8 4 0 7 2 + 0 4 2 · 1 8 1 9 1 + 0 4	2.04269+04	0.00000	1.94711+04		0.00000	1.73454+04	1.55032+04	0.0000

	-1.04549+04	-9.1950 6+0 3	0.00000	-1.78964+0		0.00000	-2.02676+04	=1.80697+04	0.0000
	*2.20422+04	-1 - 99783+04	0.00000	92.38938+D	4 -2-17617+04	0+00000	#2.59549+04	*2.36726+04	0.0000
EPSILON PLAS *	2+89151-02	1 • 73584=02	0 • 00000	2.66764*0		0.0000	2.44331.02	1.62734-02	0 4 0 0 0 0
	2.21927-02	1 * 47307 * 02	0.0000 ₀	1,99483*0		0.0000	1.77967=02	1016424002	0.0000
	1.54714-02	1.01072-02	0.00000	1.32479=0		0 • 00000	1.10384-02	7.04612-03	0.000
	8.83677=03	5.55983-03	0.00000	6,62993*0		0.00000	4.39508-03	2.60565=03	0.000
	2-16634-03	1.19083-03	0.00000	3.38287 0		0.00000	-1-53992-03	~1.36521-03	0.000
	-3.14048-03 -9.46437-03	-2.48713-03 -6.74178-03	0.00000 0.00000	*4.99930*0. *1.17004*0		0.00000	-7.21691-03 -1.39207-02	*5.22453*03 *9.79548*03	0+000
			440000	-1411000-0		0.60000	-113160,-02		9+000
				·					
9.7128997-0	2 0 • 0	000000	9.712	8997*02	1+2830000*01	5.93	30000-03	*1.2247401*0	12
5.7556266*0	3 7.4	772922-03	0.000	0000	-3.3557214701	~2.80	64268-01	2+375885490	2
0.0000000	0.0	1000000	1.558	7908403	1 . 7753294+03	0.00	00000	-1.4049660#C	
5.5903824-0	4 -2.4	1774274+02	9+377	7378101	1+0006131+02		00000	2.900424590	
1.9332681-0		0000000	3.579	8191404	3.6761547404		00000	0.0000000	
*2.7258541*0	2 0.0	000000	*2 • 373	1440+04	-2+4540983+04	0+00	00000	0.0000000	
NPLA #	1 2	3 4 5	6 7.	8 9 10	11 12 13	14 15.	16 -17 18	19 20 21	
- Y - M	2-47/:5404	7-5708240#	C	3 512464	2 404-4-4-4				
IGMA B	3+67615+04	3.57982+04	0+00000	3.51249+0			3.34535+04	3.26598+04	0 + 000
	3 • 1 8 3 4 0 + 0 4	3+11467+04	0.00000	3+04709+04		_ D • O O O O O	2.91545+04	2-85043+04	0.000
	2.75494+04	2 • 6 9 4 4 9 + 0 4	0.00000	2.5635240		0.00000	2.34440404	S+30131+04	0.000
•	2 • 1 150 • + 04	2+08316+04	0.00000	1+89428+04		0.00000	1+49395+04	1.62530+04	0.000
	1.47519+04 -9.65828+03	-9+32540+04 -9+32122+03	0.00000 0.00000	1.18868+D		0.00000	1.94396403	1.55833+02	0.000
	#2.10226+04	-2+03501+04	0.00000	#2.26628+D		0.00000	-1.93914+04 -2.45410+04	71.84647#04 72.37344+04	0.000
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EPSILON PLAS =	2,66282-02	2.15049-02	0.0000	2.45817402	1.98038#02	0.00000	2,25393-02	1.80991-02	0.000
	2.04932-02	1+63920-02	0.00000	1.84289-0		0.00000	1.43400-02	1.27588-02	0.000
	1.43093-02	1+12572=02	0.0000	1.22826=0		0.00000	1.02732-02	7.90136-03	0.000
•	8.27036=03	6.23672-03	0.00000	6.25734=0		0.00000	4.22212.03	2.93978=03	0.000
	2.18351-03	1+35633*03	0.00000	1.86024*0		0.00000	P1.21373P03	*1.37941=n3	0.000
	~2.65930*03	-2 + 661 80 -03	0.00000	-4+33076-03	-4-07975-03	0.00000	-6.33138-03	95 · 67849 • 03	0.000
	w8.38169=D3	#7+36956*03	0.0000	#1+04281 <u>#</u> 02	*9.07017*03	0.00000	#1.24584#02	-1.07585+02	0.000
									· .
1.2086100=0	0.0	000000	1 - 2086	100-01	1+2830000701	5.93	30000=03	*1.2832238*Q	2
6.1002128=03	8.0	542503-03	0.000	0000	-3-4800452-01	-2.95	12783+01	2.503264390	2
		000000	1+3881	096+03	1.7164693403	0+00	00000	71+42703487Ö	2
0.0000000	-3.0	759372+02		590+01	9+3925141+01	0.00	00000	3.0378849-0	
7 • 3727781 • 0			2.4.96	1929+04	3+3528554+04	0+00	00000	0.0000000	•
7+3727781=04 1+9258043=01	0.0	000000	9,13,1						
7.3727781*0	0.0	000000	-2-3396		-2-3729577+04	0.00	80000	0.0000000	
7.3727781=06 1.9258063=01 -3.5669443=02	0.0				11 12 13		16 -17 18	19 20 21	
7.3727791-04 1.9258063-01 -3.5669443-02	1 2	3 4 5	6 7	8 9 10	11 12 13	14 15	16 -17 18	19 20 21	0.000
7+3727781=04 1+9258043=01	0 • 0 2	000000	-2+3396	244+04	11 12 13 3.32611+04			 _	0.0000

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	2.0000	3+04	2*154	55+04	9.0000	3	1+92	601+04	1.	72448	+94	0.90000	0	1+7	7619	7+04	100	42955	+04	0.0000
	1.65117	7+04	1 . 292	97+64	0.00000		1+24	173+04	9.	44527	+92	0.00000	9	7+1	1767	1+03		95293		0.0000
	-7 - 67 254		-1:070		0+60000			952+04		71346		0+00000				3+04		89022		0.0000
	-2+0941	8+04	~2.047	184+0+	0+60000		-2.22	683*04	*2.	19177	404	0.00000	9	.S.	3724	6+04	-201	33762	707	0+0000
Epglion plag *	2+82446	8"0Z	24281	03-02	0+00000	-	2161	157°02	24	04679	-02	0 - 00000	,	21;	3992	צטייג	105	71650	-02	0.0000
	2,17881	1-02	1.735	76-02	9,0000		1,94	457*02	1.	85526	*92	0.0000	3			7°02		37621		0,0000
	1.53791	1-02		36-03	0.00000	,		448-02		01570		0.00000				P=02		34728		0+0000
a recasement de la compa	8+77450	0-03		44+07	0+00000			352"03		87142		0+00000				e-03		20878		0+0000
	2 - 5184			187-07	0.0000			069"04		67925		0.00000				1-03		49628		0.0000
	-2.7156		*2+5-0¢		0+0000			003"03		15159		0 * 90 0 0 0				6+D3		95793		0.0000
	-5.44413	5-03	-7.750	145+03	0+00001		-1+0+	060-02	-7.	56146	-03	0.00000		-1	2/13	7-02	744	13498	-04	0+0000
1.4469999wa)		0-0	000000	-		57299	901		1.26	30000	201		5.03	90000	-03		*1	2941	1001	02
1+4467277-01			000000										Contract Name	THE RESERVE	_	_			8639	
4+1975312-03			044071-	-0.2		000000				97531				34837-	-01				2390	
0.0000000			760000	10.9		58662				64659 67929				00000	_	-			4489	
0.7411754-07			7507554	20		29499				50300				20000			1/2/	+0000		
-4+3141977*0Z			000000			24147				01489			-	00000	8			+0000		
-41-21-41-77	+						• 1			3.740					8. 17		- 27		-	
HPLA #	1 4	2	3 4	5	6 7		9	10	11	.12	13	19 10		16 -	17	10	19	20	21	
SIGNA "	3+2058		_	75+04	0.0000	,		149*04		29435	market in comme	0.00000			-	2+09		11982		9+0000
	2 . 8567	9+0+	2+993	90+04	0+60000		2 . 73	854*04	2 .	86554	+04	0.00000	9		7.6	3404		73100		0+0000
	2.44950	0+04	2:500	10*01	0+00000		2+30	701+04	2 .	91199	1104	D+00000	0			5+04		23076		0+0000
	1.9630	4+04	2+061	59+04	0 > 00000		1 : 69.	257+04	1.	84053	1404	0+00000	0			2+04		1004		0.0000
040	1+52274			54+04	0.0000			793+04		66010		0+90000	_		8458			19551		0+0090
	-4+03550		-1+045	and the second second	0+00000			340+64		70131		0+00000				2+04		92054		0+0900
	-1 - 73386	9104	*2+059	04404	9+0000		~2+07	PQ+236	-21	18905	1404	0 * 0 0 n 0 t	2	4200	2185	0+09	-444	22241	787	0+0000
EPSILON PLAS ×	2,3532	4-02	2,312	67-02	0.00000		2,17	953-02	2.	13037	-03	0.00000	0			3.02		94730		0,000
	1+82257	7-02	1+765	20-02	9+00094		1069	110"02	1 .	56133	-02	0+00000	0			7-02		39878		0.0000
	1 - 26735	5-0Z	10217	25-02	0.00000			265-02		03676		0+00090	9			5-63		66571		0+0000
	7+02290	8~03	6+771	43-03	9 . 00000	1		652~93		00567		0.8900	D.			69=6		27591		0+0000
	2+23983	3-03		72-03	0+0000			369-04		65820		0+00000	-			7+04		91753		0.0000
	-3-03131	-	*2+560		0+00000			343703		11074		0.00000	*			0:03		72366		0.0000
	-5-45469	0~03	*7 * 7 % 1	91-03	0.00000	-	-8-91	769-03		598q6	203	0.00000	8	-1+1	3100	2-92	-11	19254	*84	0+0000
	-	-			A (1000)	Carriery	35000.0								2000			22432	122710	
1+6832498=01		0.0	000000		1+41	32448	-01			20000	N. W. S. W. S.			ecces-					785-	
6+2117170~02		7.0	478929-	63	· 0+0;					02677			March Control	17534	101				3170	
0+0000000			000000			64447			1.00	10165				90000					1884	
1+0955072*03			7984174	50		00532				42523	_		-	09990					7597	12
1 - 9053572-01		7.7	800000			24650				64705				00000				0000		
+5+0055347-02		0.0	960239		-2+3:	56622	709		2+07	01948	TR9		2+000	10000	-	-	8	.0000	000	· ·
MPLA s	17	2	24	- 5	6 .7	- 8	9	10	11	12	13	-74 -D		6 -	17	10	19	20	11	

	the same of the later				the second second				
	2-71971+04	3+17899+04	0.00000	2+42329*04	3-04458*04	0+00000	2.52272*04	2.90890*04	0+00000
	2+40720+04	2+74010101	0.00000	2+27770*04	2+40167+04	0+00000	2+14542+04	2.43345+04	9+00000
	2.00342+04		0.00000	1.84444*04	1.78488+09	0+00000	1.70224+04	1.48492+09	0,00000
100000000000000000000000000000000000000	1+53213+04		0.00000	1.27307*04	8.12032+03	0+00000	4+11443+03	1+44634+03	0.00000
F.C	4.51992+03	-1+031+1+04	0+00000	-1+35594+04	-1.47744104	0.00000	-1-45351+04	-1+92784+04	0+00000
	-1-61724-04	-2+07504+04	0+00000	-1+94966+04	-2.20544404	0.00000	*2+07013+04	*2.33566+04	0+00000
EPETLON PLAS *	2+25452402	2+28463-02	0.00000	2.07039*02	2-10417-02	0+00000	1.42331-02	1.72138-02	0.00000
	1.75575-02	1.73924*02	0.00000	1.56616"02	1,55804-02	0.00000	1,42004-02	1,37725-02	0.00000
	1.25460-02		0+00000	1.00937-02	1.01727*02	0+00000	9.24104-03	8,38372-03	0.00000
	7+56847-03		0+00000	5.93382-03	4.89974*03	0+00000	4.25020-03	3.23465-03	0.00000
	2.57389-03		0+00000	9+33222*04	1.15511*04	0+00000	-3.72436-04	*1.34430=03	0.00000
	*1 -45475-03	*2148407*03	0100000	*2.52279*03	*9+84274*03	0+90090	*4*04389*03	-5 .82545-03	9+00000
	-5-44001-03		0+00000	*7.30076*03	-9.46927-03	0+90090	-8.95269-03	-1-12910-02	0.00000
1+8412397-01	0.	0000000	1.0415	397-01	1+2830000=01	the second second second second second	739000+03	-1-2669046-	
4+1374484=03		8797407-03	0.0000		-2+1430505-01		93:4749-01	2.4744343+	
0+0000000		0000000		982*03	1+5827115+03		0000000	-7.9942079-	e.e.o. it is a second or in
1+1423636-03		7244019+02		735*01	7+4352455+01		0000000	1+9755729-	12
1+8740361=01		0000000		321104	2+0214202104		0000000	0:0000000	1
*5+4565499*02	84	0090000	#2+Z902	638704	-1+9417507+04	0+0	9909000	0.0000000	
				- 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1			-		
MPLA &	1 2	3 4 5	4 7	8 4 16	11 12 13	_14 _15	16 17 18	16 50 51	
SIGNA .	2-82143+04	3+24773*04	0.06006	2+73359*04	3+14498+84	0.00000	2+65842+04	3-94687+04	0+00000
-	2+58471+04	2+94425*04	0+00000	2 - 48779 + 04	2.02532*09	0.00000	2+36984+04	2+48478+04	0.00000
ALUCE CHICAGO	2+23729+05	2+53485*05	0.000000	2+07944704	2428219+04	0100000	1.96834*04	2+22695*Q4	0100000
	1+64661+04	2+05278+04	0:00000	1.74274404	1.05546*99	0+00000	1-43542*04	1+60061*04	0+00000
	1+50232+04	1+21029109	0.00000	1.21917704	7.84531+03	a.0ooca	5+71055+03	7.59540102	0.00000
,	03+19430+03	****1428*@3	0.00000	49+44825+03	-1+42775+09	0+00000	-1.41741+04	=1+90453+04	0+00000
	*1.05879+04	22:04884±04	9±0000e	*1+81819*04	-2-17387*09	D+90000	21.25175+05	.42.27024+04	D+00000
EPSILON PLAS .	1.00072-02	2,27381-92	0.00000	1+47531+02	2,09276=02	0+00000	1,54043-02	1.71147-02	0,00000
district the state of the	1 - 40571-02	1+73080-02	9.09000	1+27240*02	1.55128-92	0+00000	1+14052-02	1+37270-02	0+00000
	1+00947-02	1+19474*02	0.00000	8.29188*03	1+01698*02	0100000	7+48021-03	4+29+80-03	0+00000
	6+15207+03	6>69496*93	0.00000	4.00319*03	4.71808"93	0+00000	3+42747-03	3:25658-03	0.00000
	2+05415-03	1+49565=03	0100000	4+03022*01	1:29625"04	0100000	-1-70017-04	-1+27749-03	0+00000
	-1 -04987-03	*2+46950*03	0.00000	"2.038\$2"D3	~3+87736~03	0,00000	-3-06001-03	*8+45744-03	0+00000
	**********	*7:47777703	0.000000	*5.56022703	-9+28945-03	0100000	-6.R4672-03	-1+10781+02	9:00000
-,									
1-6760000-01	6.	0000000	1+8750	1000*01	1+2630000*01	5.1	122000000	*1.2645304=)2
4+1250114-03	5.	6108130+03	A+0e06		-3-1390345-01	=2.5	104000005	2448753270	
0+0000000	0.	0000000	1+3251	638*63	1+5404264+03	0.0	000000	-7.0810742-	13
1+1484397=03		7591032+02		778*01	7+3878944+01		1000000	1.75627627	12.
		0000000		448404	2+80*2457+04		1000000	0.0000000	
1+8952622*01							000000	0.40000000	
*5+4842574*03	0.	0000000	*2*2490	104104	-1-9325514404	- 010	1000000	0.0000000	

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STEHA *	2+80827+04		0.00000	2072244404	3 * 1 4 1 9 2 + 0 4	0.00000	2+64852+04	3.04378404	0.00000
3 3 20 1100	2.57357+04	2.94172+04	0.00000	2,47491+04	2.81936+04	0.90090	2,35692+04	2,6g0g0+ 0 4	0.00000
	2.22566+04	2.53204+04	0.00000	2.07010*04	2.38009+04	0.00000	1.96128+04	2.22508+04	0.00000
	1.84367+04	2.05129+04	0.00000	1.73952404	1.85368+04	0.00000	1.63394+04	1.59767+04	0.00000
	1.49994+04	1 • 20878+04	0.00000	1.21845*04	7.84395+03	0.00000	5.74297+03	7.39512.02	0.00000
	*3.08667+03	≈9.27473+03	0.00000	** 9 . 4 4 9 0 8 * 0 3	~1.61709+04	0 • 0 0 0 0 0 0	×1.40591+04	~1.90397+04	0.00000
	91.64854+04	-2-04779+04	0.00000	-1.69691404	~2.17286+04	0.00000	*! · 93255+04	2.28902004	0.00000
EPEILON PLAS W	1.79076*02	2.25589*02	0 · 0000ci	1.65852*02	2.08816*02	0.00000	1.52527-02	1.90746-02	0.00000
SLESPAN LEUD	1.39197-02	1.72714-02	0.00000	1.24030-02	1.54799*02	0.00000	1,12997-02	1.36978-02	0,00000
	1.00057-02	1.19212-02	0 • 0000p	8.71488*03 4.76675*03	1.01462*02	0.00000	7.41665-03 3.41465-03	8.37636~03 3.23991~03	0.00000
	6.10185-03 2.04784-03	1 6 9 1 1 4 = 0 3	0.00000	8.10360*04	1.29816-04	0.00000	~1.71632-04	~1.27305-03	0.00000
	#1.01770903	-2.47366°D3	0 • 0 0 0 0 0	"2 + 00042"03	-3.894 <u>0</u> 7-03	0.00000	~3 *02393~03	-5.64276-03	0.00000
	-4-21024-03	*7 + 45 9 Q 8 * Q 3	0+00000	~5.46702~03	~9.26738~03	0.00000	-6.75996-03	*1.10727*02	0.00000

REGION NUMBER 3 THERE ARE I SEGMENTS AND O KINEMATIC LINKS WITHIN THIS REGION SEGNENT NUMBER 1 SEGMENT CODE 21 NO. OF LAYERS 20 TABLE ORDER PHI OR S VS. CROSSECTION PROPERTIES · 1875000+00. • 6100000+00 · 1283000+00 +1223000+00 PH; (RAD, OR IN.) DEGRES R ZERO BASE THICKNESS STEP EPSILON THETA IN EPSILON THETA EPSILON PHI GAMMA PHI THETA K PHI K THETA EPSILON THETA OUT K PHI THETA N THETA N PHI N PHI THETA EPSILON PHI IN 4 A J PHI STAR H THETA H PHI M PHI THETA EPSILON PHI QUT T. PHI THETA SIGNA THETA IN SIGNA PHI IN TAU PHI THETA IN GAMMA PHI THETA IN OMEGA THETA OMEGA PHI SIGNA THETA OUT SIGNA PHI OUT TAU PHI THETA OUT GAMMA PHI THETA OUT CYCLE 50. 1.8750000-01 0.0000000 1 . 8750000 01 1 . 28 30000 01 4 . 2250000 902 *1.2645309=02 6.1250114#03 4.3893477-03 0.0000000 -1.9325211-01 -2.9260047-01 2,4895331-02 0.0000000 0.0000000 1 43316176+03 1+3220654+03 0.0000000 ~8.0077754**~**03 1 = 1484376=03 -4.7124183+D2 8 - 6768125 +01 7+3677046+01 0.0000000 106786471002 1 . 8752822701 0.0000000 3.2597969+04 2+4634838+04 0.0000000 0,0000000 #6+4842590*02 0.0000000 **2+3**055371+04 -1 · 7203840+04 0.0000000 0.00000000 NPLA B 2 10 11 15 *16 *17 18 19 20 21 12 SIGNA . 2+46348+04 3 - 25 9 80 +04 0 · 0000n 2.58131+04 3 - 15222+04 0.00000 2.50110+04 3.04469+04 0.00000 2041657+04 2093118404 0.00000 2.31528+04 2+80231+0# 0.00000 2.20193/04 2.66144+04 0.000000 2 - 07 908+04 2+51147+04 0.00000 1+95131+04 2.35433+04 0.00000 1.82358+04 2 + 19670 +04 0.00000 1469806+04 2+02713+04 0.00000 1.57232+04 1.84099404 0.00000 1 - 43436+04 1+60874+04 0.00000 1 - 26437+04 1 0 2 8 8 0 5 + 0 4 0.00000 9.53437403 9-15109+03 0.00000 1 • 29217 + 03 *4 · 04172+02 0.00000 #7.73449+na P1+15775+04 0.00000 "1 . 25880 +04 #1.71#22*D# *1.52024+04 #1.91397+04 0.00000 0.00000 #1.48175+04 #2.05381+04 0 • 0000n -1.81161+04 -2 . 18432+04 -1-92038+04 0.00000 -2.30554+04 0.00000 EPSILON PLAS . 1 - \$2743-02 2+26279902 0 * 00000 1 - 40791 -02 2.08274"02 0.00000 1 - 28819-02 1 . 90276=02 000000 1+14871-02 1.72321-02 0.0000 1.05033-02 1.54440-02 0.00000 9.32729-03 1.36675-02 0.00000 8 - 15744-03 1+18947-02 0.00000 6,97065-03 1.01253-02 8.36011-03 0.00000 5.82242mD3 0.00000 4.64896-03 4+40512-03 0.00000 3.47050-03 4.86585-03 2.28918-03 0.00000 3-16664-03 0.00000 1+11058-03 1+54161-03 0.0000 4.95901-05 -7.79017-05 0.00000 -7 . D5268-04 -1.30401-03 0.00000

	01.43646003	~2,40062~03	0.00000	~2.38882~03	*3.70022*03 *7.25734*03	0.00000	*3.44233*03 *6.90344*03	~5.66917~03 ~1.10531~02	0.0000
	4.217.03	*7 • 44378 *03	0.00000	*5.72722*03	4442/34-03	.0.00000	***************************************		
						# 2	250000*02	~7.85Q48 6 7~	33
4 - 8325000*01	0.0	0000000	4 0 8 3 2 5		1.2830000*01		205076-01	1.2940625**	
2 - 5 4 5 0 6 9 3 7 0 3	107	395115-03	010000	~~~	2 2027 645 402		200000 200000	3.2643683	
0.000000	0 + 0	0000000	9+3268		1+0705541+03		300000	3 - 1525863"	
1.2299047-03		3284084+02	605028		3 • 0 3 5 0 0 2 7 † 0 1 1 • 4 4 5 7 9 8 0 † 0 4		900000	0.0000000	
1 + 6861438-01		3000000	2 • 2734		-701427858*03		900000	0.0000000	
~7.83;1026*02	0.0	0000000	#107778	300184	-142-621-684-64			minimum and a fraction of the color	
SPLA P	1 3	3 4 5	6 7	8 9 10	11 12 13	14 15	16 17 18	19 20 21	
- M - M - M	1 - 44530+04	2+27345+04	0.00000	1 41362+04	2.21605+04	0.00000	1.38608+04	2.15874+04	0.0000
SIGNA P		2.07500+04	0.00000	1.32110+04	2.02624404	0.00000	1.28850+04	1.95184+04	0.0000
*	1.35375+04	1 - 8 6 6 3 4 + 8 4	0.00000	1 + 22249 + 04	1.77577404	0.00000	1.18991+04		0 0000
	1.14200+04	1.52842+04	0.00000	1.14244404	1.35095+04	0.00000	1.12161+04	1,09564+04	0.000
~ ~	1.03037+04		0.00000	7.65147*03		0.00000	4.13535+03	#4 + 17910 + D3	0 • 0 0 0 0
	1.31017+03		0.00000	≈1,14643 † 03		0.00000	~3,12656+03		0.0000
	#4.75329+G3		0.00000	∞6.01739+03	~1.46169+Q4	0.00000	∞7 • 1 4 2 7 9 • Q 3	40141991117	
sh			0.00000	2.34145*03	1 . 02348 . 02	0.00000	Z.22835°03	9.24120=03	0.0000
EPSILON PLAS *	2-49015-03	1 - 1 2 2 9 8 - 0 2		1,76599+03		0.00000	1,83234,03	6,28891-03	0.0000
	2,09760-03		0,00000	1.55725*03		0.00000	1.41198-03		0.000
z :	1.69788-03		0.00000	1.07605-03		0.00000	8.74350=04		0 * 0 0 0 0
	1 - 25451 - 03		0.00000	6.16188-04		0.00000	6.49094-04		0.000
<u> </u>	6+89D73*D4		0+00000	6.49133*04		0.00000	\$ • 23°04°04		0.000
	4+54468=04 5-80033=04		0 • 0000a	5 . 18584 -04		0.00000	4-47954-04	-6.38180°03	0.000
	5.82032-04								
									03
			E - 6978	992901	1.2830000*01	4 0 2	250000002	-7-0753662	
5-6774978**08	_	0000000		1448-01	1 • 2830000 * 01		2500000°02 087626°01	-7-0753662° 1-1001623°	
5°6774978°0; 1°9631285°03	. 10	5134510=03	0 • 0 0 0 0	0000	-1.3701320902	w104	087626-01	1 • 1 0 0 1 6 2 3 ° 6 • 3 4 7 1 1 3 7 °	02 104
1.7631285~03	0.0	0000000 5134510=03	0+000 8+3e3	0000 8660+02	1.0246568+03	₩1 e 4 Q • £		1-1001623	02 104
1,7631285*03 0.000000 1,1145662*03	0 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -	5134510±03 0000000 5542807+02	0 • 0 0 0 0 8 • 3 0 3 6 6 • 2 3 9	0000 8660+02 1844+01	-1.3701320502 1.0246568+03 2.7660486+01	9 · C 0 · C 0 · C	087626-01 1000000	1 • 1001623• 6 • 3471137• 2 • 3925907• 0 • 6000000	02 104
1 • 9 • 3 1 2 8 5 ° 0 3 0 • 0 0 0 0 0 0 0 1 • 1 1 4 5 • 6 2 ° 0 3 1 • 6 1 9 2 0 5 • ° 0 1	0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510±03 0000000 5542907+02 0000000	0 · 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0000 8660*02 1844*0; 7579*04	1.0246568+03	0 · 6 0 · 6 0 · 6	087424-01 000000 000000	1 <u>+1001623</u> 6+3471137 2+39259 ₀ 7	02 104
1,7631285*03 0.000000 1,1145662*03	0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510±03 0000000 5542807+02	0 · 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0000 8660+02 1844+01	-1.3701320702 1.0246548+03 2.7460486+01 1.3352818+04	0 · 6 0 · 6 0 · 6	087626~01 000000 000000	1 • 1001623• 6 • 3471137• 2 • 3925907• 0 • 6000000	02 104
1 • 9 • 3 1 2 8 5 ° 0 3 0 • 0 0 0 0 0 0 0 1 • 1 1 4 5 • 6 2 ° 0 3 1 • 6 1 9 2 0 5 • ° 0 1	0 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510±03 0000000 5542907+02 0000000	0 · 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	0000 8660*02 1844*0; 7579*04	-1.3701320702 1.0246548+03 2.7460486+01 1.3352818+04	0 · 6 0 · 6 0 · 6	087626~01 000000 000000	1.1001623* 6.3471137* 2.3925907* 0.0000000 0.00000000	·02
1.9631285*03 0.0000000 1.114562*03 1.6192056*01 *7.9993846*02	1 2	5134510m03 0000000 5542807+02 0000000 0000000	0.0006 8+303 6+239 2+151 -1+698	0000 8660+02 1844+01 7679+04 3962+04	-1.3701320502 1.0246548+03 2.7660486+01 1.3352818+04 -6.1285388+03	0 • 6 0 • 6 0 • 6	087626~01 000000 000000 000000 000000 16 17 18	1.1001623* 6.3471137* 2.3925907* 0.6000000 0.00000000	0.000
1,9631285°03 0.0000000 1,145662°03 1,6192056°01 97,9993846°02	1 2 1 - 33528+04	5134510=03 0000000 5542807+02 0000000 0000000	0.0000 8.303 6.239 2.151 2.698	0000 8660+02 1844+01 7579+04 3962+04	-1.3701320502 1.0246548+03 2.7460486+01 1.3352818+04 -6.1285388+03 11 12 13	9104 000 000 000 000	087626~01 000000 000000 000000 16 17 18 1.28457+04 1.20136+04	1.1001623 6.3471137 2.34725907 0.000000 0.0000000 19 20 2 2.04281+04 1.83947+04	9 · 0 9 0 9 0 9 0 9 0 9 0 9 0 9 0 9 0 9
1.9631285*03 0.0000000 1.114562*03 1.6192056*01 *7.9993846*02	1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510=03 0000000 5542807+02 0000000 0000000 3 4 5 2+15174+04 1+78024+04	0.0000 8.303 6.239 2.151 ~1.698 6 7	3000 8640+02 1844+01 7579+04 3962+04 8 9 10 1.31258+04 1.22857+04	-1.3701320502 1.0246548+03 2.7460486+01 1.3352818+04 -6.1265358+03 11 12 13 2.10072+04 1.71285+04	0 · 0 0 · 0 0 · 0 0 · 0 1 · 4 1 · 5	16 17 18 1 22457404 1 12246404	1.1001623 6.3471137 2.3925907 0.000000 0.0000000 19 20 2 2.04281+04 1.83947+04 1.55007+04	02 04 03 000 0000 0000
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1.9631285*03 0.0000000 1.114562*03 1.6192056*01 *7.9993846*02	1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	\$134510*03 0000000 \$542807*02 0000000 3 4 5 2015174*04 1078024*04 1075844*04 1041002*04	0.0000 8.303 6.239 2.151 -1.698 6 7 0.00000 0.00000	3000 8660+02 1844+01 7579+04 3962+04 8 9 10 1.31258+04 1.22857+04	1:3701320702 1:0246548+03 2:7690486+01 1:3352818+04 -6:1285358+03 11 12 13 2:10072+04 1:71285+04 1:66341+04 1:22476+04	14 15 0.00000 0.00000 0.00000 0.00000 0.00000	16 17 18 1 28457+04 1 2136+04 1 06724+04 3 87934+03	1.1001623* 6.3471137* 2.3725907* 0.0000000 0.00000000 1.7 20 2: 2.04281+04 1.835947+04 1.550077+04 9.49389+03	02 04 03 000 000 000 000 000 000 000 000
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1.9631285*03 0.0000000 1.114562*03 1.6192056*01 *7.9993846*02	1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510m03 0000000 5542807*02 0000000 0000000 3 4 5 2:15174*04 1:78024*04 1:71002*04 1:41002*04 3:40764403	0.0000 8.303 6.239 2.151 -1.698 6 7 0.00000 0.00000	0000 0660+02 1844+01 7579+04 3962+04 8 9 10 1.031258+04 1.22657+04 1.0168+04 4.90113+03	-1.3701320502 1.0246548+03 2.7460486+01 1.3352818+04 -6.1265358+03 11 12 13 2.10072+04 1.71285+04 1.64341+04 1.2270+04 3.480105+02 -1.10270+04	14 15 0.00000 0.00000 0.00000 0.00000 0.00000	16 17 18 1 28457+04 1 2136+04 1 06724+04 3 87934+03	1.1001623* 6.3471137* 2.3925907* 0.6000000 0.00000000 19 20 2 2.04281+04 1.83947+04 1.55007+04 1.55007+04 1.95289+03 3.44.95289+03	0.000 0.000 0.000 0.000 0.000 0.000 0.000
1.9631285*03 0.0090000 1.114562*03 1.6192056*01 **7.9993846*02	1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	5134510*03 0000000 5542807*02 0000000 0000000 3 4 5 2*15174*04 1*78844*04 1*75844*04 1*41002*04 5*02508*03 **2*49744*03 3 *1*44657*04	6 7 0 000000 0 000000 0 000000 0 000000 0 000000	3000 8640+02 1844+01 7579+04 3962+04 8 9 10 1 * 31258*04 1 * 22857*04 1 * 14768*04 1 * 09168*04 6 * 99113*03 * 7 * 51354*02 * 5 * 17699*03	-1.3701320702 1.024658+03 2.7690486+01 1.3352818+04 -6.1285358+03 11 12 13 2.10072+04 1.71285+04 1.71285+04 1.66341+04 1.22476+04 2.460105+02 2.460105+02 2.460105+02 2.460105+02	0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000	16 17 18 1 28457+04 1 12246+04 1 08784+04 2 18784+04 2 18784+04 2 18784+03 3 2 2 4 9 7 2 + 03	1.1001623* 6.3471137* 2.3725907* 0.0000000 0.00000000 1.7 20 2; 2.04281+04 1.83947+04 1.85907+04 7.49389+03 0.4095289+03 1.49840+04	0.000 0.000 0.000 0.000 0.000 0.000 0.000
1.9631285*03 0.0000000 1.114562*03 1.6192056*01 *7.9993846*02	1 2 1 33528+04 1 025636*04 1 017493+04 1 019285+04 1 032953+04	5134510*03 0000000 5542807*02 0000000 0000000 3 4 5 2 15174*04 1 98024*04 1 175844*04 1 141002*04 5 02508*03 8 9 9 37199*03	0.0000 8+3036 6+239 2+151 2+699 6 7 0.00000 0.00000 0.00000 0.00000 0.00000	3000 8660+02 1844+01 7579+04 3962+04 8 9 10 1.31258+04 1.22857+04 1.1768+04 1.07168+04 4.98113+03 -7.51354+02	-1.3701320702 1.0246548+03 2.7690486+01 1.3352818+04 -6.1285388+03 11 12 13 1 2.10072+04 1.71285+04 1.71285+04 1.64341+04 1.22476+04 2 -4.80105+02 2 -1.10270+04 3 -1.59512+04 3 8.50962-93	0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.00000	16 17 18 1 28457+04 1 2136+04 1 06724+04 3 87834+03 -6 12854+03	1.1001623* 6.3471137* 2.3925907* 0.000000 0.0000000 1.9 20 2: 2.04281+04 1.83947+04 1.855007+04 9.49389+03 -1.30540+04 1.49840+04 3.7.65212=03	0.000 0.000 0.000 0.000 0.000 0.000 0.000

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A St. St.	7.74360=04	1+87072*03	.040000a >	8.58881704	1-13979-03	0.00000	7-05414-04	4.91145-04	0.0000
<u> </u>	5.80442-04	-2-11496-05	0.00000	5+77630=04	-4.95803-04	0.00000	· 37047-04	-1.05867-03	0.0000
	6.03320#04	-1-71361-03	0.0000	7-11283-04	-2.43339-03	0.00000	77.26098-04	-3-19911-03	0.0000
	7-24980-04	-3.99632-03	0.00000	7 • 14329-04	-4.81506-03	0.00000	6.84600904	~5·45046~c3	0.0000
V. H.			*				The same state of the same sta		To a supplemental and the supplemental and
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1.0463394-03		484891+02	6-14095		2+4882354+01		00000	2 - 1546421	03
1.5852780-01		000000	2.10173		1.2980834+04		00000	0.0000000	
-8-0591677-02		000000	-1+67434		-5+8628776+03	0.00	00000	0.0000000	
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φ <u>ή</u> 2014	1+14262+04	1 . 70422+04	0.00000	1.11794404		0.00000	1.09540+04	1.49277+04	0.0000
	1 • 07834+04	1 . 3 4 9 1 1 + 0 4	0.00000	1.06878404		0.00000	1.04019+04	8.73280+03	0.0000
	9.24210+03	4.16687403	Q+0000ō	6.57359+03		0.00000	3.74979+03	-5.30443+03	0.0000
· ·	1.34106+03	-8+54400+03	0.00000	97.24744402		0.00000	-2,38490+03	-1.29842+04	0.0000
	-3.77439+D3	#1.45044+04		94.94246+03	-1.57454±04	0.00000	-5.84288+D3	1.6Z435±04_	0.000
EPSILON PLAS D	1.57892=03	8-59494-03	0.00000	1.51174=03	7.79101=03	0.0000	1.44700=03	4.98995-03	0.0000
	1.38089-03	6-19331-03	0 • 0000n	1.31275703		0.00000	1.24203-03	4.61599-03	0.000
	1.16926-03	3.84149-03	D • 00000	1.09049-03		0.00000	1.00352-03	2.33294-03	0.0000
	9.02484704	1.61689-03	0.00000	7.79689-04		0+00000	6.45015=04	3.62997-04	0.0000
	5.39837-04	-8+41361-05	0+00000 0	5.56186704		0+00000	6.20985-04		0.0000
	6.76441-04	-1 - 66450-03	0 • G0GGO	7-21474-04		0.00000	7+47486=04	~3.05579~03	0.0000
14 <u>5.</u>	7-60093-04	-3 · 60225-03	0.00000	7 • 680 40 *0 4	-4.568.7-D3	000000	7 - 44181 - 04	~5.34967~p3	0.0000

REGION NUMBER 4

THERE ARE	1 SECHENTS AND	O KINGMATTC I NKS 4	TTUIN THIS REGION -

SEGMENT NUMBER 1	SEGMENT CODE 21	NO. OF LAYERS 20
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TABLE GROER PHI OR S VS. CROSSECTION PROPERTIES

**100000+00	.2610000+01
+1283000+00	·1283000+00

PHI (RAD. OR IN.)	DEGRES	R ZERO	BASE THICKNESS	STEP	EPSILON THETA IN
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U	K PHI THETA	N THETA	N PHI	N PHI THETA	EPSILON PHI IN
٧	J PHI STAR	H THETA	M PHI	H PHI THETA	EPSILON PHI OUT
	T PHI THETA	SIGNA THETA IN	SIGMA PHI IN	TAU PHI THETA IN	GAMMA PHI THETA IN
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CYCLE 50.

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	1 . 07845+04	1 . 34910+04	0+00000	1.06902+84	1-15894+04	0 * 0 0 0 0 0	1+04052+04	8.73270+03	0.00000
	9+24724+03	4 • 1 6845 + 03	0.00000	6.58122+03	*1.09928403	0.00000	3.75934+03	-5 - 29733+03	0.00000
	1.35201+03	*8.53405+03	0.00000	7012914+02	"1 . 10684+04	0.00000	#2.37277+03	-1.29772+04	0.00000
**	*3.76434+03	-1 - 44 984 + 04	0.00000	94.93089 ⁺ 03	P1.57399+04	0.00000	-5-85143+03	-1-67387+04	0.00000
EPSILON PLAS .	1-57604-03	8.57470-03	0.00000	1.50923-03	7.79095-03	0.00000	1 • 44485 = 03	6.98990-03	0.00000
	1.37910-03	6+19326-03	0.00000	1.31132-03	5.40155-03	0.00000	1.24095-03	4.61594-03	0.00000
72	1-14853-03	3,84144-03	0.00000	1.09009=03	3.07755-03	0.00000	1.00344-03	2.33298-03	0.00000
tito 2	9 • 0270 • • 04	1.61693-03	0.00000	7.80187-04	9.47538-04	0.00000	6.45807#04	3.63112-04	0+00000
要	5 - 40 70 4 70 4	-8-61245-05	0.00000	5.57517-04	-5.15759-04	0.00000	. 22590°04	-1-05217-03	0.00000

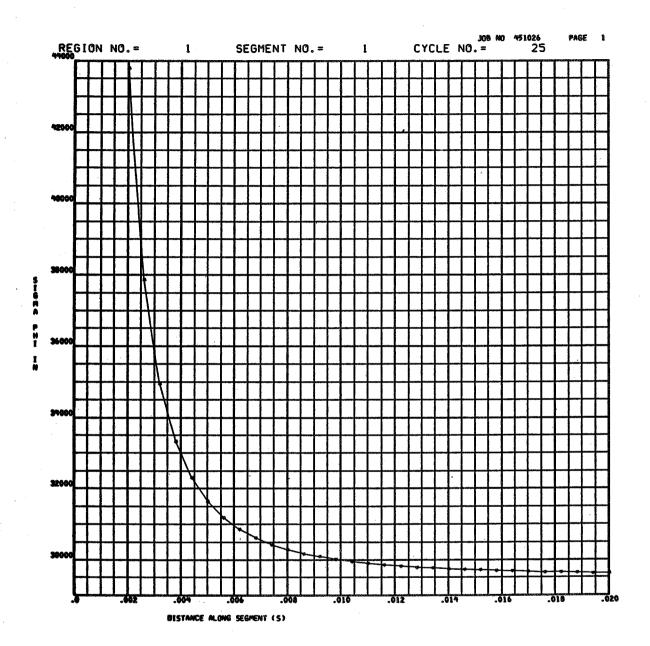
	6•78333-04 7••3000-04	-1•66691-03 -3•80246-03	Ú•800Un Ú•898Un	7•23667°64 7•63342°04		0 • 0 0 0 0 0 0 • 0 0 0 0 0	7•50019+04 7•47886+04	-3.05608-03 -5.34977-03	0•00000 0•00000
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SIGMA =	4.90539+03	9+60646+03	0.00000	4.81402+63	8.75546+03	0.00000	4.70412+03	7.70008+03	0.00000
	4.55817+03	6•40849+03	ម∙ចេចចច	4.30118*03	4.64386+03	0.0000	3.91676+03	2 • 2 6 6 6 5 + 0 3	U * 00000
•	3 • 48073 + 03	~4.79633*52	ܕ0000n	2 • 74465 • 63		0.00000	1 • 40830+07	~4.81441+03	U • 80800
	1 • 18337 + 03	∞6+26B99+D3	0 • 0000n	5 • 6 8 4 1 8 + 0 2		0.00000	4.56793+01	~8•39399+ ₀ 3	0.00000
	-4.12645+02 -1.51404+03	-9+23272+03 -1+11914+04	0 • 66060 0 • 66060	-8.18671°02 -1.80783°03		0.00000	≈1•18221÷03	~1.05912+04	0.00000
	-2.32697+03	-1+25970+64	U•00000	*2.56087*63		0 * 60000 0 * 60000	~2.07720+03 ~2.78182+03	#1.21580+04	0.0000
1. a			•			0.0000	***************************************	-1.34103+04	0.00000
EPSILON PLAS =	-8.73964-05	5-71272-04	0.00000	-6.06559-05	4.01602-04	0.00000	-3.85737-05	2.50814-04	4,00000
	-2.04829-05	1 • 21389-04	0.00000	*6.68261*06		0.00000	0.00000	0.00000	U = 00000
	0 • 00000 1 • 7 1 4 4 9 = 0 4	0 • 00 000 -2 • 65 1 3 6 - 0 4	0.00000	3.75253~05		0+00000	1.03083-04	-1 + 32274-04	000000
	3.64406-04	-7.75814-04	0 • 00000 0 • 00000	2 * 38517 ° 04 4 * 25582 ° 04	-4.22361-64 -9.68912-04	0.00000	3.02332-04 4.84571-04	~5.93442 ~04	0.00000
4-49	5 - 420 94-04	-1.36742-03	0.00000	5.99134~34		0 * 00000 0 * 00000	6.54920.04	~1 • 16631-03 ~1 • 78876-03	0 • 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
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0•000∪000 *3•2426313*03		000000 678404501	-8-16710		7 • 2325915+01		60000	1 • 10 1 1 7 3 6 = 0	
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-7·4537372-02	• -	000000	~[• 26365		1+5512511+03		00000 00000	0.0000000	
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A Committee of the Comm	1.19988+03	8.51118+02	0 • 00 0 0 o	1.13098463	~1 . 25488+03	0.00000	1.06208+03	~3.36087+03	0.00000
	7.61316+02	-4 - 84106+03	0.0000	4 • 5 9 3 8 3 + 6 2	~ 5•98904+63	0.00000	1+85176+02	~6.92029+03	A . 00000
	=5 · 23305 +01	-7 · 73760 +03	0 • 0 0 0 0 0	~2+71228+62	-8.41768+D3	0.00000	~4.6547u+02	-9.03843+03	0.00000
	-6.43468+02 -1.09102+03	-9•57300+63 -1•09402+64	0 • 00000 m	~8.u4702*02	91.00754+04	0.00000	₩9.53932+02	-1.04899+04	0.00000
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EPSILON PLAS =	-5.97006-05	1.43706-04	0,0000	-3.14957-05	7.45411-05	0.00000	-1.11220-05	2.60039-05	0.00000
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	4-17500-05	≈6•68875=û5	0.00000	9 • 40526-05	-1-65451-04	0.00000	1.50526-04	~2.83784-04	0.00000
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2-07085-04 -4-11615-04
                                               0.00000
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                  3.84579+04 -8.50810-04
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   -3 - 6777712-03
                          -3.3868721+61
                                                  1.8530518+01
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SIGMA "
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                 #7 . 25728+02
                               -1 · 93218+63
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EPSILON PLAS =
                 -3.79413-05
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                  5.65752-05
                               -1-27217-04
                                                             1-04687-04
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                  3.95248-04
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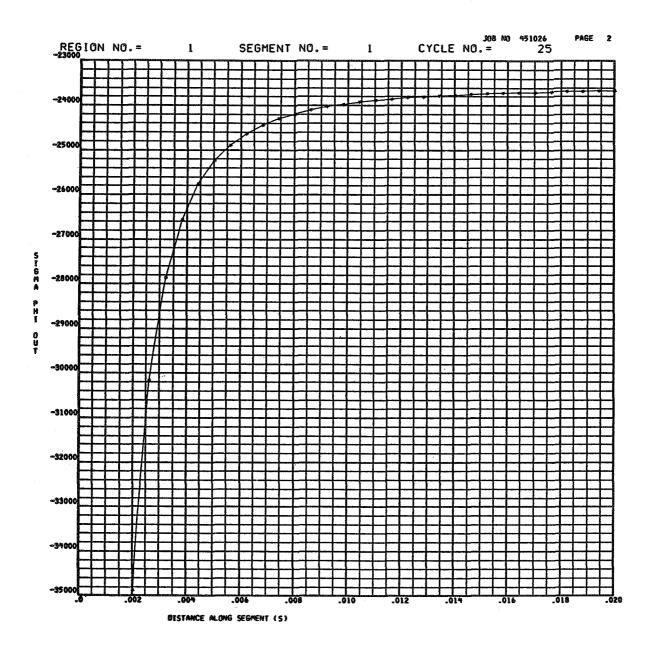
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4-50

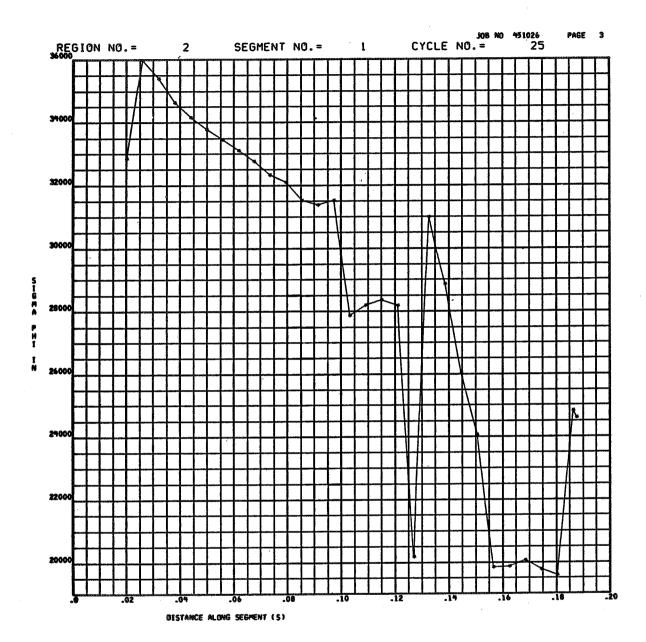




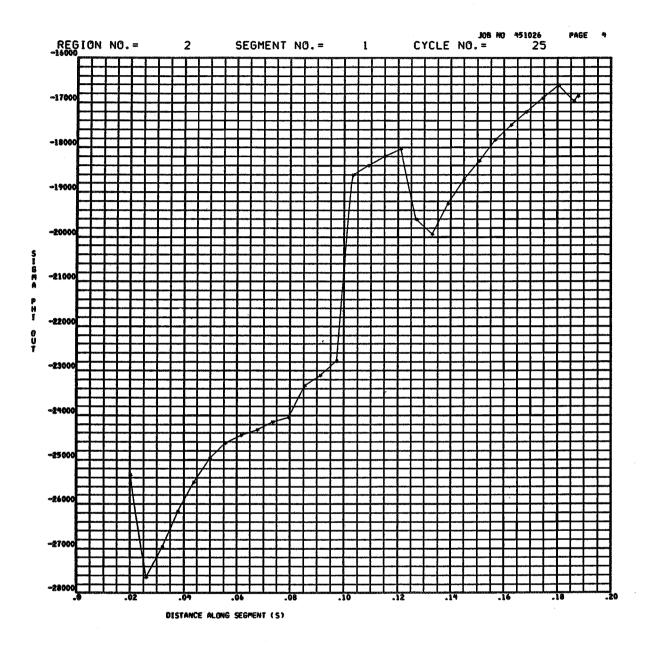




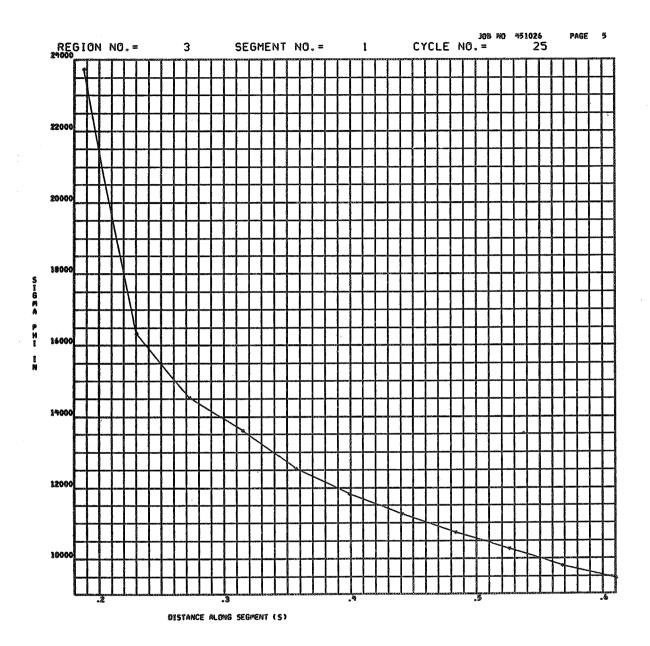




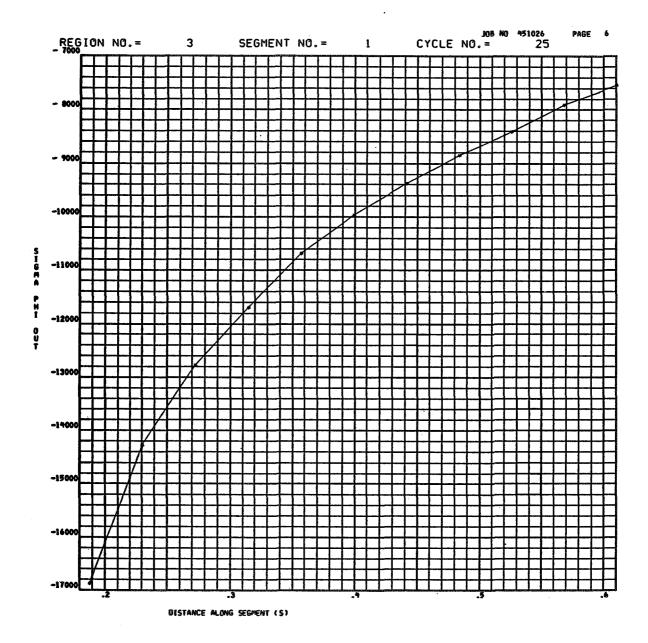




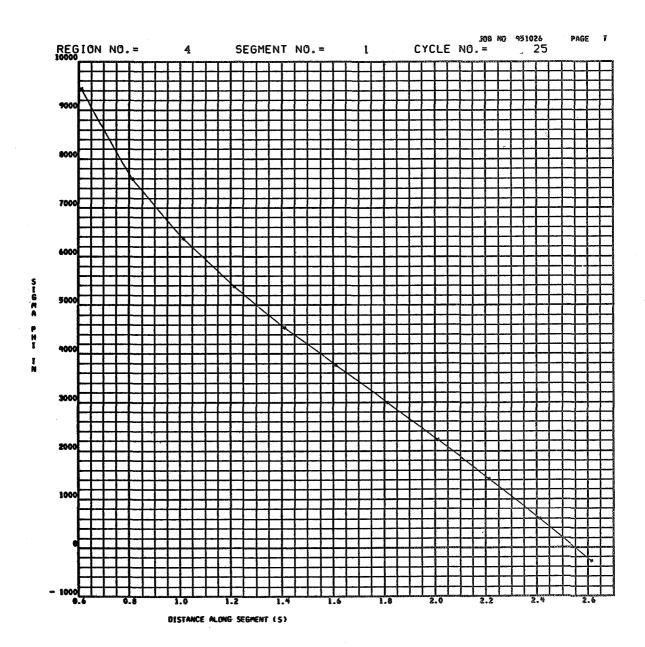




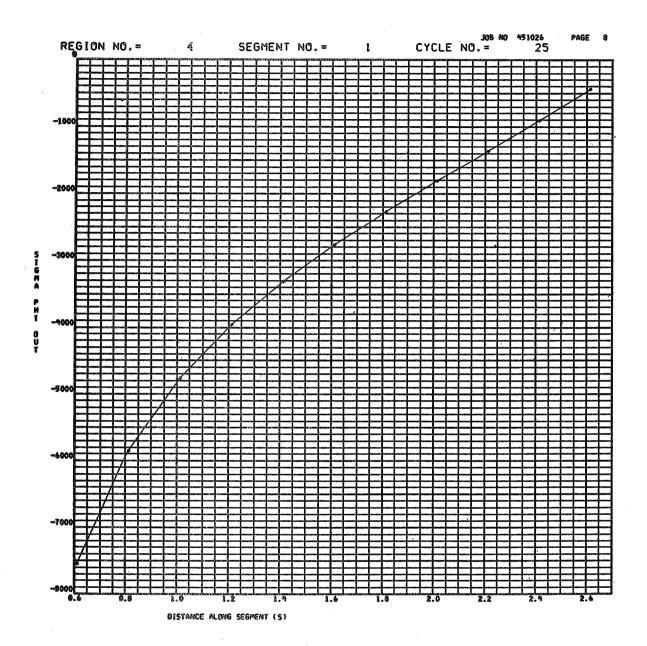




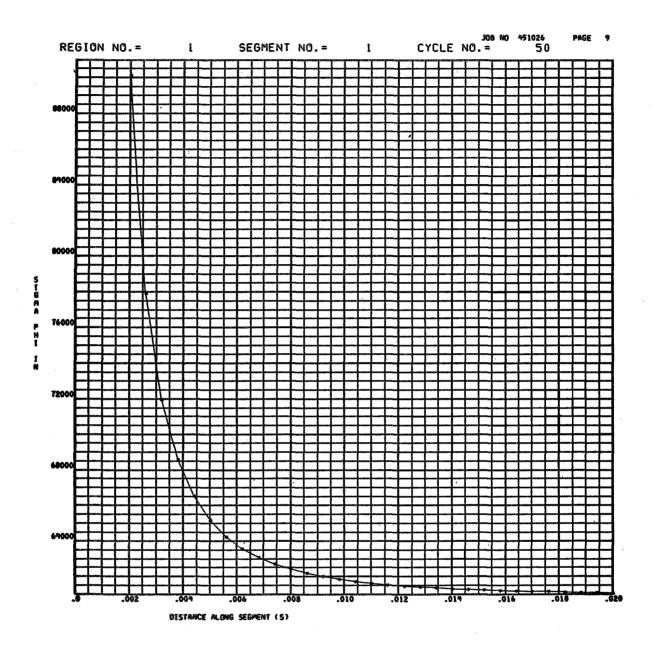




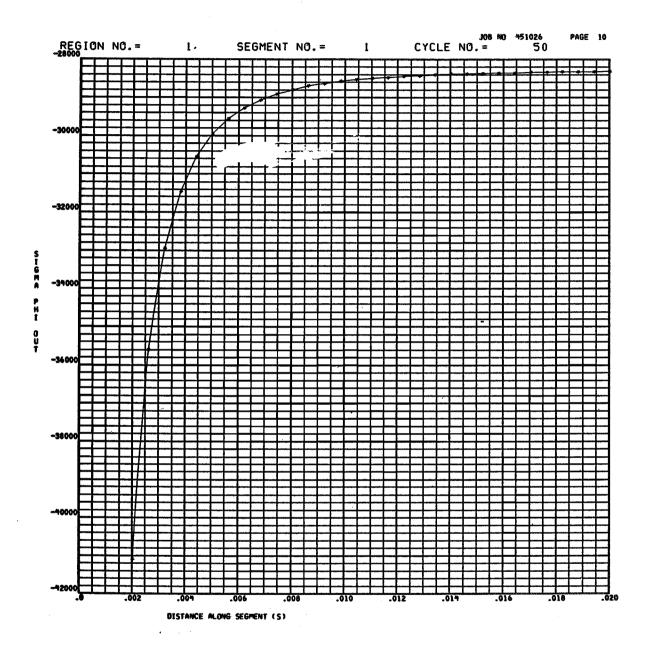




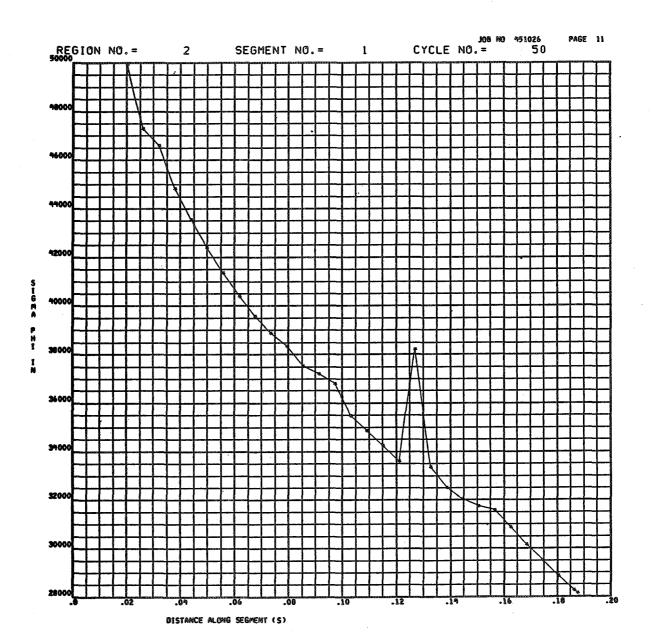




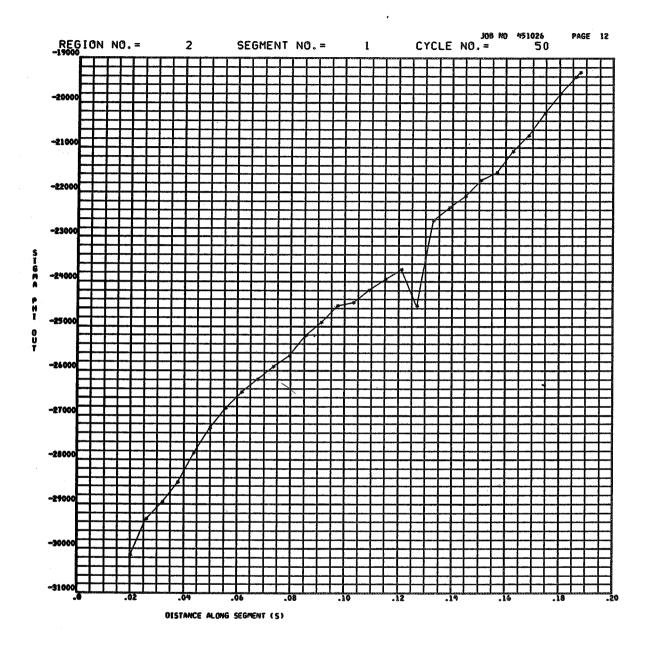




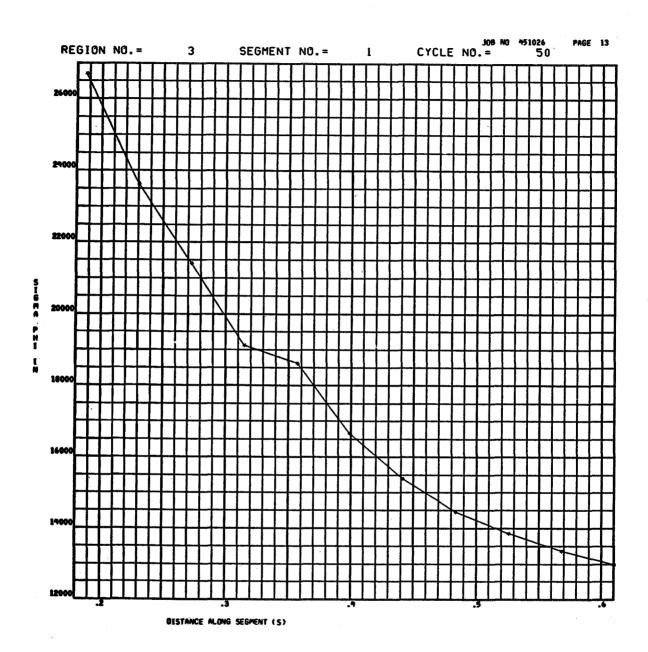




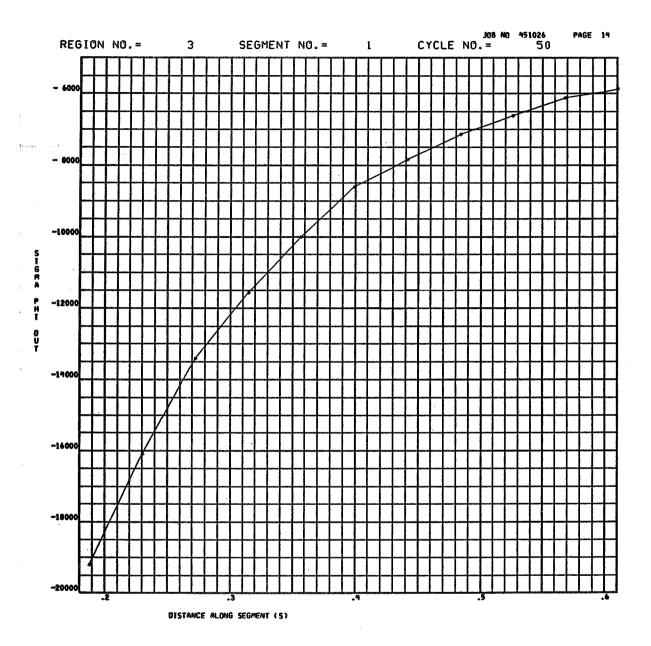




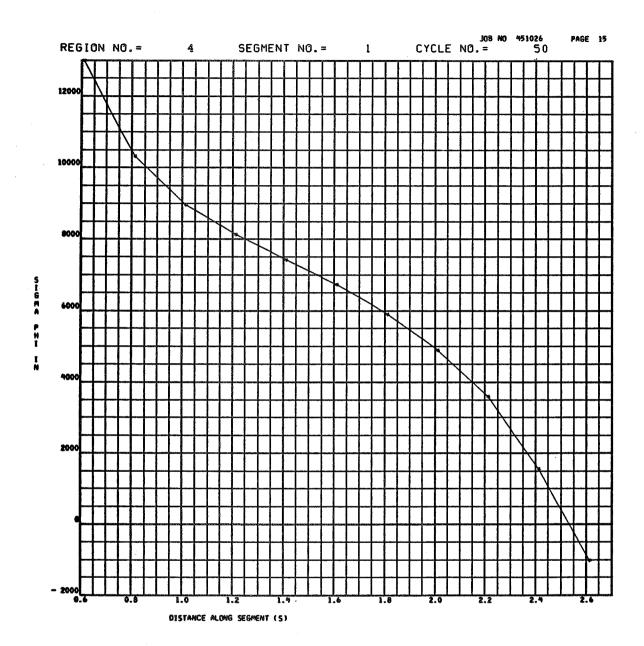




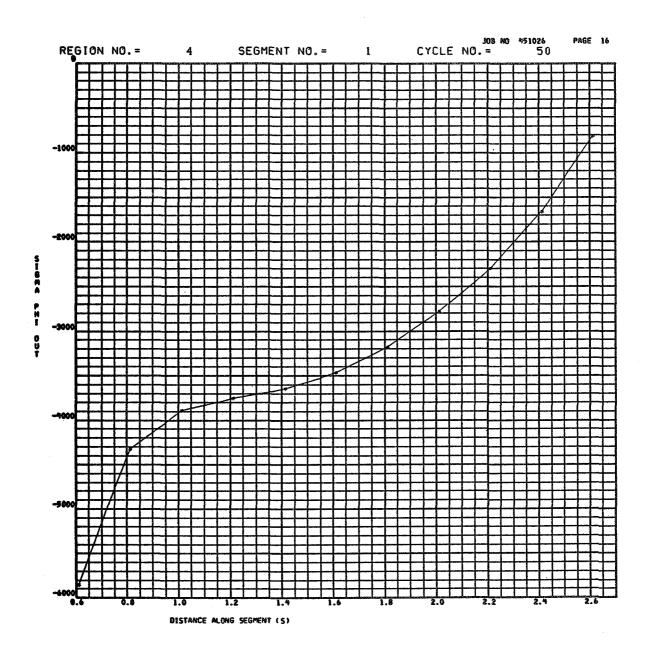












SECTION 5

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- 2. Turing, A. M., "Rounding Off Errors in Matrix Processes", Quarterly Journal of Mechanics and Physics, Sept. 1948, pp. 287-308.
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- 4. Svalbonas, V., "Numerical Analysis of Stiffened Shells of Revolution, Vol. I: Theory Manual", NASA CR-2273, Sept. 1973.
- 5. Foster, B., and Thomas, J., "Automated Shell Theory for Rotating Structures (ASTROS)", NASA TN D-6485, Nov. 1971.

APPENDIX A

CONVERSION OF U.S. CUSTOMARY UNITS TO SI UNITS

The International System of Units (SI) was adopted by the Eleventh General Conference on Weights and Measures in 1960. Conversion factors for the units used in this report are given in the following table:

Physical Quantity	U.S. Customary Unit	Conversion factor (*)	SI Unit (**)
Length	in.	. 0.0254	meters (m)
Stress modulus	ksi	6.895 x 10 ⁶	newtons/meter ² (N/m ²)
Stress resultant	lbf/in.	175.1	newtons/meter (N/m)
Temperature change	$o_{\mathbf{F}}$	5/9	Kelvin (K)

^{*} Multiply value given in U.S. Customary Unit by conversion factor to obtain equivalent value in SI Units.

** Prefixes to indicate multiple of units are as follows:

Prefix	Multiple
giga (G)	109
mega (M)	10 ⁶
kilo (k)	103
deci (d)	10-1
centi (c)	10 2
milli (m)	10 ⁻³